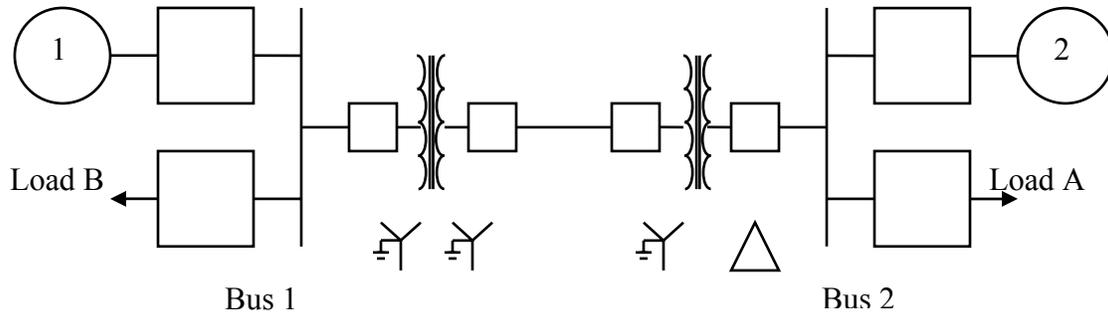
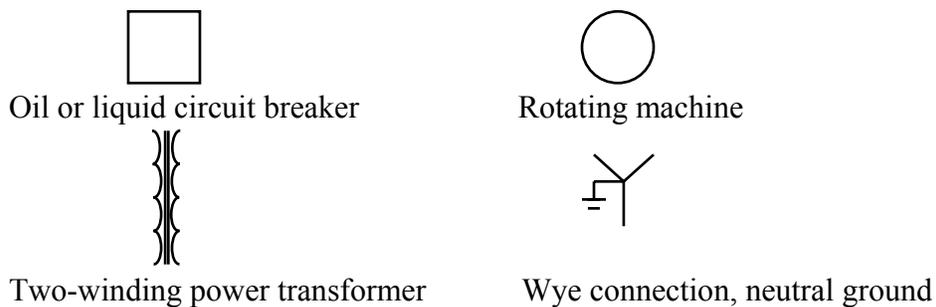


## Power System Representation and Equations



**A one-line diagram of a simple power system**



### Per-Phase, Per Unit System

$$I_{\text{base}} = \frac{S_{3\Phi, \text{base}}}{\sqrt{3}V_{L, \text{base}}}$$

$$Z_{\text{base}} = \frac{V_{L, \text{base}}}{\sqrt{3}I_{\text{base}}}$$

$$Z_{\text{base}} = \frac{(V_{L, \text{base}})^2}{S_{3\Phi, \text{base}}}$$

$$\text{Quantity in per unit} = \frac{\text{actual value}}{\text{base value of quantity}}$$

As we have seen in Chapter 2, many transformers and machines have their internal impedances specified as per unit resistances and reactances, using the voltage and apparent power ratings of the device itself as the base quantity. If these impedances are expressed in per unit to a base other than the one selected as a base for a power system, we must convert the impedances to per unit on the new base. This conversion could be done by using the original base impedance to convert the impedances back into ohms,



$Z_{\text{base},3} = \frac{(V_{L,\text{base}})^2}{S_{3\phi\text{base}}} = \frac{(13.2 \text{ kV})^2}{100 \text{ MVA}} = 1.743 \Omega$	Region 3
---	----------

$R_{G1,\text{pu}} = 0.1 \text{ per unit}$ $X_{G1,\text{pu}} = 0.9 \text{ per unit}$ $R_{T1,\text{pu}} = 0.01 \text{ per unit}$ $X_{T1,\text{pu}} = 0.05 \text{ per unit}$
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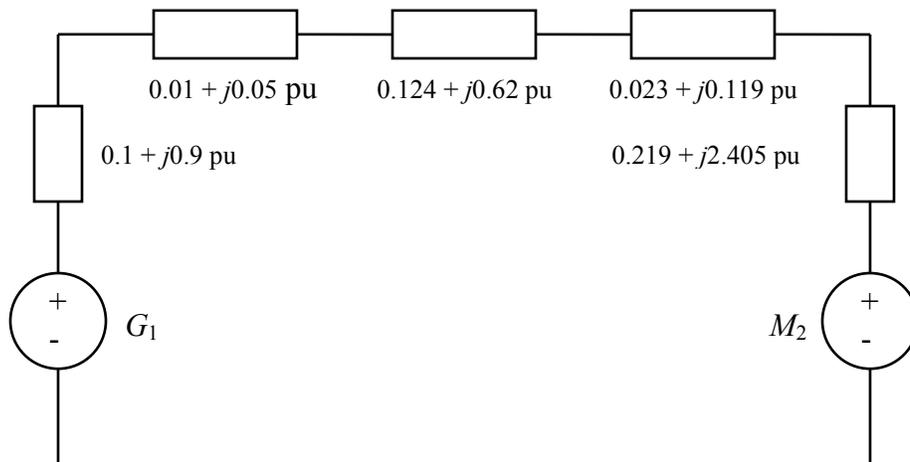
$R_{\text{line, system}} = \left( \frac{15 \Omega}{121 \Omega} \right) = 0.124 \text{ per unit}$ $X_{\text{line, system}} = \left( \frac{75 \Omega}{121 \Omega} \right) = 0.620 \text{ per unit}$
---

$\text{Per - unit } Z_{\text{new}} = \text{per - unit } Z_{\text{given}} \left( \frac{V_{\text{given}}}{V_{\text{new}}} \right)^2 \left( \frac{S_{\text{new}}}{S_{\text{given}}} \right)$
---

$R_{T2,\text{pu}} = (0.01) \left( \frac{14.4 \text{ kV}}{13.2 \text{ kV}} \right)^2 \left( \frac{100 \text{ MA}}{50 \text{ MA}} \right) = 0.238 \text{ per unit}$ $X_{T2,\text{pu}} = (0.05) \left( \frac{14.4 \text{ kV}}{13.2 \text{ kV}} \right)^2 \left( \frac{100 \text{ MA}}{50 \text{ MA}} \right) = 0.119 \text{ per unit}$
---

$\text{Per - unit } Z_{\text{new}} = \text{per - unit } Z_{\text{given}} \left( \frac{V_{\text{given}}}{V_{\text{new}}} \right)^2 \left( \frac{S_{\text{new}}}{S_{\text{given}}} \right)$
---

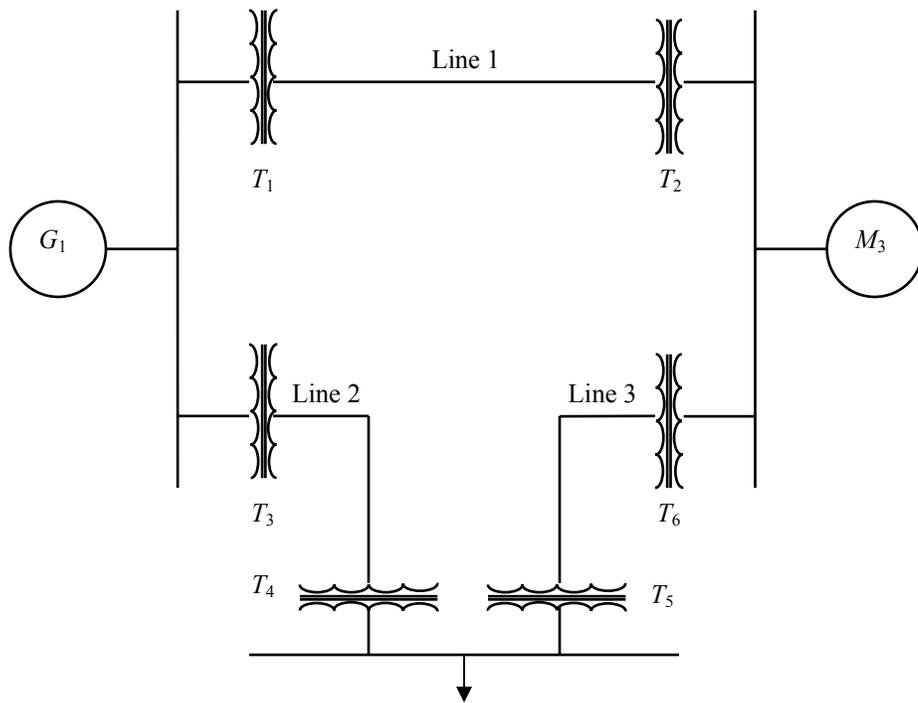
$R_{M2,\text{pu}} = (0.01) \left( \frac{13.8 \text{ kV}}{13.2 \text{ kV}} \right)^2 \left( \frac{100 \text{ MA}}{50 \text{ MA}} \right) = 0.219 \text{ per unit}$ $X_{M2,\text{pu}} = (0.05) \left( \frac{13.8 \text{ kV}}{13.2 \text{ kV}} \right)^2 \left( \frac{100 \text{ MA}}{50 \text{ MA}} \right) = 2.405 \text{ per unit}$
---



Per-phase, per unit equivalent circuit of the simple power system.

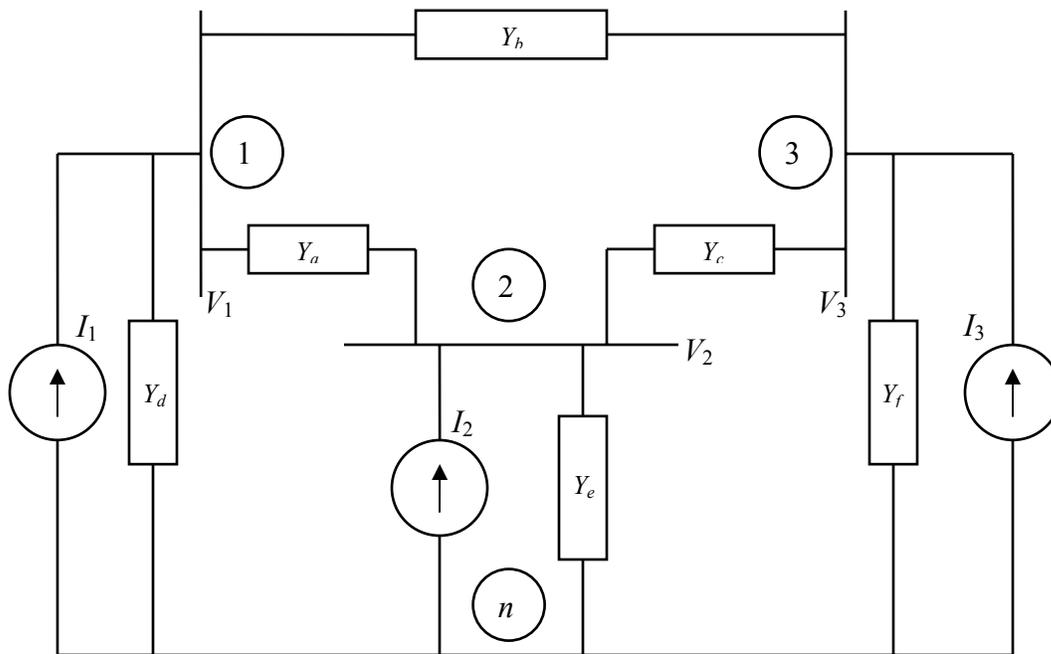
### Writing Node Equations for Equivalent Circuit

Once the per-phase, per unit equivalent circuit of a power system is created, it may be used to find the voltages, currents, and powers present at various points in a power system. The most common technique used to solve such circuits is nodal analysis. In nodal analysis, we use Kirchhoff's current law equations to determine the voltages at each node (each bus) in the power system, and then using the resulting voltages to calculate the currents and power flows at various points in the power system, and then use the resulting voltages to calculate the currents and power flows at various points in the system. Consider the following simple three-phase power system containing three busses connected by three transmission lines. The system includes a generator connected to bus 1, a load connected to bus 2, and a motor connected to bus 3.



Load 2

A simple three-phase power system



Sum of currents out of a node = sum of currents into the node

Apply KCL on node 1

$$(V_1 - V_2)Y_a + (V_1 - V_3)Y_b + V_1Y_d = I_1$$

Apply KCL on node 2

$$(V_2 - V_1)Y_a + (V_2 - V_3)Y_c + V_2Y_e = I_2$$

Apply KCL on node 3

$$(V_3 - V_1)Y_b + (V_3 - V_2)Y_c + V_3Y_f = I_3$$

Rearrange these equations to collect the terms in each voltage

$$(Y_a + Y_b + Y_d)V_1 - Y_aV_2 - Y_bV_3 = I_1$$

$$-Y_aV_1 + (Y_a + Y_c + Y_e)V_2 - Y_cV_3 = I_2$$

$$-Y_bV_1 - Y_cV_2 + (Y_b + Y_c + Y_f)V_3 = I_3$$

The above equation can be expressed in matrix form

$$\begin{bmatrix} Y_a + Y_b + Y_d & -Y_a & -Y_b \\ -Y_a & Y_a + Y_c + Y_e & -Y_c \\ -Y_b & -Y_c & Y_b + Y_c + Y_f \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \\ V_3 \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix}$$

This equation is of the form

$$Y_{\text{bus}} V = I$$

Where  $Y_{\text{bus}}$  is the self admittance of a system.

There are many ways for solving systems of simultaneous linear equations, such as substitution, Gaussian elimination, LU factorization, and so forth! For us, MATLAB has very efficient equation solvers built directly into it! If a system of  $n$  simultaneous linear equations in  $n$  unknowns can be expressed in the form:

$$Ax = b$$

Where  $A$  is  $n \times n$  matrix, and  $b$  is a  $n$ -element column vector. It may be expressed as

$$x = A^{-1}b$$

Where  $A^{-1}$  is the inverse of a matrix!