ELG6108: Introduction to Convex Optimization

Lecture 3: Convex Functions

Dr. Sergey Loyka EECS, University of Ottawa

February 10, 2021

Lecture 3, ELG6108: Introduction to Convex Optimization

Convex functions¹

- Definition
- Examples
- 1st order condition
- 2nd order condition
- Operations that preserve convexity
- Quasiconvex functions
- Log-concave and log-convex functions
- Generalized inequalities

¹adapted from Boyd & Vandenberghe, Convex Optimization, Lecture slides.

• $f(\mathbf{x})$ is convex if **dom** f is a convex set and

$$f(heta \mathbf{x} + (1 - heta)\mathbf{y}) \le heta f(\mathbf{x}) + (1 - heta)f(\mathbf{y})$$
 (1)

for all $\mathbf{x}, \mathbf{y} \in \mathbf{dom} \ f$, $0 \le \theta \le 1$

• $f(\mathbf{x})$ is convex if **dom** f is a convex set and

$$f(heta \mathbf{x} + (1 - heta) \mathbf{y}) \le heta f(\mathbf{x}) + (1 - heta) f(\mathbf{y})$$
 (1)

for all $\mathbf{x}, \mathbf{y} \in \mathbf{dom} \ f$, $0 \le \theta \le 1$



geometrically: any line segment is above the graph

• $f(\mathbf{x})$ is convex if **dom** f is a convex set and

$$f(heta \mathbf{x} + (1 - heta) \mathbf{y}) \le heta f(\mathbf{x}) + (1 - heta) f(\mathbf{y})$$
 (1)

for all $\mathbf{x}, \mathbf{y} \in \mathbf{dom}\ f$, $0 \leq heta \leq 1$



- geometrically: any line segment is above the graph
- strictly convex: if the inequality is strict for any $\mathbf{x} \neq \mathbf{y}$ and $\mathbf{0} < \theta < 1$

• $f(\mathbf{x})$ is convex if **dom** f is a convex set and

$$f(heta \mathbf{x} + (1 - heta) \mathbf{y}) \le heta f(\mathbf{x}) + (1 - heta) f(\mathbf{y})$$
 (1)

for all $\mathbf{x}, \mathbf{y} \in \mathbf{dom} \ f$, $0 \le \theta \le 1$



- geometrically: any line segment is above the graph
- strictly convex: if the inequality is strict for any $\mathbf{x} \neq \mathbf{y}$ and $\mathbf{0} < heta < 1$
- f is concave if -f is convex (equivalently: opposite inequality)

Examples: convex f(x) of scalar x

• **quadratic**: x^2 (most simple, my favorite)

Examples: convex f(x) of scalar x

- **quadratic**: x^2 (most simple, my favorite)
- affine (linear): ax + b for any a, b (convex and concave sim.)
- exponential: e^{ax}, for any a
- powers: x^{α} for x > 0, $\alpha \ge 1$ or $\alpha \le 0$
- powers of absolute value: $|x|^p$ for $p \ge 1$
- negative entropy: x log x for x > 0

Examples: concave f(x) of scalar x

• **negative quadratic**: $-x^2$ (most simple, my favorite)

Examples: concave f(x) of scalar x

- **negative quadratic**: $-x^2$ (most simple, my favorite)
- affine (linear): ax + b for any a, b
- powers: x^{α} for x > 0 and $0 \le \alpha \le 1$
- logarithm: $\log x$ for x > 0

Examples: vector argument x

• affine functions are convex and concave; all norms are convex

Examples: vector argument **x**

- affine functions are convex and concave; all norms are convex
- Euclidean norm = length $|\mathbf{x}| = |\mathbf{x}|_2$
- affine function $f(\mathbf{x}) = \mathbf{a}^T \mathbf{x} + b$
- l_p norms: $|\mathbf{x}|_p = (\sum_{i=1}^n |x_i|^p)^{1/p}$ for $p \ge 1$
- $|x|_{\infty} = \max_k |x_k|$

Examples: convex $f(\mathbf{X})$ of matrix \mathbf{X}

- trace: $f(\mathbf{X}) = tr(\mathbf{X})$ for any **X** (convex and concave)
- affine function for any **X** (convex and concave)

$$f(\mathbf{X}) = \operatorname{tr}(\mathbf{A}^{T}\mathbf{X}) + b = \sum_{i,j} a_{ij} x_{ij} + b$$
(2)

- max. eigenvalue: $f(\mathbf{X}) = \lambda_{max}(\mathbf{X})$ for $\mathbf{X}^T = \mathbf{X}$
- spectral norm (max. singular value) for any X

$$f(\mathbf{X}) = |\mathbf{X}|_2 = \sigma_{max}(\mathbf{X}) = (\lambda_{max}(\mathbf{X}^T \mathbf{X}))^{1/2}$$
(3)

Examples: concave $f(\mathbf{X})$ of matrix \mathbf{X}

- trace: $f(\mathbf{X}) = tr(\mathbf{X})$ for any **X** (convex and concave)
- min. eigenvalue: $f(\mathbf{X}) = \lambda_{min}(\mathbf{X})$ for $\mathbf{X}^{T} = \mathbf{X}$
- log-det: $f(\mathbf{X}) = \log |\mathbf{X}|$ for $\mathbf{X} > 0$

Restriction to a line

- makes it simple to check convexity in many cases
- $f(\mathbf{x})$ is convex if and only if g(t) is convex:

$$g(t) = f(\mathbf{x} + t\mathbf{y}) \tag{4}$$

for any $\mathbf{x}, \mathbf{y}, t$ such that $(\mathbf{x} + t\mathbf{y}) \in \mathbf{dom} f$

- same applies to f(X)
- note that g(t) is simpler than f(x): t scalar, but x vector
- can check convexity of $f(\mathbf{x})$ by checking convexity of g(t)

Example: $f(\mathbf{X}) = \log |\mathbf{X}|, \ \mathbf{X} > 0$

$$g(t) = \log |\mathbf{X} + t\mathbf{Y}| \tag{5}$$

$$= \log |\mathbf{X}| + \log |\mathbf{I} + t\mathbf{X}^{-1/2}\mathbf{Y}\mathbf{X}^{-1/2}|$$
(6)

$$= \log |\mathbf{X}| + \sum_{i} \log(1 + t\lambda_i)$$
(7)

 $\lambda_i = \lambda_i (\mathbf{X}^{-1/2} \mathbf{Y} \mathbf{X}^{-1/2})$ are the eigenvalues g(t) is concave (why?), for any $t, \mathbf{X}, \mathbf{Y}$ such that $\mathbf{X} + t\mathbf{Y} > 0$ hence, $f(\mathbf{X})$ is also concave

S. Loyka

First-order condition

Assume $f(\mathbf{x})$ is differentiable, the gradient $\nabla f(\mathbf{x})$

$$\nabla f(\mathbf{x}) = \left(\frac{\partial f(\mathbf{x})}{\partial x_1}, \frac{\partial f(\mathbf{x})}{\partial x_2}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}\right)^T$$
(8)

exists for each $\mathbf{x} \in \mathbf{dom} \ f$

1st-order condition: differentiable $f(\mathbf{x})$ with convex domain is convex iff

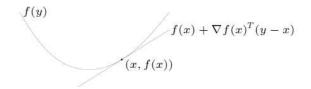
$$f(\mathbf{y}) \ge f(\mathbf{x}) + \nabla f(\mathbf{x})^T (\mathbf{y} - \mathbf{x})$$
 for all $\mathbf{x}, \mathbf{y} \in \mathbf{dom} \ f$ (9)

S. Loyka

First-order condition

Differentiable $f(\mathbf{x})$ with convex domain is convex iff

$$f(\mathbf{y}) \geq f(\mathbf{x}) +
abla f(\mathbf{x})^T (\mathbf{y} - \mathbf{x})$$
 for all $\mathbf{x}, \mathbf{y} \in \mathbf{dom} \ f(\mathbf{y})$



Geometry: first-order approximation of $f(\mathbf{x})$ is its **global underestimator**

Second-order condition

Twice differentiable $f(\mathbf{x})$, Hessian $\mathbf{H} = \nabla^2 f(\mathbf{x})$ exists at each $\mathbf{x} \in \mathbf{dom} f$,

$$\mathbf{H} = \nabla^2 f(\mathbf{x}) = \frac{\partial^2 f(\mathbf{x})}{\partial \mathbf{x}^T \partial \mathbf{x}} = \left\{ \frac{\partial^2 f(\mathbf{x})}{\partial x_i \partial x_j} \right\}$$
(10)

2nd-order conditions: for twice differentiable $f(\mathbf{x})$ with convex domain

• $f(\mathbf{x})$ is convex if and only if

$$\mathbf{H} = \nabla^2 f(\mathbf{x}) \ge 0 \text{ for all } \mathbf{x} \in \mathbf{dom} f$$
(11)

strictly convex if ∇²f(x) > 0

• quadratic function: $f(\mathbf{x}) = (1/2)\mathbf{x}^T \mathbf{P} \mathbf{x} + \mathbf{q}^T \mathbf{x} + r$

$$\nabla f(\mathbf{x}) = \mathbf{P}\mathbf{x} + \mathbf{q}, \quad \nabla^2 f(\mathbf{x}) = \mathbf{P}$$
 (12)

convex if $\mathbf{P} \succeq \mathbf{0}$, concave if $\mathbf{P} \le \mathbf{0}$

• quadratic function: $f(\mathbf{x}) = (1/2)\mathbf{x}^T \mathbf{P} \mathbf{x} + \mathbf{q}^T \mathbf{x} + r$

$$\nabla f(\mathbf{x}) = \mathbf{P}\mathbf{x} + \mathbf{q}, \quad \nabla^2 f(\mathbf{x}) = \mathbf{P}$$
 (12)

convex if $\textbf{P} \succeq \textbf{0},$ concave if $\textbf{P} \leq \textbf{0}$

• least-squares objective: $f(\mathbf{x}) = |\mathbf{A}\mathbf{x} - \mathbf{b}|_2^2$

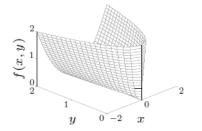
$$\nabla f(\mathbf{x}) = 2\mathbf{A}^T (\mathbf{A}\mathbf{x} - \mathbf{b}), \quad \nabla^2 f(\mathbf{x}) = 2\mathbf{A}^T \mathbf{A} \ge 0$$
 (13)

convex for any **A** (even non-square)

• quadratic-over-linear: $f(x, y) = x^2/y$ convex for y > 0

• quadratic-over-linear: $f(x, y) = x^2/y$ convex for y > 0

$$\nabla^2 f(x,y) = \frac{2}{y^3} \begin{bmatrix} y \\ -x \end{bmatrix} \begin{bmatrix} y \\ -x \end{bmatrix}^T \succeq 0$$
(14)



Lecture 3, ELG6108: Introduction to Convex Optimization

• log-sum-exp: $f(\mathbf{x}) = \log \sum_{k=1}^{n} \exp x_k$ is convex

• log-sum-exp: $f(\mathbf{x}) = \log \sum_{k=1}^{n} \exp x_k$ is convex

$$\nabla^2 f(\mathbf{x}) = \frac{1}{\mathbf{1}^T \mathbf{z}} \operatorname{diag}(\mathbf{z}) - \frac{1}{(\mathbf{1}^T \mathbf{z})^2} \mathbf{z} \mathbf{z}^T \quad (z_k = \exp x_k)$$
(15)

Proof: show that $\nabla^2 f(\mathbf{x}) \succeq 0$ via $\mathbf{v}^T \nabla^2 f(\mathbf{x}) \mathbf{v} \ge 0$ for all \mathbf{v} :

$$\mathbf{v}^{T} \nabla^{2} f(\mathbf{x}) \mathbf{v} = \frac{\left(\sum_{k} z_{k} v_{k}^{2}\right) \left(\sum_{k} z_{k}\right) - \left(\sum_{k} v_{k} z_{k}\right)^{2}}{\left(\sum_{k} z_{k}\right)^{2}} \ge 0$$
(16)

since $(\sum_k v_k z_k)^2 \leq (\sum_k z_k v_k^2) (\sum_k z_k)$ (from Cauchy-Schwarz inequality)

 geometric mean: f(x) = (∏ⁿ_{k=1} x_k)^{1/n} is concave for {x_k > 0, ∀k} (similar proof as for log-sum-exp)

Sublevel set

• *α*-sublevel set of *f* :

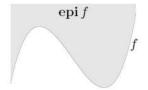
$$C_{\alpha} = \{ \mathbf{x} \in \operatorname{dom} f : f(\mathbf{x}) \le \alpha \}$$
(17)

- i.e. the set of points where function values do not exceed given level α : $f(\mathbf{x}) \leq \alpha$
- sublevel sets of convex functions are convex (converse is false)

Epigraph

- the set of points above the function's graph
- epigraph of $f(\mathbf{x})$:

$$epi \ f = \{(\mathbf{x}, t) : \mathbf{x} \in \operatorname{dom} f, f(\mathbf{x}) \le t\}$$
(18)



Epigraph

- the set of points above the function's graph
- epigraph of $f(\mathbf{x})$:

$$epi \ f = \{(\mathbf{x}, t) : \mathbf{x} \in \operatorname{dom} f, f(\mathbf{x}) \le t\}$$
(18)



• $f(\mathbf{x})$ is convex if and only if **epi** f is a convex set

Jensen's inequality

• the definition of convexity of $f(\mathbf{x})$: for $0 \le \theta \le 1$,

$$f(heta \mathbf{x} + (1 - heta)\mathbf{y}) \le heta f(\mathbf{x}) + (1 - heta)f(\mathbf{y})$$
 (19)

• extension: if $f(\mathbf{x})$ is convex, then

$$f(\mathbb{E}\mathbf{z}) \leq \mathbb{E}f(\mathbf{z})$$
 (20)

for any random vector $\boldsymbol{z};\,\mathbb{E}\{\cdot\}$ is statistical expectation

Jensen's inequality

• the definition of convexity of $f(\mathbf{x})$: for $0 \le \theta \le 1$,

$$f(heta \mathbf{x} + (1 - heta)\mathbf{y}) \le heta f(\mathbf{x}) + (1 - heta)f(\mathbf{y})$$
 (19)

• extension: if $f(\mathbf{x})$ is convex, then

$$f(\mathbb{E}\mathbf{z}) \leq \mathbb{E}f(\mathbf{z})$$
 (20)

for any random vector \mathbf{z} ; $\mathbb{E}\{\cdot\}$ is statistical expectation

the definition is special case with discrete distributions

$$\Pr(\mathbf{z} = \mathbf{x}) = \theta, \quad \Pr(\mathbf{z} = \mathbf{y}) = 1 - \theta$$
 (21)

S. Loyka

Lecture 3, ELG6108: Introduction to Convex Optimization

20 / 43

Jensen's inequality

- powerful applications
 - communications
 - information theory
 - signal processing
 - control, etc.
- examples:
 - entropy/mutual information/channel capacity
 - error rate in fading channels
 - mean square error

February 10, 2021

How to establish convexity ?

How to establish convexity ?

1. Use definition (often simplified by restricting to a line)

How to establish convexity ?

- 1. Use definition (often simplified by restricting to a line)
- 2. Use $\nabla^2 f(\mathbf{x}) \succeq 0$ (for twice differentiable functions)

How to establish convexity ?

- 1. Use definition (often simplified by restricting to a line)
- 2. Use $\nabla^2 f(\mathbf{x}) \succeq 0$ (for twice differentiable functions)
- 3. Show that $f(\mathbf{x})$ is obtained from simple convex functions by operations that preserve convexity

How to establish convexity ?

- 1. Use definition (often simplified by restricting to a line)
- 2. Use $\nabla^2 f(\mathbf{x}) \succeq 0$ (for twice differentiable functions)
- 3. Show that $f(\mathbf{x})$ is obtained from simple convex functions by operations that preserve convexity

Some methods may be much simpler than others (example: $f(x) = x^2$)

Convexity-preserving operations

- nonnegative weighted sum
- composition with affine function
- pointwise maximum/supremum
- composition
- minimization
- perspective

Positive weighted sum

- nonnegative multiple: $\alpha f(\mathbf{x})$ is convex if $f(\mathbf{x})$ is convex and $\alpha \geq 0$
- sum: f₁(x) + f₂(x) convex if f₁(x), f₂(x) convex (extends to infinite sums, integrals)
- positive weighted sum: convex if $f_i(\mathbf{x})$ are convex and $\alpha_i \ge 0$

$$\sum_{i} \alpha_{i} f_{i}(\mathbf{x}), \ \alpha_{i} \ge 0$$
(22)

also extends to infinite sums and integrals

Composition with affine function

- composition with affine function: f(Ax + b) is convex if f is convex
 - proof?

Composition with affine function

• composition with affine function: f(Ax + b) is convex if f is convex

- proof?
- examples
 - log barrier for linear inequalities

$$f(\mathbf{x}) = -\sum_{i=1}^{m} \log \left(b_i - \mathbf{a}_i^T \mathbf{x} \right), \quad \mathbf{dom} \ f = \{ \mathbf{x} : \mathbf{a}_i^T \mathbf{x} < b_i \ \forall i \}$$
(23)

Composition with affine function

• composition with affine function: f(Ax + b) is convex if f is convex

- proof?
- examples
 - log barrier for linear inequalities

$$f(\mathbf{x}) = -\sum_{i=1}^{m} \log \left(b_i - \mathbf{a}_i^T \mathbf{x} \right), \quad \mathbf{dom} \ f = \{ \mathbf{x} : \mathbf{a}_i^T \mathbf{x} < b_i \ \forall i \}$$
(23)

- any norm of affine function: $f(\mathbf{x}) = \|\mathbf{A}\mathbf{x} + \mathbf{b}\|$
- proof?

Pointwise maximum

• if f_1, \ldots, f_m are convex, then

$$f(\mathbf{x}) = \max \{f_1(\mathbf{x}), \dots, f_m(\mathbf{x})\}$$
(24)

is convex

- proof: via $\max\{a_1 + b_1, a_2 + b_2\} \le \max\{a_1, a_2\} + \max\{b_1, b_2\}$

Pointwise maximum

• if f_1, \ldots, f_m are convex, then

$$f(\mathbf{x}) = \max \{ f_1(\mathbf{x}), \dots, f_m(\mathbf{x}) \}$$
(24)

is convex

- proof: via $\max\{a_1 + b_1, a_2 + b_2\} \le \max\{a_1, a_2\} + \max\{b_1, b_2\}$
- examples
 - piecewise-linear function: $f(\mathbf{x}) = \max_{i=1,...,m} (\mathbf{a}_i^T \mathbf{x} + b_i)$

• sum of *r* largest components of **x**:

$$f(\mathbf{x}) = x_{[1]} + x_{[2]} + \dots + x_{[r]}$$
(25)

 $x_{[i]}$ is *i*-th largest component of **x**,

$$x_{[1]} \ge x_{[2]} \ge \dots \ge x_{[r]}$$
 (26)

• sum of *r* largest components of **x**:

$$f(\mathbf{x}) = x_{[1]} + x_{[2]} + \dots + x_{[r]}$$
(25)

 $x_{[i]}$ is *i*-th largest component of **x**,

$$x_{[1]} \ge x_{[2]} \ge \dots \ge x_{[r]}$$
 (26)

• proof: via

$$f(x) = \max\{x_{i_1} + x_{i_2} + \dots + x_{i_r} \mid 1 \le i_1 < i_2 < \dots < i_r \le n\} \quad (27)$$

• sum of *r* largest components of **x**:

$$f(\mathbf{x}) = x_{[1]} + x_{[2]} + \dots + x_{[r]}$$
(25)

 $x_{[i]}$ is *i*-th largest component of **x**,

$$x_{[1]} \ge x_{[2]} \ge \dots \ge x_{[r]}$$
 (26)

• proof: via

$$f(x) = \max\{x_{i_1} + x_{i_2} + \dots + x_{i_r} \mid 1 \le i_1 < i_2 < \dots < i_r \le n\} \quad (27)$$

• example: $f(\mathbf{x}) = x_{[1]}$

• sum of *r* largest components of **x**:

$$f(\mathbf{x}) = x_{[1]} + x_{[2]} + \dots + x_{[r]}$$
(25)

 $x_{[i]}$ is *i*-th largest component of **x**,

$$x_{[1]} \ge x_{[2]} \ge \dots \ge x_{[r]}$$
 (26)

proof: via

$$f(x) = \max\{x_{i_1} + x_{i_2} + \dots + x_{i_r} \mid 1 \le i_1 < i_2 < \dots < i_r \le n\} \quad (27)$$

- example: $f(\mathbf{x}) = x_{[1]}$
- Q: what about smallest component?

S. Loyka

• if $f(\mathbf{x}, \mathbf{y})$ is convex in \mathbf{x} for each $\mathbf{y} \in \mathcal{A}$, then $g(\mathbf{x})$ is also convex,

$$g(\mathbf{x}) = \max_{\mathbf{y} \in \mathcal{A}} f(\mathbf{x}, \mathbf{y})$$
(28)

• if $f(\mathbf{x}, \mathbf{y})$ is convex in \mathbf{x} for each $\mathbf{y} \in \mathcal{A}$, then $g(\mathbf{x})$ is also convex,

$$g(\mathbf{x}) = \max_{\mathbf{y} \in \mathcal{A}} f(\mathbf{x}, \mathbf{y})$$
(28)

examples

• support function of a set $C : S_C(\mathbf{x}) = \max_{\mathbf{y} \in C} \mathbf{y}^T \mathbf{x}$

• if $f(\mathbf{x}, \mathbf{y})$ is convex in \mathbf{x} for each $\mathbf{y} \in \mathcal{A}$, then $g(\mathbf{x})$ is also convex,

$$g(\mathbf{x}) = \max_{\mathbf{y} \in \mathcal{A}} f(\mathbf{x}, \mathbf{y})$$
(28)

examples

- support function of a set $C : S_C(\mathbf{x}) = \max_{\mathbf{y} \in C} \mathbf{y}^T \mathbf{x}$
- distance to farthest point in a set C :

$$f(\mathbf{x}) = \max_{\mathbf{y} \in C} |\mathbf{x} - \mathbf{y}| \tag{29}$$

• if $f(\mathbf{x}, \mathbf{y})$ is convex in \mathbf{x} for each $\mathbf{y} \in \mathcal{A}$, then $g(\mathbf{x})$ is also convex,

$$g(\mathbf{x}) = \max_{\mathbf{y} \in \mathcal{A}} f(\mathbf{x}, \mathbf{y})$$
(28)

examples

- support function of a set $C : S_C(\mathbf{x}) = \max_{\mathbf{y} \in C} \mathbf{y}^T \mathbf{x}$
- distance to farthest point in a set C :

$$f(\mathbf{x}) = \max_{\mathbf{y} \in C} |\mathbf{x} - \mathbf{y}|$$
(29)

maximum eigenvalue of symmetric matrix X = X^T:

$$\lambda_1(\mathbf{X}) = \max_{|\mathbf{y}|_2=1} \mathbf{y}^T \mathbf{X} \mathbf{y}$$
(30)

• if $f(\mathbf{x}, \mathbf{y})$ is convex in \mathbf{x} for each $\mathbf{y} \in \mathcal{A}$, then $g(\mathbf{x})$ is also convex,

$$g(\mathbf{x}) = \max_{\mathbf{y} \in \mathcal{A}} f(\mathbf{x}, \mathbf{y})$$
(28)

examples

- support function of a set $C : S_C(\mathbf{x}) = \max_{\mathbf{y} \in C} \mathbf{y}^T \mathbf{x}$
- distance to farthest point in a set C :

$$f(\mathbf{x}) = \max_{\mathbf{y} \in C} |\mathbf{x} - \mathbf{y}|$$
(29)

maximum eigenvalue of symmetric matrix X = X^T:

$$\lambda_1(\mathbf{X}) = \max_{|\mathbf{y}|_2=1} \mathbf{y}^T \mathbf{X} \mathbf{y}$$
(30)

• Q: what about minimum eigenvalue? 2nd largest?

S. Loyka

Lecture 3, ELG6108: Introduction to Convex Optimization

28 / 43

Composition with scalar functions

• composition of $g(\mathbf{x})$ and h(y) :

$$f(\mathbf{x}) = h(g(\mathbf{x})) \tag{31}$$

- $f(\mathbf{x})$ is convex if:
 - $g(\mathbf{x})$ convex, h(y) convex and nondecreasing

f

• $g(\mathbf{x})$ concave, h(y) convex and nonincreasing

Composition with scalar functions

• composition of $g(\mathbf{x})$ and h(y) :

$$f(\mathbf{x}) = h(g(\mathbf{x})) \tag{31}$$

- $f(\mathbf{x})$ is convex if:
 - $g(\mathbf{x})$ convex, h(y) convex and nondecreasing
 - $g(\mathbf{x})$ concave, h(y) convex and nonincreasing
- proof for scalar x, differentiable g, h:

$$f''(x) = h''(g(x))g'(x)^2 + h'(g(x))g''(x)$$
(32)

Composition with scalar functions

• composition of $g(\mathbf{x})$ and h(y) :

$$f(\mathbf{x}) = h(g(\mathbf{x})) \tag{31}$$

- $f(\mathbf{x})$ is convex if:
 - $g(\mathbf{x})$ convex, h(y) convex and nondecreasing
 - $g(\mathbf{x})$ concave, h(y) convex and nonincreasing
- proof for scalar x, differentiable g, h:

$$f''(x) = h''(g(x))g'(x)^2 + h'(g(x))g''(x)$$
(32)

examples

- $e^{g(\mathbf{x})}$ is convex if $g(\mathbf{x})$ is convex
- $1/g(\mathbf{x})$ is convex if $g(\mathbf{x})$ is concave and positive

Vector composition

composition of $\mathbf{g}(\mathbf{x})$ and $h(\mathbf{y})$:

$$f(\mathbf{x}) = h(\mathbf{g}(\mathbf{x})) = h(g_1(\mathbf{x}), g_2(\mathbf{x}), \dots, g_k(\mathbf{x}))$$
(33)

 $f(\mathbf{x})$ is convex if:

- $g_i(\mathbf{x})$ convex, $h(\mathbf{y})$ convex, h nondecreasing in each argument
- $g_i(\mathbf{x})$ concave, $h(\mathbf{y})$ convex, h nonincreasing in each argument

Vector composition

composition of $\mathbf{g}(\mathbf{x})$ and $h(\mathbf{y})$:

$$f(\mathbf{x}) = h(\mathbf{g}(\mathbf{x})) = h(g_1(\mathbf{x}), g_2(\mathbf{x}), \dots, g_k(\mathbf{x}))$$
(33)

 $f(\mathbf{x})$ is convex if:

- $g_i(\mathbf{x})$ convex, $h(\mathbf{y})$ convex, h nondecreasing in each argument
- $g_i(\mathbf{x})$ concave, $h(\mathbf{y})$ convex, h nonincreasing in each argument

proof for scalar x, differentiable g, h

$$f''(x) = \mathbf{g}'(x)^T \nabla^2 h(g(x)) \mathbf{g}'(x) + \nabla h(\mathbf{g}(x))^T \mathbf{g}''(x)$$
(34)

Vector composition

composition of $\mathbf{g}(\mathbf{x})$ and $h(\mathbf{y})$:

$$f(\mathbf{x}) = h(\mathbf{g}(\mathbf{x})) = h(g_1(\mathbf{x}), g_2(\mathbf{x}), \dots, g_k(\mathbf{x}))$$
(33)

 $f(\mathbf{x})$ is convex if:

- $g_i(\mathbf{x})$ convex, $h(\mathbf{y})$ convex, h nondecreasing in each argument
- $g_i(\mathbf{x})$ concave, $h(\mathbf{y})$ convex, h nonincreasing in each argument

proof for scalar x, differentiable g, h

$$f''(x) = \mathbf{g}'(x)^T \nabla^2 h(g(x)) \mathbf{g}'(x) + \nabla h(\mathbf{g}(x))^T \mathbf{g}''(x)$$
(34)

examples:

- $\sum_{i=1}^{m} \log g_i(\mathbf{x})$ is concave if g_i are concave and positive
- $\log \sum_{i=1}^{m} \exp g_i(\mathbf{x})$ is convex if g_i are convex

Minimization

If $f(\mathbf{x}, \mathbf{y})$ is (jointly) convex in (\mathbf{x}, \mathbf{y}) and C is a convex set, then $g(\mathbf{x})$ is convex,

$$g(\mathbf{x}) = \min_{\mathbf{y} \in C} f(\mathbf{x}, \mathbf{y})$$
(35)

Minimization

If $f(\mathbf{x}, \mathbf{y})$ is (jointly) convex in (\mathbf{x}, \mathbf{y}) and C is a convex set, then $g(\mathbf{x})$ is convex,

$$g(\mathbf{x}) = \min_{\mathbf{y} \in C} f(\mathbf{x}, \mathbf{y})$$
(35)

examples

• distance to a set S: convex if S is convex,

$$dist(\mathbf{x}, S) = \min_{\mathbf{y} \in S} |\mathbf{x} - \mathbf{y}|$$
(36)

Minimization

examples

• distance to a set S: convex if S is convex,

$$dist(\mathbf{x}, S) = \min_{\mathbf{y} \in S} |\mathbf{x} - \mathbf{y}|$$
(37)

•
$$f(\mathbf{x}, \mathbf{y}) = \mathbf{x}^T \mathbf{A} \mathbf{x} + 2\mathbf{x}^T \mathbf{B} \mathbf{y} + \mathbf{y}^T \mathbf{C} \mathbf{y}$$
 with

$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B}^T & \mathbf{C} \end{bmatrix} \succeq 0, \quad \mathbf{C} \succ 0$$
(38)

minimizing over y gives

$$g(\mathbf{x}) = \min_{\mathbf{y}} f(\mathbf{x}, \mathbf{y}) = \mathbf{x}^{T} \left(\mathbf{A} - \mathbf{B}\mathbf{C}^{-1}\mathbf{B}^{T} \right) \mathbf{x}$$
(39)

Since $g(\mathbf{x})$ is convex, Schur complement $\mathbf{A} - \mathbf{B}\mathbf{C}^{-1}\mathbf{B}^T \succeq 0$

S. Loyka

Lecture 3, ELG6108: Introduction to Convex Optimization

the **perspective** of a function f is the function g,

$$g(\mathbf{x},t) = tf(\mathbf{x}/t), \quad \operatorname{dom} g = \{(\mathbf{x},t) \mid \mathbf{x}/t \in \operatorname{dom} f, t > 0\}$$
(40)

 $g(\mathbf{x}, t)$ is convex if $f(\mathbf{x})$ is convex

the **perspective** of a function f is the function g,

$$g(\mathbf{x},t) = tf(\mathbf{x}/t), \quad \operatorname{dom} g = \{(\mathbf{x},t) \mid \mathbf{x}/t \in \operatorname{dom} f, t > 0\}$$
(40)

 $g(\mathbf{x}, t)$ is convex if $f(\mathbf{x})$ is convex

examples

•
$$f(\mathbf{x}) = \mathbf{x}^T \mathbf{x}$$
 is convex; hence $g(\mathbf{x}, t) = \mathbf{x}^T \mathbf{x}/t$ is convex for $t > 0$

the **perspective** of a function f is the function g,

$$g(\mathbf{x},t) = tf(\mathbf{x}/t), \quad \operatorname{dom} g = \{(\mathbf{x},t) \mid \mathbf{x}/t \in \operatorname{dom} f, t > 0\}$$
(40)

 $g(\mathbf{x}, t)$ is convex if $f(\mathbf{x})$ is convex

examples

- $f(\mathbf{x}) = \mathbf{x}^T \mathbf{x}$ is convex; hence $g(\mathbf{x}, t) = \mathbf{x}^T \mathbf{x}/t$ is convex for t > 0
- negative logarithm $f(x) = -\log x$ is convex; hence relative entropy $g(x, t) = t \log t t \log x$ is convex for x, t > 0

the **perspective** of a function f is the function g,

$$g(\mathbf{x},t) = tf(\mathbf{x}/t), \quad \operatorname{dom} g = \{(\mathbf{x},t) \mid \mathbf{x}/t \in \operatorname{dom} f, t > 0\}$$
(40)

 $g(\mathbf{x}, t)$ is convex if $f(\mathbf{x})$ is convex

examples

- $f(\mathbf{x}) = \mathbf{x}^T \mathbf{x}$ is convex; hence $g(\mathbf{x}, t) = \mathbf{x}^T \mathbf{x}/t$ is convex for t > 0
- negative logarithm $f(x) = -\log x$ is convex; hence relative entropy $g(x, t) = t \log t t \log x$ is convex for x, t > 0
- if f is convex, then

$$g(\mathbf{x}) = \left(\mathbf{c}^{\mathsf{T}}\mathbf{x} + d\right) f\left(\frac{\mathbf{A}\mathbf{x} + \mathbf{b}}{\mathbf{c}^{\mathsf{T}}\mathbf{x} + d}\right)$$
(41)

is convex on $\{\mathbf{x} : \mathbf{c}^T \mathbf{x} + d > 0, (\mathbf{A}\mathbf{x} + \mathbf{b}) / (\mathbf{c}^T \mathbf{x} + d) \in \operatorname{dom} f\}$

The conjugate function

the conjugate of a function $f(\mathbf{x})$ is

$$f^*(\mathbf{y}) = \max_{\mathbf{x} \in \text{dom } f} \left(\mathbf{y}^T \mathbf{x} - f(\mathbf{x}) \right)$$
(42)

- $f^*(\mathbf{y})$ is convex, even if $f(\mathbf{x})$ is not
- Q: why?
- is used in duality theory

The conjugate function: examples

• negative logarithm $f(x) = -\ln x$

$$f^{*}(y) = \max_{x>0} (xy + \ln x)$$

$$= \begin{cases} -1 - \ln(-y) & y < 0 \\ \infty & \text{otherwise} \end{cases}$$
(43)

The conjugate function: examples

• negative logarithm $f(x) = -\ln x$

t

$$f^{*}(y) = \max_{x>0} (xy + \ln x)$$

$$= \begin{cases} -1 - \ln(-y) & y < 0 \\ \infty & \text{otherwise} \end{cases}$$
(43)

• strictly convex quadratic $f(\mathbf{x}) = (1/2)\mathbf{x}^T \mathbf{Q} \mathbf{x}, \ \mathbf{Q} > 0$,

$$f^{*}(\mathbf{y}) = \max_{\mathbf{x}} \left(\mathbf{y}^{T} \mathbf{x} - (1/2) \mathbf{x}^{T} \mathbf{Q} \mathbf{x} \right)$$
(45)
$$= \frac{1}{2} \mathbf{y}^{T} \mathbf{Q}^{-1} \mathbf{y}$$
(46)

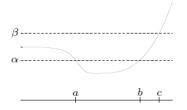
S. Loyka

Quasiconvex functions

 $f(\mathbf{x})$ is quasiconvex if dom f is convex and the sublevel sets

$$S_{\alpha} = \{ \mathbf{x} : f(\mathbf{x}) \le \alpha \}$$
(47)

are convex for all $\boldsymbol{\alpha}$

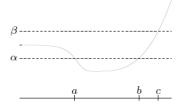


Quasiconvex functions

 $f(\mathbf{x})$ is quasiconvex if dom f is convex and the sublevel sets

$$S_{\alpha} = \{ \mathbf{x} : f(\mathbf{x}) \le \alpha \}$$
(47)

are convex for all α



- *f* is quasiconcave if −*f* is quasiconvex
- f is quasilinear if it is quasiconvex and quasiconcave

Quasiconvex functions: examples

• $\sqrt{|x|}$ is quasiconvex

- $\sqrt{|x|}$ is quasiconvex
- $\operatorname{ceil}(x) = \min\{z \in \mathbf{Z} : z \ge x\}$ is quasilinear

- $\sqrt{|x|}$ is quasiconvex
- $\operatorname{ceil}(x) = \min\{z \in \mathbf{Z} : z \ge x\}$ is quasilinear
- log x is quasilinear on x > 0

- $\sqrt{|x|}$ is quasiconvex
- $\operatorname{ceil}(x) = \min\{z \in \mathbf{Z} : z \ge x\}$ is quasilinear
- log x is quasilinear on x > 0
- $f(x_1, x_2) = x_1 x_2$ is quasiconcave on $x_1, x_2 > 0$

- $\sqrt{|x|}$ is quasiconvex
- $\operatorname{ceil}(x) = \min\{z \in \mathbf{Z} : z \ge x\}$ is quasilinear
- log x is quasilinear on x > 0
- $f(x_1, x_2) = x_1 x_2$ is quasiconcave on $x_1, x_2 > 0$
- linear-fractional function is quasilinear,

$$f(\mathbf{x}) = \frac{\mathbf{a}^T \mathbf{x} + b}{\mathbf{c}^T \mathbf{x} + d}, \quad \text{dom } f = \{\mathbf{x} : \mathbf{c}^T \mathbf{x} + d > 0\}$$
(48)

- $\sqrt{|x|}$ is quasiconvex
- $\operatorname{ceil}(x) = \min\{z \in \mathbf{Z} : z \ge x\}$ is quasilinear
- log x is quasilinear on x > 0
- $f(x_1, x_2) = x_1 x_2$ is quasiconcave on $x_1, x_2 > 0$
- linear-fractional function is quasilinear,

$$f(\mathbf{x}) = \frac{\mathbf{a}^T \mathbf{x} + b}{\mathbf{c}^T \mathbf{x} + d}, \quad \text{dom } f = \{\mathbf{x} : \mathbf{c}^T \mathbf{x} + d > 0\}$$
(48)

distance ratio is quasiconvex,

$$f(\mathbf{x}) = \frac{|\mathbf{x} - \mathbf{a}|_2}{|\mathbf{x} - \mathbf{b}|_2}, \quad \text{dom } f = \{\mathbf{x} : |\mathbf{x} - \mathbf{a}|_2 \le |\mathbf{x} - \mathbf{b}|_2\}$$
(49)

S. Loyka

Lecture 3, ELG6108: Introduction to Convex Optimization

37 / 43

Quasiconvex functions: properties

• modified Jensen inequality: for quasiconvex $f(\mathbf{x})$

$$0 \le \theta \le 1 \implies f(\theta \mathbf{x} + (1 - \theta)\mathbf{y}) \le \max\{f(\mathbf{x}), f(\mathbf{y})\}$$
 (50)

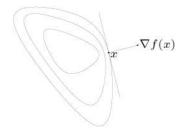
Quasiconvex functions: properties

• modified Jensen inequality: for quasiconvex $f(\mathbf{x})$

$$0 \le \theta \le 1 \implies f(\theta \mathbf{x} + (1 - \theta)\mathbf{y}) \le \max\{f(\mathbf{x}), f(\mathbf{y})\}$$
 (50)

• **first-order condition:** differentiable $f(\mathbf{x})$ with convex domain is quasiconvex iff

$$f(\mathbf{y}) \le f(\mathbf{x}) \implies \nabla f(\mathbf{x})^T (\mathbf{y} - \mathbf{x}) \le 0$$
 (51)



sums of quasiconvex functions are not necessarily quasiconvex

Log-concave and log-convex functions

a positive function $f(\mathbf{x})$ is log-concave if log $f(\mathbf{x})$ is concave:

$$f(heta \mathbf{x} + (1 - heta) \mathbf{y}) \ge f(\mathbf{x})^{ heta} f(\mathbf{y})^{1 - heta}$$
 for $0 \le heta \le 1$ (52)

 $f(\mathbf{x})$ is log-convex iff log $f(\mathbf{x})$ is convex

Log-concave and log-convex functions

a positive function $f(\mathbf{x})$ is log-concave if log $f(\mathbf{x})$ is concave:

$$f(heta \mathbf{x} + (1 - heta)\mathbf{y}) \ge f(\mathbf{x})^{ heta} f(\mathbf{y})^{1 - heta} \quad \text{ for } 0 \le heta \le 1$$
 (52)

 $f(\mathbf{x})$ is log-convex iff log $f(\mathbf{x})$ is convex

examples

• powers: x^p on x > 0 is log-convex for $p \le 0$, log-concave for $p \ge 0$

Log-concave and log-convex functions

a positive function $f(\mathbf{x})$ is log-concave if log $f(\mathbf{x})$ is concave:

$$f(heta \mathbf{x} + (1 - heta) \mathbf{y}) \ge f(\mathbf{x})^{ heta} f(\mathbf{y})^{1 - heta} \quad ext{ for } 0 \le heta \le 1$$
 (52)

 $f(\mathbf{x})$ is log-convex iff log $f(\mathbf{x})$ is convex

examples

- powers: x^p on x > 0 is log-convex for $p \le 0$, log-concave for $p \ge 0$
- many common probability densities are log-concave, e.g. normal:

$$f(\mathbf{x}) = \frac{1}{\sqrt{(2\pi)^n |\mathbf{R}|}} e^{-\frac{1}{2}(\mathbf{x} - \bar{\mathbf{x}})^T \mathbf{R}^{-1}(\mathbf{x} - \bar{\mathbf{x}})}$$
(53)

cumulative Gaussian distribution function Φ is log-concave

$$\Phi(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{x} e^{-u^2/2} du$$
 (54)

Lecture 3, ELG6108: Introduction to Convex Optimization

39 / 43

Properties of log-concave functions

• twice differentiable $f(\mathbf{x})$ with convex domain is log-concave iff

$$f(\mathbf{x})\nabla^2 f(\mathbf{x}) \preceq \nabla f(\mathbf{x})\nabla f(\mathbf{x})^T \ \forall \ \mathbf{x} \in \operatorname{dom} f$$
(55)

Properties of log-concave functions

• twice differentiable $f(\mathbf{x})$ with convex domain is log-concave iff

$$f(\mathbf{x})\nabla^2 f(\mathbf{x}) \preceq \nabla f(\mathbf{x})\nabla f(\mathbf{x})^T \ \forall \ \mathbf{x} \in \operatorname{dom} f$$
(55)

- product of log-concave functions is log-concave
- sum of log-concave functions is not always log-concave
- integration: if $f(\mathbf{x}, \mathbf{y})$ is log-concave, then

$$g(\mathbf{x}) = \int f(\mathbf{x}, \mathbf{y}) d\mathbf{y}$$
 (56)

is log-concave (not easy to show)

Consequences of integration property

• convolution f * g of log-concave functions f, g is log-concave

$$(f * g)(x) = \int f(x - y)g(y)dy$$
(57)

Consequences of integration property

• convolution f * g of log-concave functions f, g is log-concave

$$(f * g)(x) = \int f(x - y)g(y)dy$$
(57)

 if set C convex and y is a random variable with log-concave pdf, then f(x) is log-concave,

$$f(\mathbf{x}) = \Pr(\mathbf{x} + \mathbf{y} \in C) \tag{58}$$

Consequences of integration property

• convolution f * g of log-concave functions f, g is log-concave

$$(f * g)(x) = \int f(x - y)g(y)dy$$
(57)

 if set C convex and y is a random variable with log-concave pdf, then f(x) is log-concave,

$$f(\mathbf{x}) = \Pr(\mathbf{x} + \mathbf{y} \in C) \tag{58}$$

• proof: write $f(\mathbf{x})$ as integral of product of log-concave functions,

$$f(\mathbf{x}) = \int g(\mathbf{x} + \mathbf{y}) p(\mathbf{y}) d\mathbf{y}, \quad g(\mathbf{u}) = \begin{cases} 1 & \mathbf{u} \in C \\ 0 & \mathbf{u} \notin C, \end{cases}$$
(59)

 $p(\mathbf{y})$ is the pdf of \mathbf{y}

S. Loyka

Lecture 3, ELG6108: Introduction to Convex Optimization

Example: yield function

$$Y(\mathbf{x}) = \Pr(\mathbf{x} + \mathbf{w} \in S) \tag{60}$$

- x : nominal parameter values for product
- w : random variations of parameters in manufactured product
- S : set of acceptable values

Example: yield function

$$Y(\mathbf{x}) = \Pr(\mathbf{x} + \mathbf{w} \in S) \tag{60}$$

- x : nominal parameter values for product
- w : random variations of parameters in manufactured product
- S : set of acceptable values
 - if S is convex and \mathbf{w} has a log-concave pdf, then
- Y(x) is log-concave
- yield regions $\{\mathbf{x} : Y(\mathbf{x}) \ge \alpha\}$ are convex

• matrix inequality (positive semi-definite):

$$\mathbf{A} \ge \mathbf{B} \Leftrightarrow \mathbf{A} - \mathbf{B} \ge 0 \Leftrightarrow \mathbf{z}^{\mathsf{T}} (\mathbf{A} - \mathbf{B}) \mathbf{z} \ge 0 \,\,\forall \,\, \mathbf{z} \tag{61}$$

• matrix inequality (positive semi-definite):

$$\mathbf{A} \ge \mathbf{B} \Leftrightarrow \mathbf{A} - \mathbf{B} \ge 0 \Leftrightarrow \mathbf{z}^{\mathsf{T}} (\mathbf{A} - \mathbf{B}) \mathbf{z} \ge 0 \,\,\forall \,\, \mathbf{z} \tag{61}$$

• $f(\mathbf{X})$ is matrix-convex if dom f is convex and

$$f(\theta \mathbf{X} + (1 - \theta)\mathbf{Y}) \leq \theta f(\mathbf{X}) + (1 - \theta)f(\mathbf{Y})$$
(62)

for $\mathbf{X}, \mathbf{Y} \in \operatorname{dom} f, 0 \leq \theta \leq 1$

• matrix inequality (positive semi-definite):

$$\mathbf{A} \ge \mathbf{B} \Leftrightarrow \mathbf{A} - \mathbf{B} \ge 0 \Leftrightarrow \mathbf{z}^{\mathsf{T}} (\mathbf{A} - \mathbf{B}) \mathbf{z} \ge 0 \,\,\forall \,\, \mathbf{z} \tag{61}$$

• $f(\mathbf{X})$ is matrix-convex if dom f is convex and

$$f(\theta \mathbf{X} + (1 - \theta)\mathbf{Y}) \leq \theta f(\mathbf{X}) + (1 - \theta)f(\mathbf{Y})$$
(62)

for $\mathbf{X}, \mathbf{Y} \in \operatorname{dom} f, 0 \leq \theta \leq 1$

• example:
$$f(\mathbf{X}) = \mathbf{X}^2$$
 is matrix-convex on $\mathbf{X} = \mathbf{X}^T$

• matrix inequality (positive semi-definite):

$$\mathbf{A} \ge \mathbf{B} \Leftrightarrow \mathbf{A} - \mathbf{B} \ge 0 \Leftrightarrow \mathbf{z}^{\mathsf{T}} (\mathbf{A} - \mathbf{B}) \mathbf{z} \ge 0 \,\,\forall \,\, \mathbf{z} \tag{61}$$

• $f(\mathbf{X})$ is matrix-convex if dom f is convex and

$$f(\theta \mathbf{X} + (1 - \theta)\mathbf{Y}) \leq \theta f(\mathbf{X}) + (1 - \theta)f(\mathbf{Y})$$
(62)

for $\mathbf{X}, \mathbf{Y} \in \operatorname{dom} f, 0 \leq \theta \leq 1$

• example: $f(\mathbf{X}) = \mathbf{X}^2$ is matrix-convex on $\mathbf{X} = \mathbf{X}^T$

proof: for fixed \mathbf{z} , $g(\mathbf{X}) = \mathbf{z}^T \mathbf{X}^2 \mathbf{z} = |\mathbf{X}\mathbf{z}|_2^2$ is convex in \mathbf{X} , i.e.

$$\mathbf{z}^{\mathsf{T}}(\theta \mathbf{X} + (1-\theta)\mathbf{Y})^{2}\mathbf{z} \le \theta \mathbf{z}^{\mathsf{T}}\mathbf{X}^{2}\mathbf{z} + (1-\theta)\mathbf{z}^{\mathsf{T}}\mathbf{Y}^{2}\mathbf{z}$$
(63)

therefore, $(\theta \mathbf{X} + (1 - \theta) \mathbf{Y})^2 \preceq \theta \mathbf{X}^2 + (1 - \theta) \mathbf{Y}^2$, as required