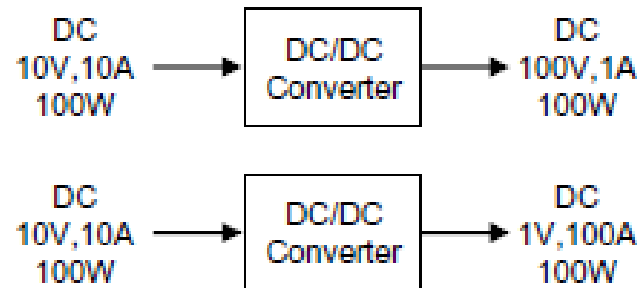


DC to DC Converters

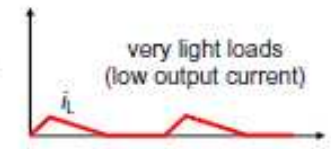
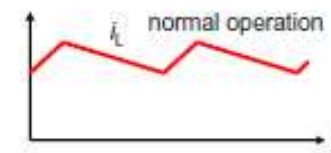
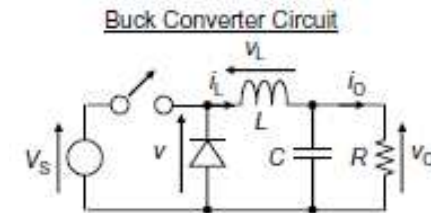
Usually use transistors as switches

Act as a DC transformer



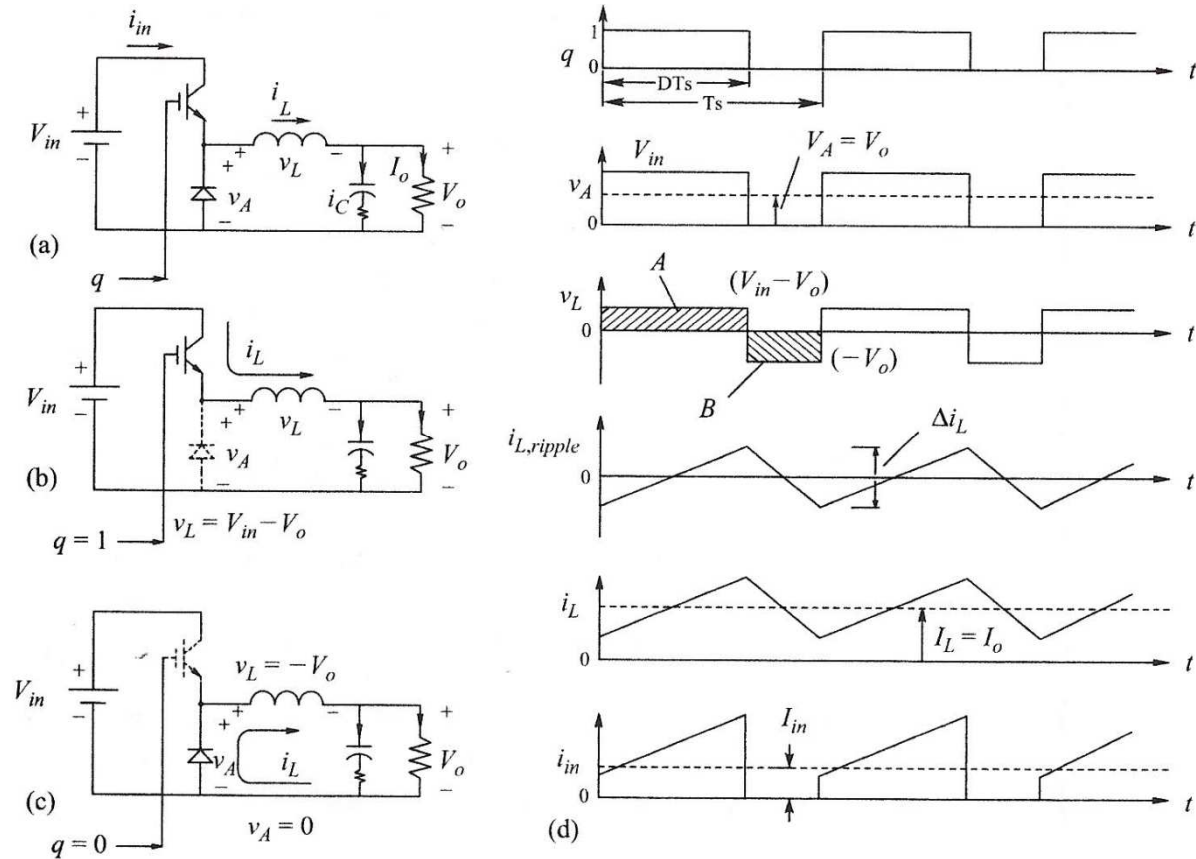
Buck Converter

- Step down converter
- Switch
- Low-pass LC filter
- Diode
- Continuous conduction
- Discontinuous current



Buck Converter Analysis

- $V_o = V_A = DV_{in}$; D = switch duty ratio
- $\Delta i_L = \frac{1}{L} (V_{in} - V_o)DT_s = \frac{1}{L} V_o (1 - D)T_s$
- $I_L = I_o = \frac{V_o}{R}$

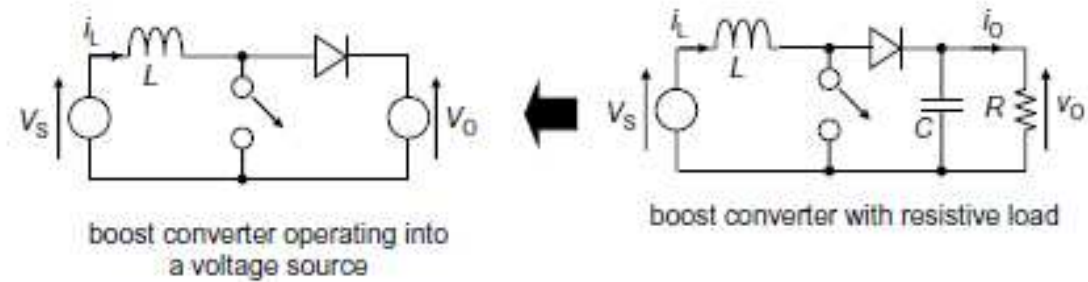


Example

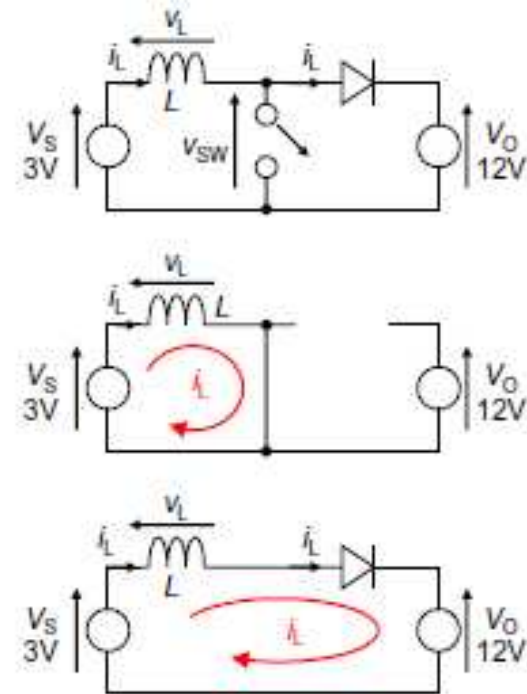
- In **Buck** converter, $L = 24\mu\text{F}$ (steady-state): $V_{\text{in}} = 20\text{V}$; $D = 0.6$; $P_o = 14\text{W}$; $f_s = 200\text{ kHz}$. Calculate and draw the waveform.

Boost Converter

- Step-up
- Same components
- Different topology!

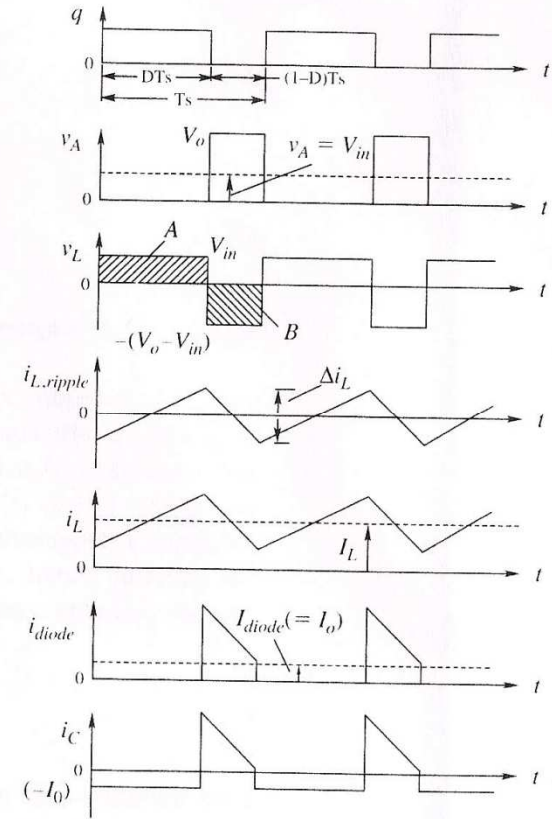
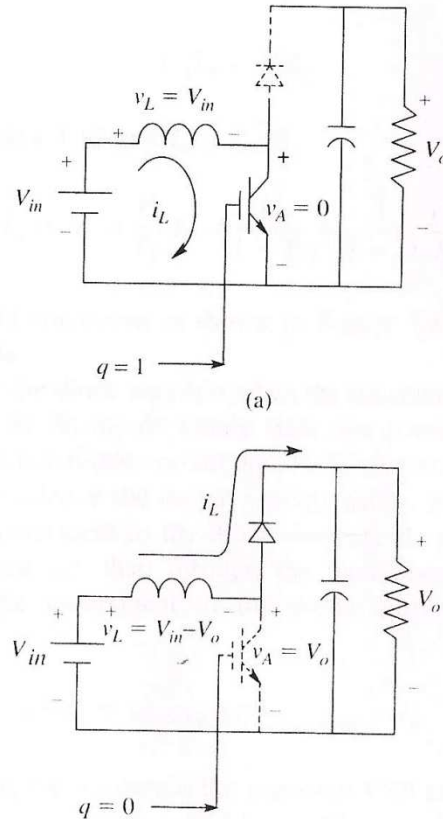


- See stages of operation



Boost Converter

- $\Delta i_L = \frac{1}{L} (V_{in}) DT_s = \frac{1}{L} (V_o - V_{in})(1 - D)T_s$
- $\frac{V_o}{V_{in}} = \frac{1}{1 - D}$

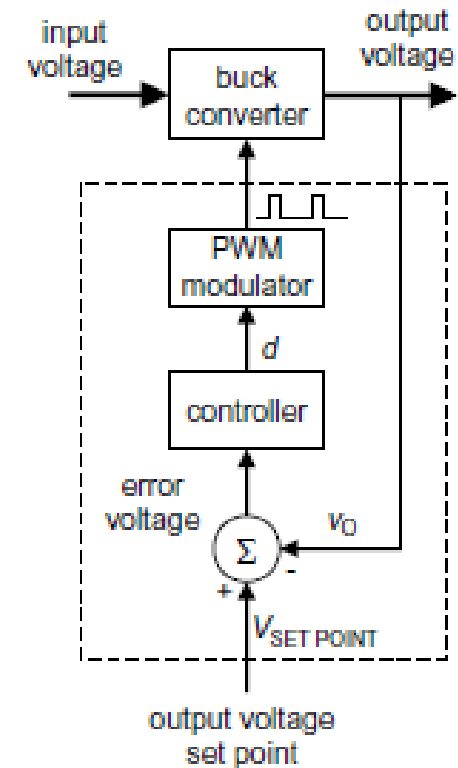


Example

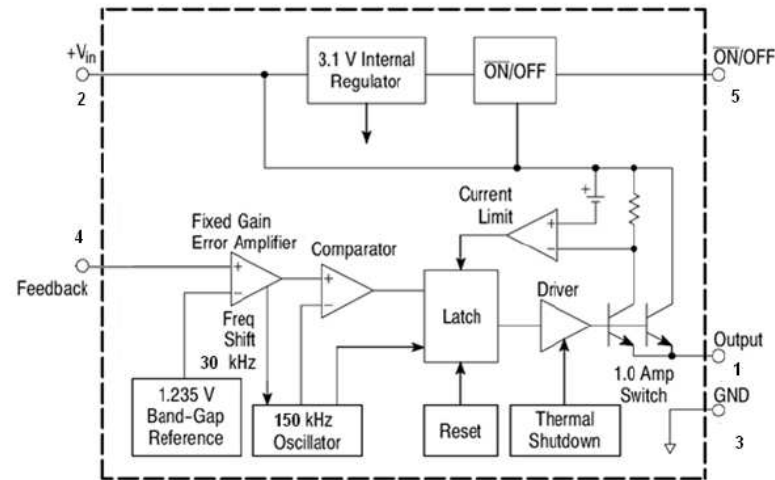
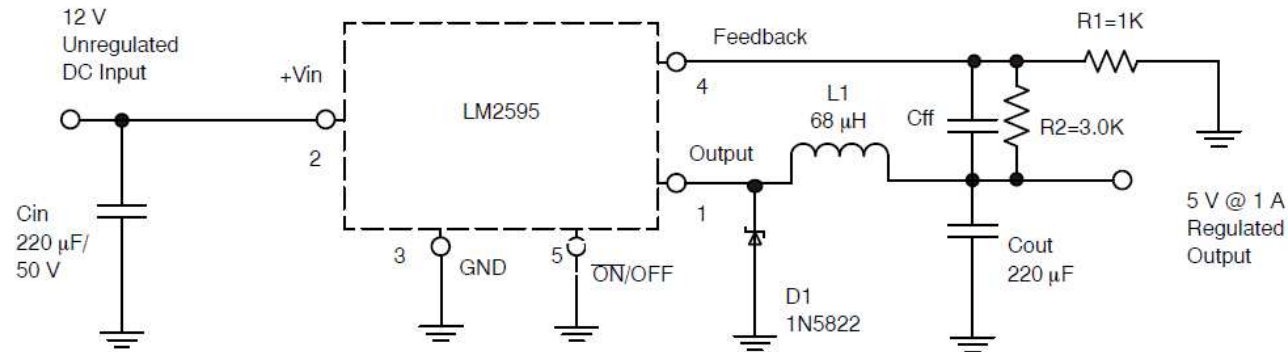
- Consider a boost converter, the inductor current has $\Delta i_L = 2$ A. $V_{in} = 5$ V, $V_o = 12$ V, $P_o = 11$ W, $f_s = 200$ kHz. Calculate L and draw the waveform.

Control of DC to DC Converter

- Error voltage = desired – actual
- Controller: Control duty cycle (PID)
- Modulator
- Entire controller is available as an IC.

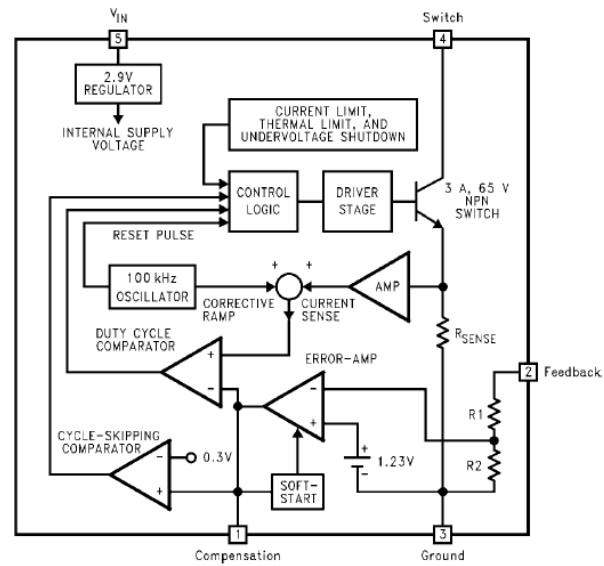
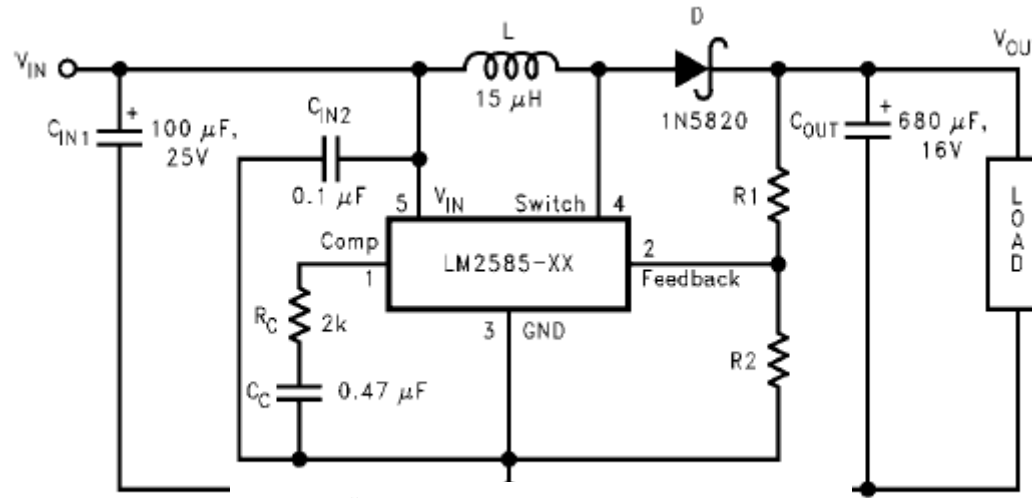


Switch, PWM, Electronics, Reference, and Buck Converter (LM2529: *Courtesy of National Semiconductors*)



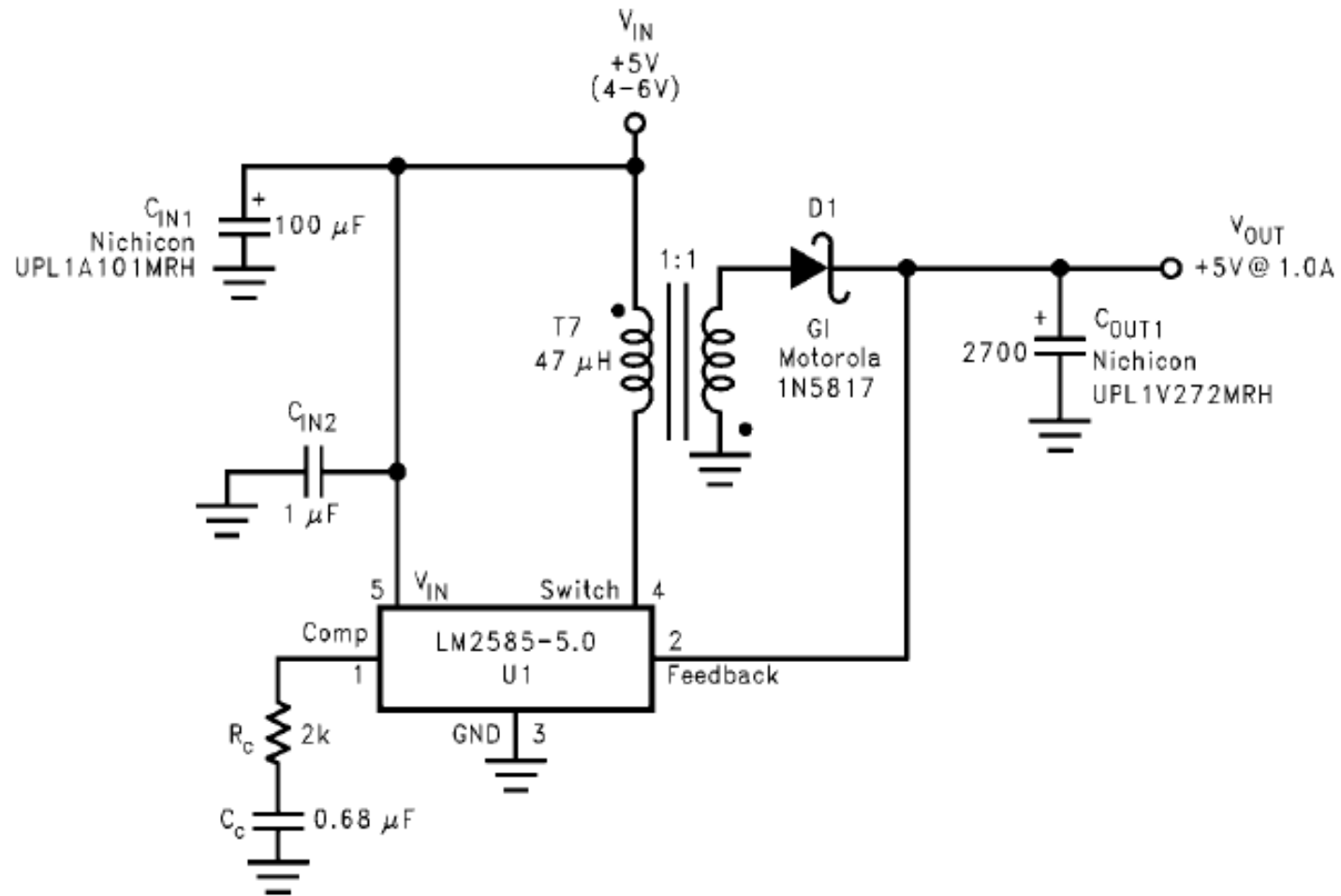
LM2585 with Boost Regulator

National Semiconductors

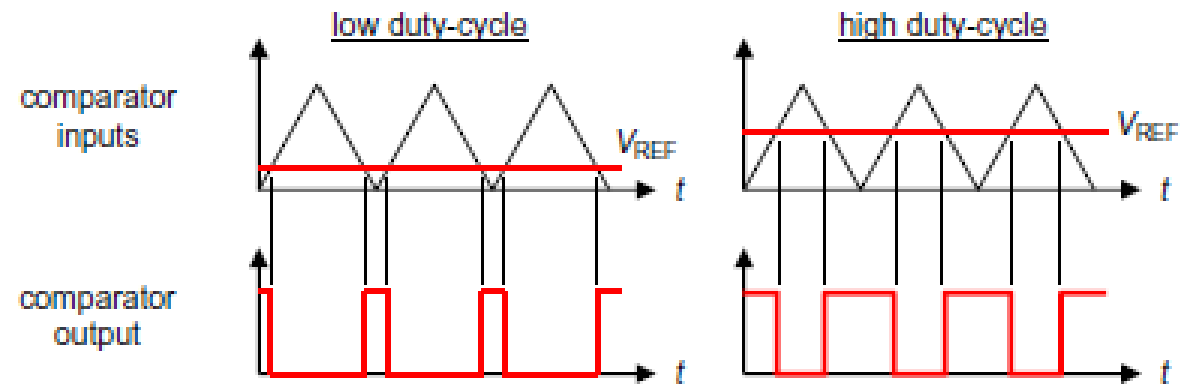
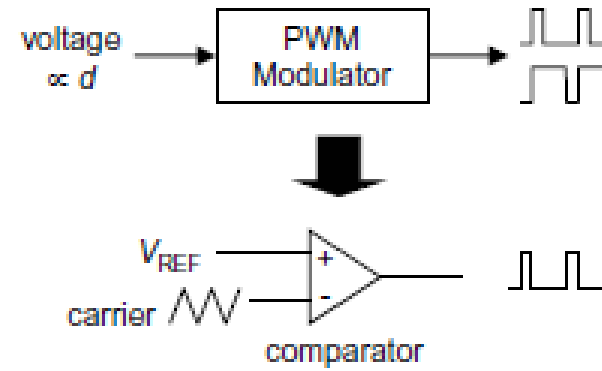


Flyback Converter

(Isolated Power Converter)

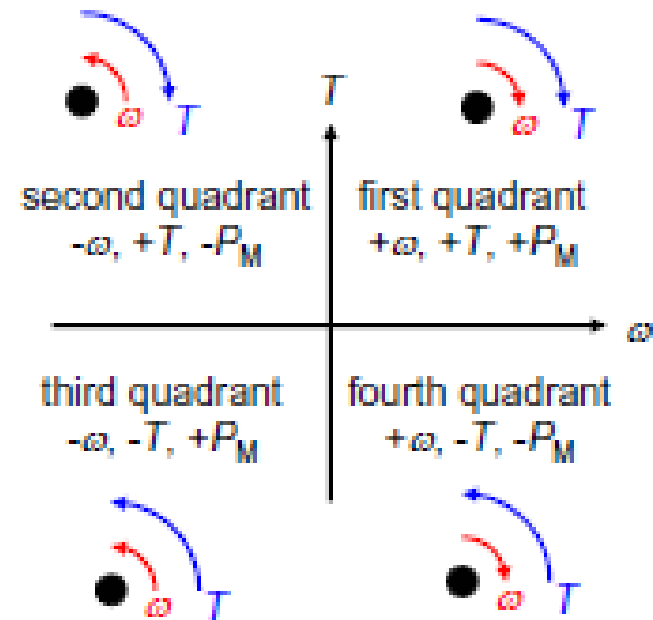


Pulse Width Modulator



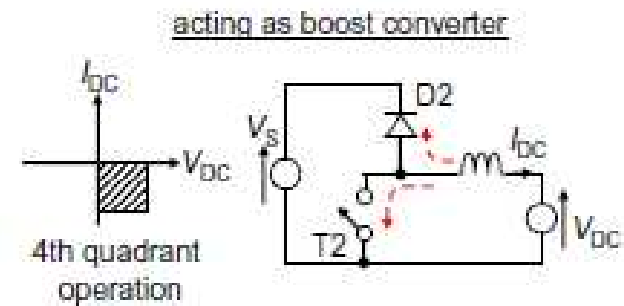
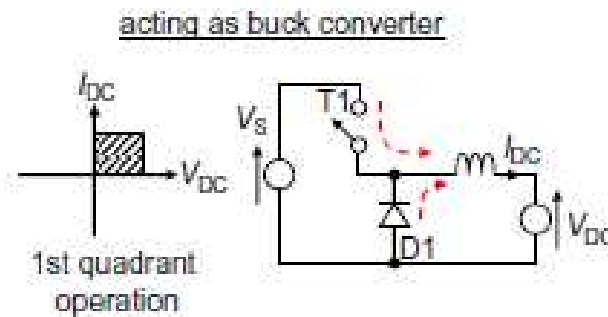
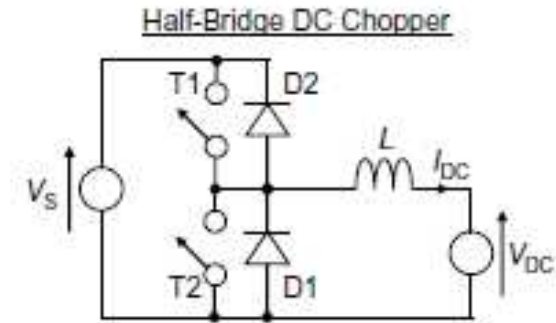
DC Motor Quadrant

- **First:** Steady-State forward driving.
- **Fourth:** Regenerative braking; machine trying to slow down; like breaking for traffic light.
- **Third:** Reverse steady-state driving.
- **Second:** Regenerative braking.



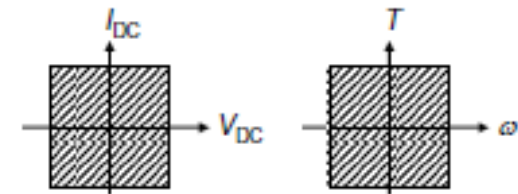
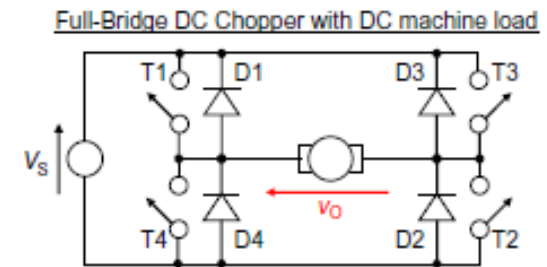
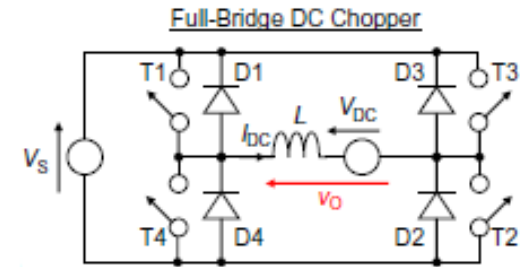
Half-Bridge DC Chopper

- **Buck converter:** Motoring
- **Boost Converter: Generating**
- Two quadrant operating capability



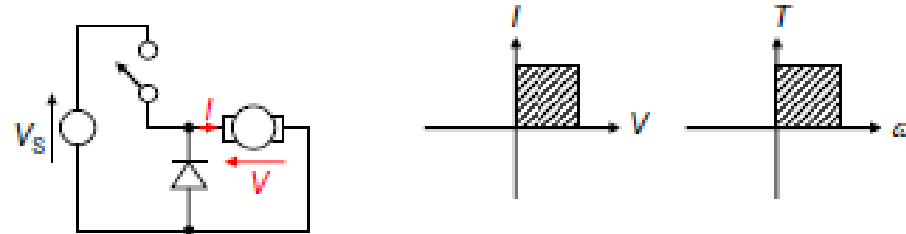
Full-Bridge DC Chopper

- Full-Quadrant Operation
- **T1 and T2 ON:** + Output voltage
- **T3 and T4 ON:** - Output voltage
- **DC current and torque:** + and -
- **DC voltage and speed:** + and -
- All quantities can be positive or negative

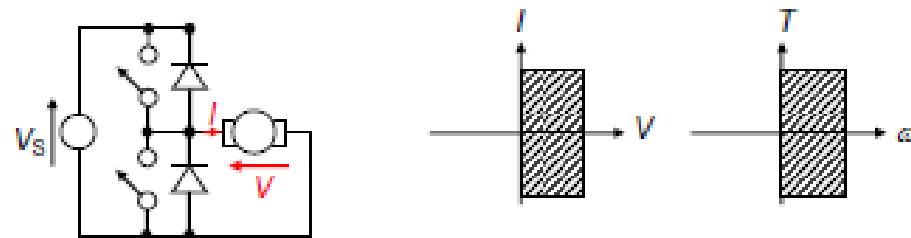


Summary of DC Choppers

- One Quadrant



- Half Bridge



- Full Bridge

