

Lectures of June 30th, 2006

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## Continuation of Poisson Process

5. Continued:

Let  $Z(t)$  be the random impulse train in the form of

$z(t) = \sum_{k=1}^{\infty} \delta(t - T_k)$  - underlying a Poisson process where  $T_k$ 's are time instance at which random events occur. Let  $h(t) = u(t)$  be the impulse response of an *LTI* system. The output of the system with input  $z(t)$  is the Poisson process  $n(t)$ , i.e.,

$$n(t) = z(t) * u(t)$$

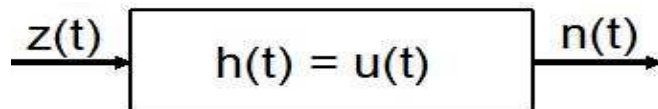


Figure 1:

6. If the impulse response of the above *LTI* system is not  $u(t)$ , but a general function, the output process is called a short noise process.

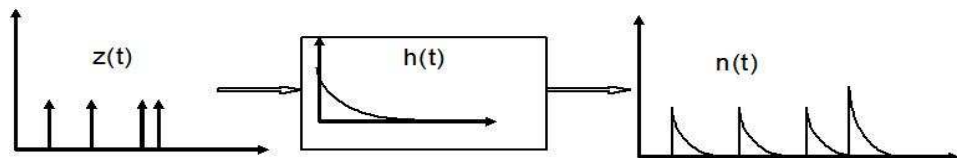


Figure 2:

For example, a photon particle when it hits a barrier.  
Or in a 2D example, an earthquake.

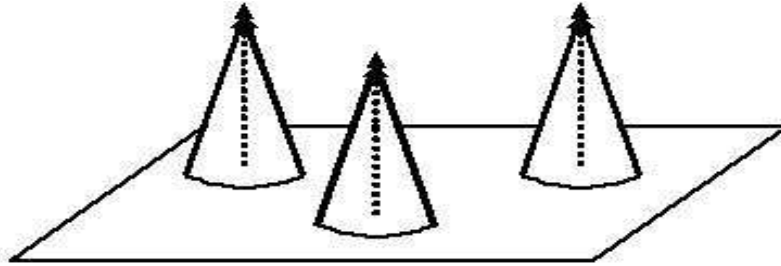


Figure 3: A 2-D example

7. The  $M_N(t)$ , (mean of a Poisson process) of  $\alpha = \lambda t$ , for a fixed  $t$  is :
- $$M_N(t) = \lambda t$$

where:  $N(t)$ =Number of events that have happened, and  $M_N(t)$  is the average number of events.

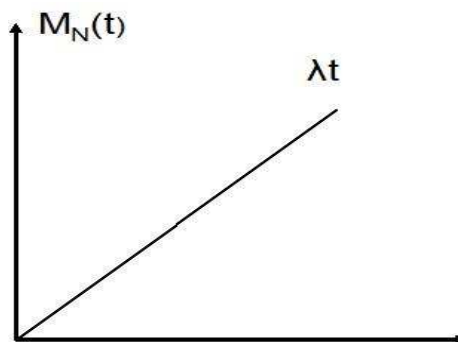


Figure 4:

## The Covariance $R_N(t_1, t_2)$

Suppose  $t_1 < t_2$ , then

$R_N(t_1, t_2) = E[N(t_1) \cdot N(t_2)] \longrightarrow$  if we think of  $N(t_2)$  as a product of other events that occurred after  $N(t_1)$ .

$$\begin{aligned} R_N(t_1, t_2) &= E[N(t_1) \cdot (N(t_1) + N(t_2 - t_1))] \\ &= E[N(t_1)^2] + E[N(t_1)N(t_2 - t_1)] \\ &\text{(the assumption of independence allows us to distribute the function as below.)} \\ &= (\lambda t_1)^2 + \text{VAR}[N(t_1)] + E[N(t_1)]E[N(t_2 - t_1)] \\ &= (\lambda t_1)^2 + \lambda t_1 + (\lambda t_1)(\lambda(t_2 - t_1)) \\ &= \lambda t_1 + \lambda^2 t_1 t_2 \end{aligned}$$

In general  $R_N(t_1, t_2) = \lambda \min(t_1 - t_2) + \lambda^2 t_1 t_2 \longrightarrow$  the autocorrelation function.

$$C_N(t_1, t_2) = R_N(t_1, t_2) - E[N(t_1)]E[N(t_2)] = \lambda \min(t_1, t_2)$$

This also justifies that the Poisson Process is not a W.S.S Process.

## Power Spectral Density and Filtering of R.P.

Suppose process  $X(t)$  is W.S.S, we will use  $R_X(t)$  to denote its autocorrelation function. Specifically,  $t$  here, denotes  $t_2 - t_1$ , in the original notation  $R_X(t_1, t_2)$  of the autocorrelation function.

The power spectral density (PSD)  $S_X(f)$  of  $X(t)$  is defined as

$S_X(f) = F\{R_X(t)\}$  Where  $F\{\}$  is either continuous / discrete time

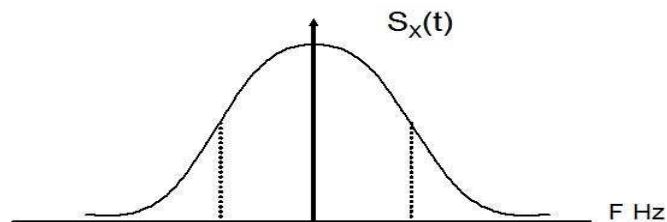


Figure 5:

It follows from the properties of Fourier Transform that

$$\int_{-\infty}^{\infty} S_X(f) df = R_X(0)$$

This can be proven as shown below:

$$x(t) \xrightarrow{F} X(f)$$

by definition:

$$X(f) = \int_{-\infty}^{\infty} x(t)e^{-j2\pi ft} dt \text{ - thus}$$

$$x(t) = \int_{-\infty}^{\infty} X(f)e^{j2\pi ft} df$$

$$x(0) = \int_{-\infty}^{\infty} X(f)e^0 df$$

Thus proving the Power Spectral Density function:

$$R_x(0) = \int_{-\infty}^{\infty} S_X(f)e^0 df$$

$$R_x(0) = E[X(t).X(t)] \text{ - For any } t. \text{ By definition of the Autocorrelation function.}$$

$$R_x(0) = VAR[X(t)] + (E[X(t)])^2$$

$R_X(0)$  means no change in  $t$ .

If we interpret the Autocorrelation function as Power, the  $VAR[X(t)]$  can be thought of as the DC Power, and  $(E[X(t)])^2$  as the AC power, then we can say that  $R_X(0)$  = to the entire power AC + DC.

Important Note: The  $S_X(f)$  is always Non-Negative.

$S_X(t)$  can be interpreted as the distribution of Power.

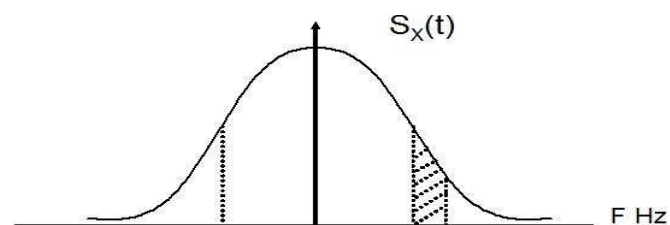


Figure 6:

Example 1.

Let  $X(t)$  be a W.S.S process with  $S_X(f)$  specified as follows (Fig 7.)

1. Find the total power of the process
2. Find the two sided power of the process within 10Hz and 30Hz

Sol:

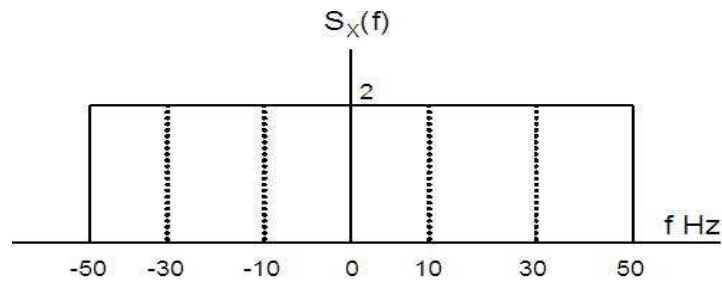


Figure 7:

$$1. \text{ Total Power} = \int_{-\infty}^{\infty} S_X(f) df = \int_{-50}^{50} 1 df = 100$$

$$\begin{aligned} 2. & \text{Over the interval [10Hz and 30Hz]} \\ &= \int_{10}^{30} S_X(f) df + \int_{-30}^{-10} S_X(f) df \\ &= 20 + 20 = 40\text{W} \end{aligned}$$

Example 2.

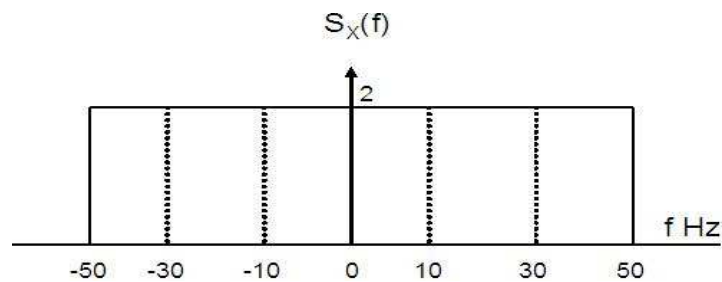


Figure 8:

1. What is the total power in the  $S_x(f)$  specified below.  
 $\delta(t)$  = dc power.

The answer is similar to example 1, but also includes a constant of 2.

## Filtering of W.S.S Random Process

Setting:

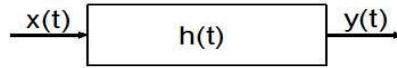


Figure 9:

$x(t)$  is W.S.S

$h(t)$  is the impulse response

Define

$$R_h(t) = h(t) * h(-t) \text{ i.e.}$$

$$R_h(t) = \int_{-\infty}^{\infty} h(\tau - t)h(\tau)d\tau \rightarrow \text{Autocorrelation function}$$

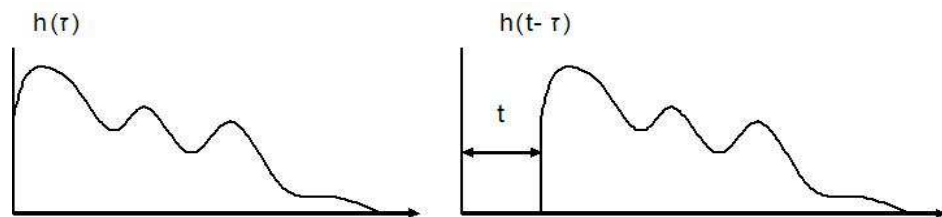


Figure 10:

$R_h(t)$  is also known as the deterministic autocorrelation function. e.g. if the process is sinusoidal, and we shift it by 1 period - we get the convolution as shown below:

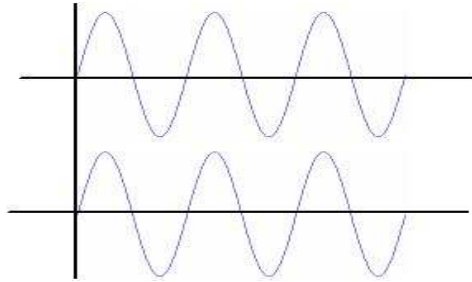


Figure 11:

However, If we shift it by  $1/2$  a period, we get negative values.

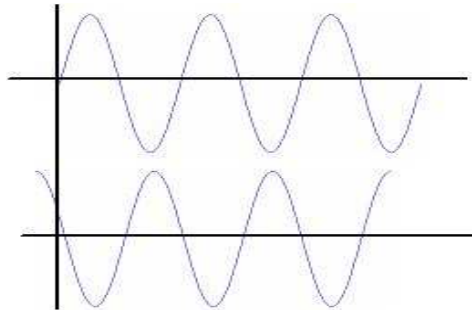


Figure 12:

$$\text{Define } S_h(t) = F\{R_h(t)\} = |H(f)|^2 = H(f) \cdot H(f)$$

$$y(t) = x(t) * h(t)$$

$$\underbrace{|Y(f)|^2}_{R_y(t)} = \underbrace{|X(f)|^2}_{R_x(t)} \cdot \underbrace{|H(f)|^2}_{R_h(t)}$$

## Key Results

1.  $M_y = H(0) \cdot M_x$  where  $H(0) = \int_{-\infty}^{\infty} h(t) dt = H(f) |_{f=0}$

This simply means that the Output Mean  $M_y$  is a scaled version of the Input mean  $M_x$ . Where the scaling factor is precisely given by the area under  $h(t)$ .

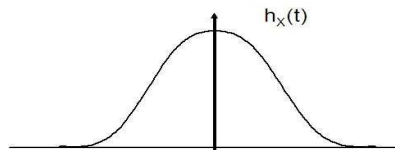


Figure 13:

2. If  $x(t)$  is W.S.S, then  $y(t)$  is also W.S.S.

3.  $R_y(t) = R_x(t) * R_h(t)$

4.  $S_y(f) = S_x(f) \cdot \underbrace{S_h(f)}$

Future Scaling Factor

$S_x(f)$  = The power distribution of a R.P across different bands of Input.

A process is said to be "White" if its PSD is flat, namely across all frequencies.

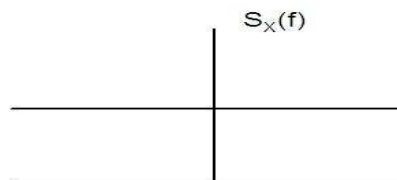


Figure 14: