

## Semi-Empirical Models

Simple theoretical models (i.e., free-space, ideal ground, etc.) do not fit well into real-life scenarios (bad accuracy, disregard of many factors). Practical models are based on combination of measurement and theory (i.e., semi-empirical).

Semi-empirical models: try to make sense of massive measurements based on a few theoretical principles.

Important effects (difficult for theoretical modeling):

- Rough terrain
- Buildings, LOS blockage due to Earth curvature
- Reflection
- Moving user (vehicle)

A simple, but popular, generalization of the two-ray model:

$$L_P = \left(\frac{d}{d_0}\right)^v L_0 \leftrightarrow L_P[\text{dB}] = L_0[\text{dB}] + 10v \lg\left(\frac{d}{d_0}\right) \quad (3.1)$$

$d_0$  is the reference distance,  $L_0$  is the path loss at  $d_0$ ,  $v$  is the path loss exponent (can assume different values at different scenarios).  $d_0$  is selected in such a way that there is an LOS Tx-Rx path (e.g.  $d_0=1$  m).

$d_0, L_0, v$  are obtained from measurements or from theory.

Equivalently, the received power  $P_r$  is:

$$P_r = \left(\frac{d_0}{d}\right)^\nu P_{r0} \leftrightarrow P_r[\text{dBm}] = P_{r0}[\text{dBm}] + 10\nu \lg\left(\frac{d}{d_0}\right) \quad (3.1a)$$

where  $P_{r0}$  is the Rx power at reference distance  $d_0$ .

Example:  $\nu = 2$  for free space;  $\nu = 4$  for ideal ground (2-ray model). In practice,  $2 \leq \nu \leq 8$ .

**Q.:** find  $L_0$ ,  $P_{r0}$  for free-space and two-ray models.

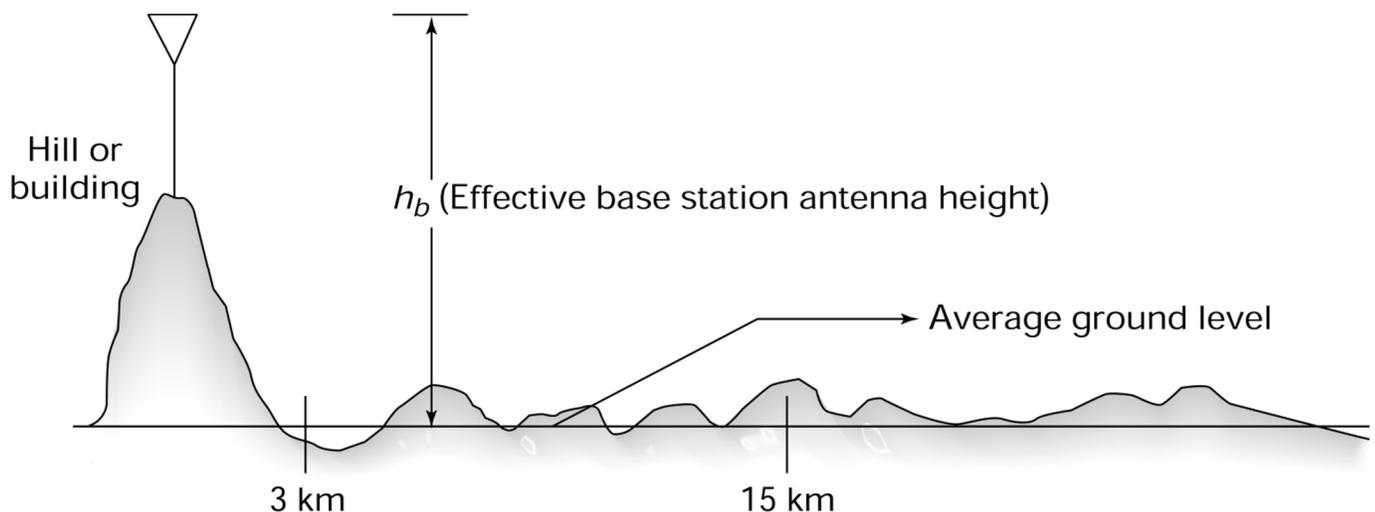
# Okumura-Hata Model

Correction factors are introduced to account for:

- Terrain profile (urban/suburban, rural, hilly etc.)
- Antenna heights
- Building profiles (height, type, concentration)
- Street shape/orientation
- Lakes

Okumura-Hata model is a very popular one.

- Generalization of Okumura measurements (1968) by Hata (analytical presentation of graphs) (1980).
- Predicts average (median) path loss (attenuation).
- Terrain profile is taken into account



P.M. Shankar, Introduction to Wireless Systems, Wiley, 2002.

**Average (median) path loss in urban areas:**

$$L_p(dB) = 69.55 + 26.16 \lg(f) + (44.9 - 6.55 \lg h_b) \lg(d) - 13.85 \lg h_b - a(h_{mu}) \quad (3.2)$$

where:  $f$  is the carrier frequency (MHz);  
 $d$  is the distance (km);  
 $h_b$  is the BS antenna height (m) (effective);  
 $h_{mu}$  is the MU antenna height (m) (above ground);  
 $a(h_{mu})$  is the correction factor;

The correction factor  $a(h_{mu})$  is

$$a(h_{mu}) = \begin{cases} 3.2(\lg(11.75h_{mu}))^2 - 4.97, & \text{large city, } f \geq 300 \text{ MHz} \\ 8.29(\lg(1.54h_{mu}))^2 - 1.1, & \text{large city, } f < 300 \text{ MHz} \\ (1.1 \cdot \lg(f) - 0.7)h_{mu} - (1.56 \lg f - 0.8), & \text{small and medium} \end{cases} \quad (3.3)$$

**Limits of validity:**

$$\begin{aligned} 150 &\leq f \leq 1500 \text{ (MHz)} \\ 30 &\leq h_b \leq 200 \text{ (m)} \\ 1 &\leq d \leq 20 \text{ (km)} \\ 1 &\leq h_{mu} \leq 10 \text{ (m)} \end{aligned} \quad (3.4)$$

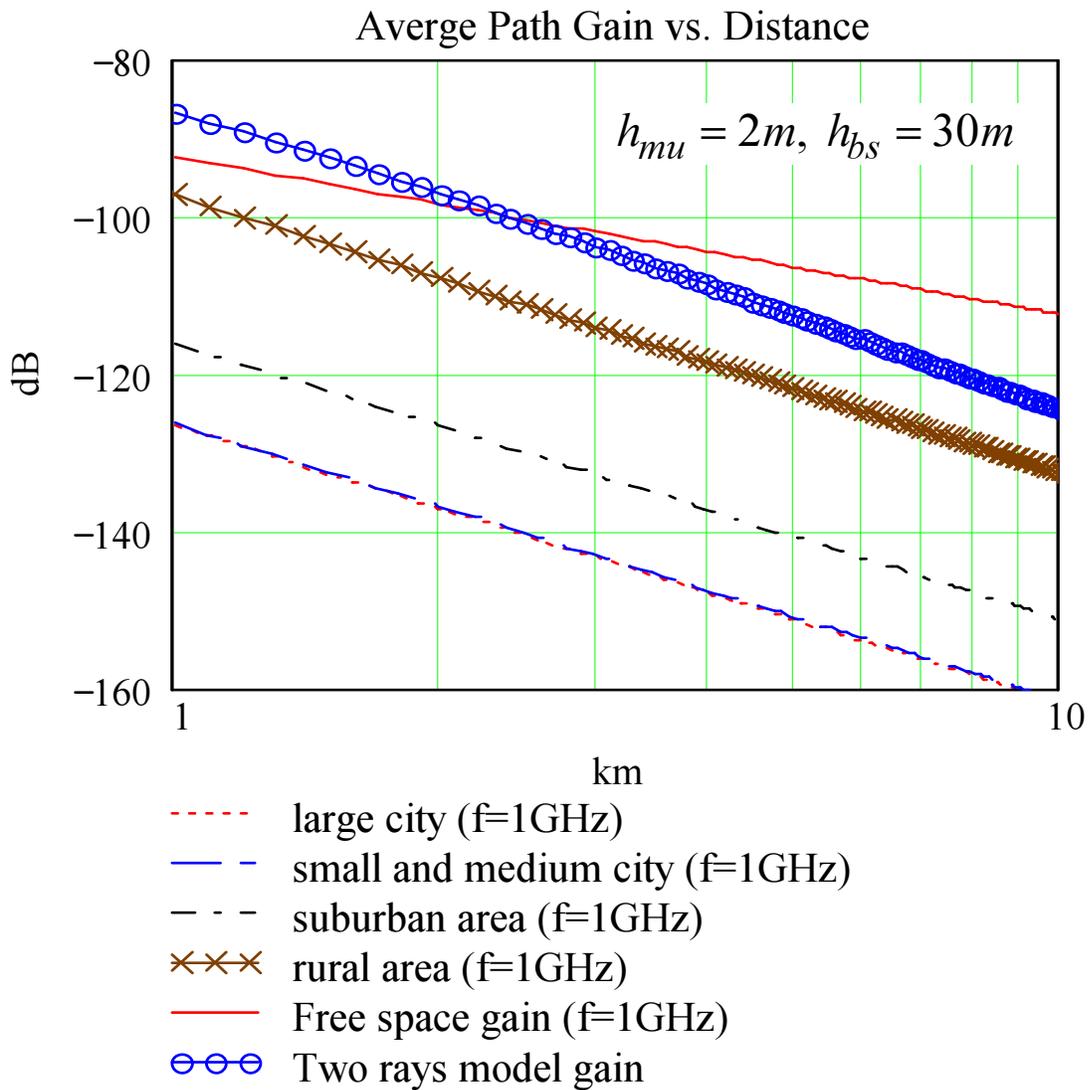
**Suburban areas:**

$$L_{sub} = L_P - 2 \left( \lg \frac{f}{28} \right)^2 - 5.4 \quad (3.5)$$

where  $L_P$  is the path loss in small to medium cities.

**Rural areas**

$$L_{rur}(dB) = L_P - 4.78(\lg f)^2 + 18.33 \lg f - 40.94 \quad (3.6)$$



*Question:* Compare to the free-space and two-ray models, what is the path loss exponent?

## An Extension

Cost-231 extension of the Hata model:

$$L_P(dB) = 46.3 + 33.93 \lg f - 13.82 \lg h_b - a(h_{mu}) + (44.9 - 6.55 \lg h_b) \lg d + c \quad (3.7)$$

where  $c$  is a correction factor :

$$c = \begin{cases} 0dB, & \text{medium city and suburban areas} \\ 3dB, & \text{metropolitan areas} \end{cases}$$

**Limits:** the same as for the Hata model, except for  $1500 \leq f \leq 2000MHz$ .

Major limitation of the 2 models above:  $d \geq 1km$

The model does not take into account building's profile, street type/orientation etc.

Many other models are available.

# COST-Walfisch-Ikegami Model

Includes 3 components: free-space loss, roof-to-street diffraction loss (scattering) and multiscreen loss.

The average path loss for **non-LOS** (NLOS):

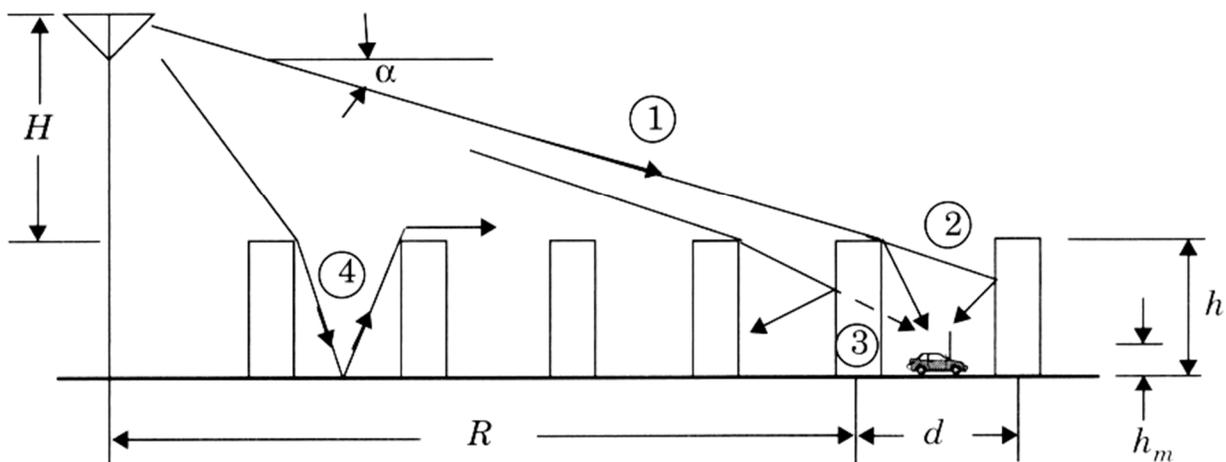
$$L_P[\text{dB}] = L_{fs} + L_{rts} + L_{ms} \quad (3.8)$$

where:

$$L_{fs}[\text{dB}] = 32.4 + 20 \lg d + 20 \lg f = (\text{free - space loss})$$

$L_{rts}$  is the roof-to-street diffraction loss

$L_{ms}$  is the multiscreen loss (rows of buildings)



**Figure 4.25** Propagation geometry for model proposed by Walfisch and Bertoni [from [Wal88] © IEEE].

T.S. Rappaport, Wireless Communications, Prentice Hall, 2002

LOS path loss (in a street canyon):

$$L_P[\text{dB}] = 42.6 + 26 \lg d + 20 \lg f \quad (d \geq 0.02\text{km}) \quad (3.11)$$

where  $d$  is in km, and  $f$  is in MHz.

**Limits:**

$$800 \leq f \leq 2000 \text{MHz}$$

$$4 \leq h_b \leq 50 \text{m}$$

$$1 \leq h_{mu} \leq 3 \text{m}$$

$$0.02 \leq d \leq 5 \text{km}$$

Accuracy: mean error is about 3dB with standard deviation of 4-8dB.

Applications: 3G and later, macrocells and microcells.

## Recent Activities: LTE (4G) Pathloss Models

General system parameters		
System parameters	Bandwidth 10MHz; Carrier Frequency 2GHz; CP type - Normal	
Antenna System	Pico: 5 dBi, 2D, Omni, 2TX & 2RX	UE: 0dBi, 2D, Omni, 1TX, 2RX
Noise Figure	Pico: 13dB	UE: 9 dB
Max Power	Pico: 24dBm	UE: 23dBm
Uplink Power control	Open Loop Power Control: P0: -76dBm; $\alpha = 0.8$ .	
Propagation characteristics		
Shadowing Pico-Pico	Pico: 6dB	
Shadowing Pico-UE	3dB for LOS and 4dB for NLOS	
Penetration loss	0dB	
Pico-Pico pathloss (R in km)	if $R \leq 2/3$ , $PL_{LOS}(R) = 98.4 + 20\log_{10}(R)$ ; else $PL_{LOS}(R) = 101.9 + 40\log_{10}(R)$	$PL_{NLOS} = 40\log_{10}(R) + 169.36$
	$P_{LOS}(R) = 0.5 - \min(0.5, 5\exp(-0.156/R)) + \min(0.5, 5\exp(-R/0.03))$	
Pico-UE pathloss (R in km)	$PL_{LOS}(R) = 103.8 + 20.9\log_{10}(R)$	$PL_{NLOS}(R) = 145.4 + 37.5\log_{10}(R)$
	$P_{LOS}(R) = 0.5 - \min(0.5, 5\exp(-0.156/R)) + \min(0.5, 5\exp(-R/0.03))$	
UE-UE pathloss (R in km)	if $R \leq 50m$ , $PL = 98.45 + 20\log_{10}(R)$ ; else $PL = 55.78 + 40\log_{10}(R)$	
Small scale fading	Pico-UE: ITU UMi UE-UE and Pico-Pico: not modeled	

Z. Shen et al, Dynamic Uplink-Downlink Configuration and Interference Management in TD-LTE, IEEE Communications Magazine, Nov. 2012, pp. 51-59.

## Recent Activities: 5G & related models

1. T. S. Rappaport et al., “Overview of millimeter wave communications for fifth-generation (5G) wireless networks — with a focus on propagation models,” *IEEE Trans. Antennas Propag.*, vol. 65, no. 12, pp. 6213–6230, Dec. 2017.
2. S. Sun et al., “Investigation of prediction accuracy, sensitivity, and parameter stability of large-scale propagation path loss models for 5G wireless communications,” *IEEE Trans. Veh. Technol.*, vol. 65, no. 5, pp. 2843–2860, May 2016.
3. S. Sun, T.S. Rappaport, et al, Propagation Models and Performance Evaluation for 5G Millimeter-Wave Bands, *IEEE Trans. Veh. Technol.*, vol. 67, no. 9, pp. 8422-8439, Sep. 2018.
4. K. Briggs, A. Shojaeifard, Coverage Regions Under Multi-Slope Pathloss Propagation, *IEEE Trans. Veh. Technol.*, vol. 69, no. 10, pp. 11786-11789, Oct. 2020.
5. Study on Channel Model for Frequencies from 0.5 to 100 GHz (Release 16), TR 38.901, 3GPP, Sophia Antipolis, France, 2019.

## Recent Activities: 5G & related models

General form of  $L_P$  [dB] for UMa/UMi/RMa (see [1]-[3][5]):

$$L_P[\text{dB}] = L_0[\text{dB}] + 10\nu \lg\left(\frac{d}{d_0}\right), \quad L_0[\text{dB}] = 20 \lg\left(\frac{4\pi d_0}{\lambda}\right)$$

Usually,  $d_0 = 1$  m (LOS). Equivalently,

$$L_P[\text{dB}] = 32 + 10\nu \lg d + 20 \lg f_c$$

$f_c$  in GHz,  $d \geq d_0 = 1$  m;

$10\nu$  [dB] = extra loss per decade of  $d$

LOS (street canyon):  $\nu = 2 \dots 2.1$

NLOS:  $\nu = 3 \dots 4$

Also: multi-break-point model [5]. You can use its simplified form:

$$L = \max\{L_{2\text{-ray}}, L_{FS}, L_{\min}, G_t G_r\}, \quad L_{\min} \approx 10^2$$

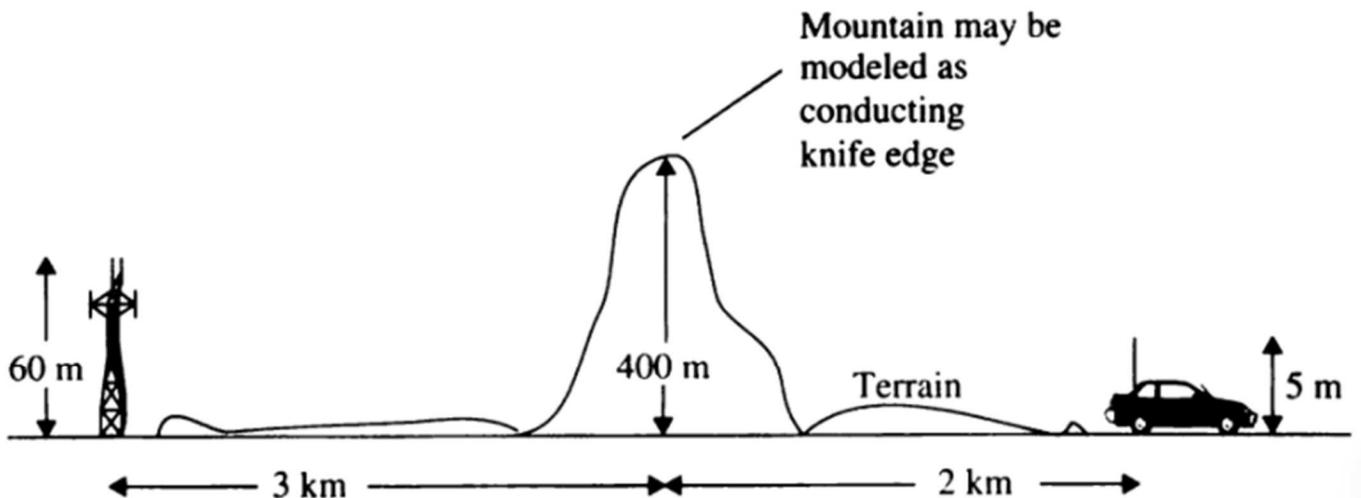
**Note:** do not forget to check the LOS distance!

$$d < d_{LOS} \approx 4\left(\sqrt{h_t} + \sqrt{h_r}\right) \text{ [km]}$$

# Non-LOS (NLOS) Propagation: Diffraction

Diffraction: penetration of EM waves into non-LOS area (“ray bending”).

Any obstruction of LOS path will result in diffraction. While the diffracted field is much weaker than LOS, it can still be important.



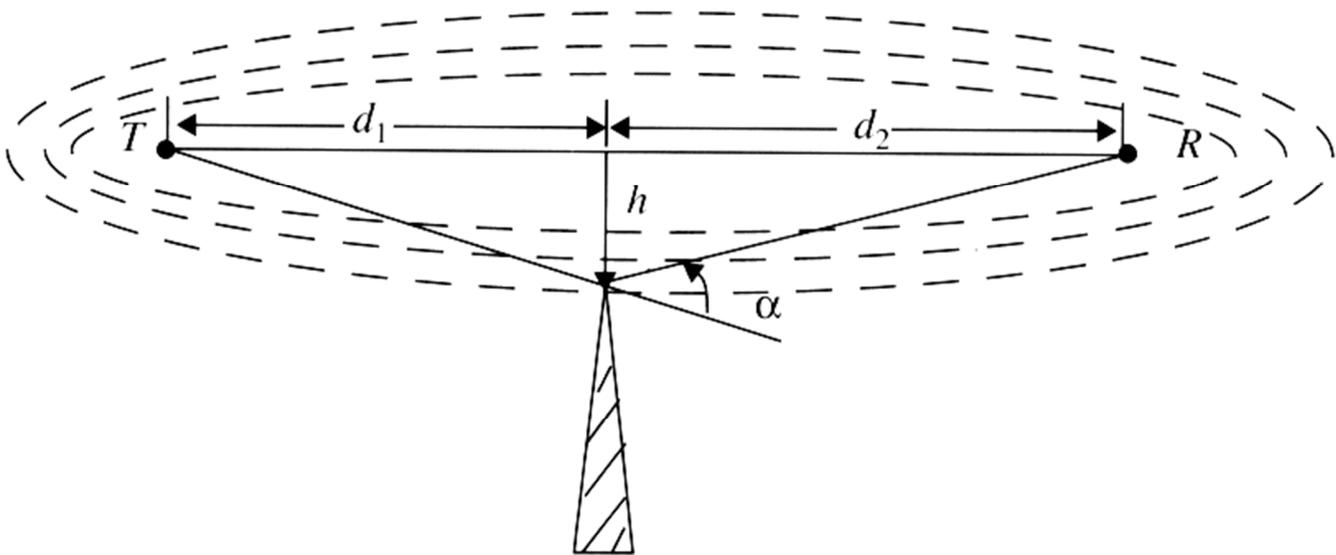
**Figure P4.19** Knife-edge geometry for Problem 4.19.

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# Fresnel Zones and Diffraction

Fresnel zones: define the space essential for EM wave propagation.

n-th Fresnel zone: region of space where the path length is  $[(n-1)\lambda/2, n\lambda/2]$  larger than LOS path length. The zone boundaries are the circles; the path length through each circle is  $n\lambda/2$ .



(c)  $\alpha$  and  $v$  are negative, since  $h$  is negative

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Fresnel zone radius:

$$r_n = \sqrt{\frac{n\lambda d_1 d_2}{d_1 + d_2}} \quad (3.12)$$

where  $d_1, d_2 \gg r_n$ .

Diffraction and Fresnel zones can be explained using Huygen's principle (secondary sources).

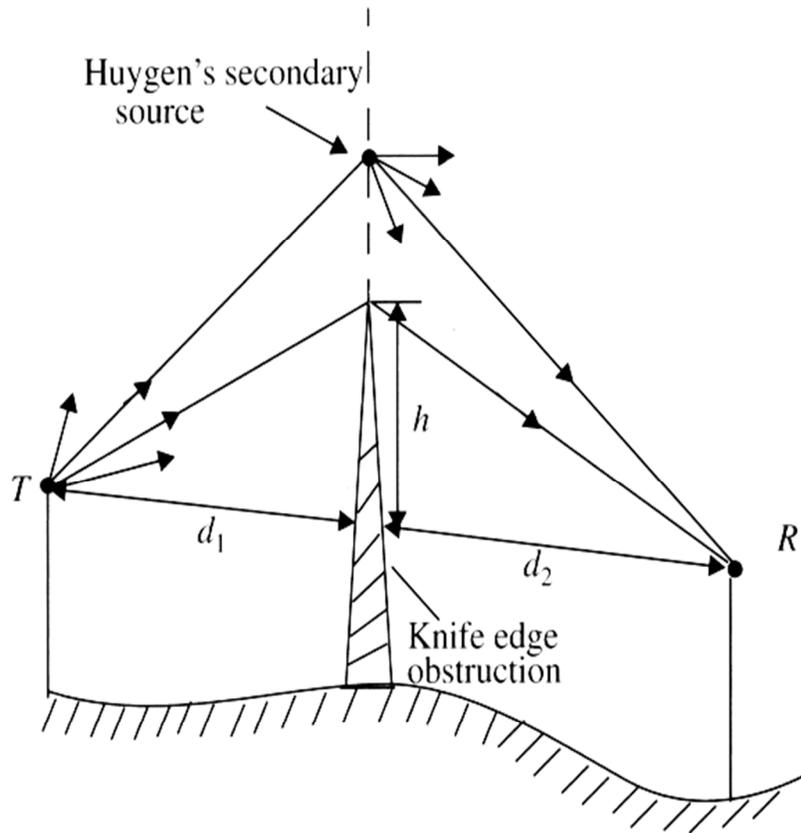
Contribution of each successive zone is less than the previous one. Blockage of some zones results in diffraction.

### **Area essential for EM wave propagation**

There is no disturbance to the wave propagation along a certain path provided that 1<sup>st</sup> Fresnel zone is cleared.

Rule of thumb for LOS microwave link design: ~50% of 1<sup>st</sup> zone must be kept clear.

# Knife-Edge Diffraction



**Figure 4.13** Illustration of knife-edge diffraction geometry. The receiver  $R$  is located in the shadow region.

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Fresnel-Kirchoff diffraction parameter

$$v = h \sqrt{\frac{2(d_1 + d_2)}{\lambda d_1 d_2}} = h\sqrt{2} / r_1 \quad (3.13)$$

The field is given by Fresnel integral

$$\frac{E}{E_0} = F(v) = \frac{1+j}{2} \int_v^{\infty} \exp(-j\pi t^2 / 2) dt \quad (3.14)$$

where  $E_0$  is the LOS field (no obstruction).

The field has oscillating behavior w.r.t.  $h$ . This is a simple model (approximation). Yet, it is good enough to model many obstacles (buildings, mountains, etc.). Generalizations are possible: multiple knife-edge models.

Another representation: introduce Fresnel integrals,

$$C(x) = \int_0^x \cos\left(\frac{\pi}{2} t^2\right) dt, \quad S(x) = \int_0^x \sin\left(\frac{\pi}{2} t^2\right) dt \quad (3.15)$$

Then,

$$F(v) = \frac{1}{2} - \frac{1+j}{2} [C(v) - jS(v)] \quad (3.16)$$

Note that  $C(\infty) = S(\infty) = 1/2$ .

The total path loss is

$$L_p = L_0 L_d \quad (3.17)$$

where  $L_0 = (4\pi R / \lambda)^2$  is the free-space path loss,

$L_d = |F(v)|^{-2}$  is the diffraction loss.

# An Approximation<sup>1</sup>

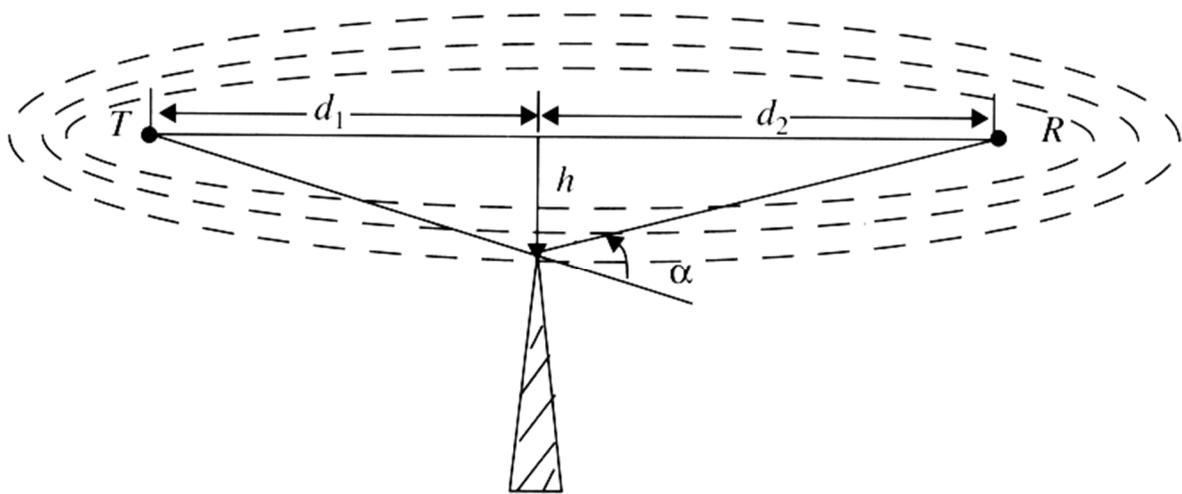
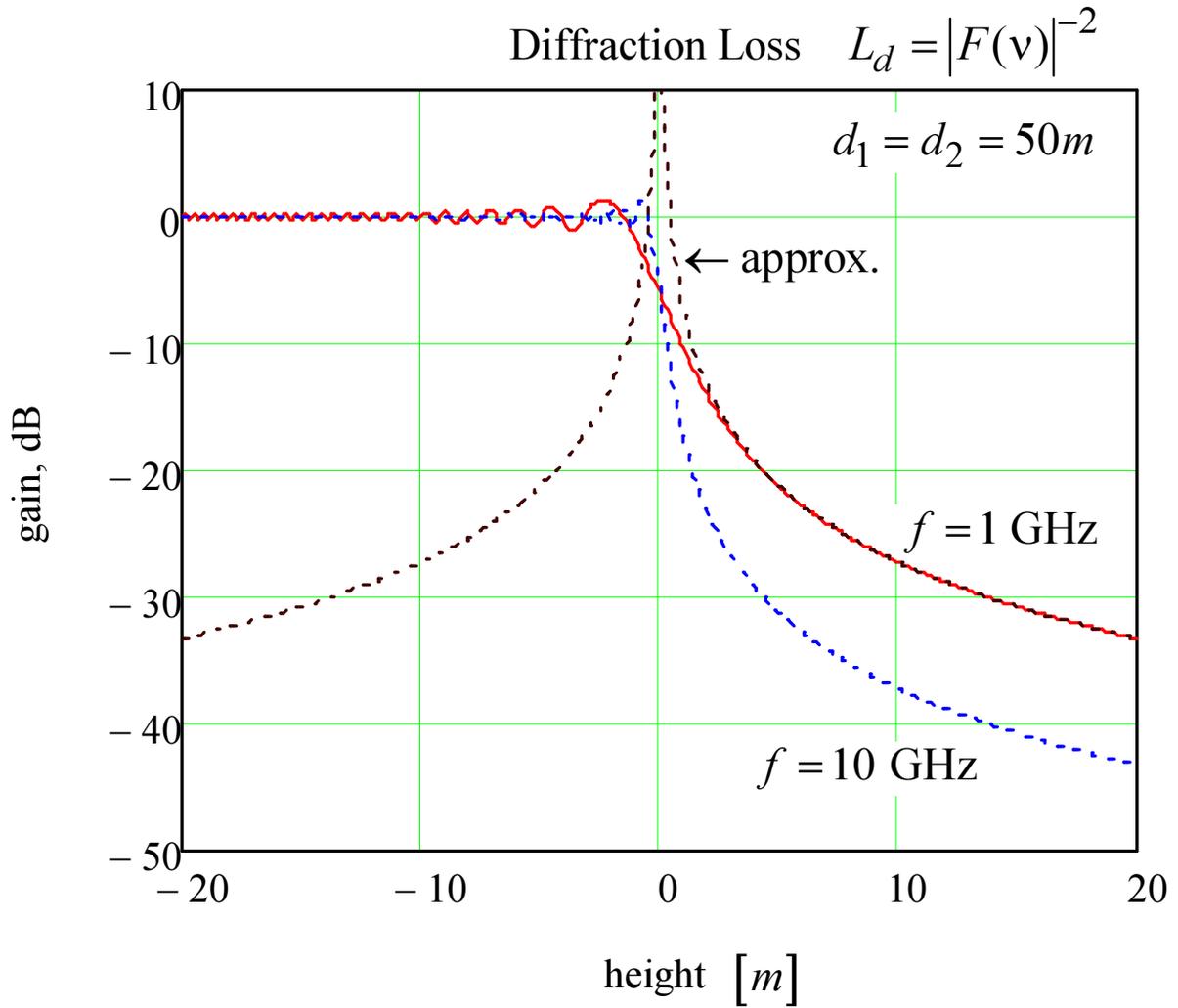
If  $d_1, d_2 \gg h \gg \lambda$ :

$$\frac{1}{L_d} = |F(\nu)|^2 = \left| \frac{E}{E_0} \right|^2 \approx \frac{\lambda}{4\pi^2 h^2} \frac{d_1 d_2}{d_1 + d_2}$$

**Note:** if the edge is not sharp but rounded, expect 10-20 dB more loss.

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<sup>1</sup> see Kraus, Fleish, Electromagnetics with Applications, 5<sup>th</sup> Edition, McGraw Hill, 1999. (p.235-236).



(c)  $\alpha$  and  $v$  are negative, since  $h$  is negative

T.S. Rappaport, Wireless Communications, Prentice Hall, 2002

# Summary

- Average (median) path loss. Semi-empirical models.
- Okumura-Hata model. Extension to PCS environments.
- COST-Walfisch-Ikegami Model.
- Fresnel zones and diffraction. Knife-edge diffraction.

## Reading:

- Rappaport, Ch. 4.

## References:

- S. Salous, Radio Propagation Measurement and Channel Modelling, Wiley, 2013. (available online)
- J.S. Seybold, Introduction to RF propagation, Wiley, 2005.
- Other books (see the reference list).

Note: Do not forget to do end-of-chapter problems. Remember the learning efficiency pyramid!