

Introduction to Combinatorial Algorithms

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Introduction to the course

What are :

- Combinatorial Structures?
- Combinatorial Algorithms?
- Combinatorial Problems?

Combinatorial Structures

Combinatorial structures are *collections* of k -subsets/ k -tuple/permutations from a parent set (finite).

- **Undirected Graphs:**

Collections of 2-subsets (edges) of a parent set (vertices).

$$V = \{1, 2, 3, 4\} \quad E = \{\{1, 2\}, \{1, 3\}, \{1, 4\}, \{3, 4\}\}$$

- **Directed Graphs:**

Collections of 2-tuples (directed edges) of a parent set (vertices).

$$V = \{1, 2, 3, 4\} \quad E = \{(2, 1), (3, 1), (1, 4), (3, 4)\}$$

- **Hypergraphs or Set Systems:**

Similar to graphs, but hyper-edges are sets with possibly more than two elements.

$$V = \{1, 2, 3, 4\} \quad E = \{\{1, 3\}, \{1, 2, 4\}, \{3, 4\}\}$$

Building blocks: finite sets, finite lists (tuples)

● Finite Set

$$X = \{1, 2, 3, 5\}$$

- ▶ unordered structure, no repeats
 - $\{1, 2, 3, 5\} = \{2, 1, 5, 3\} = \{2, 1, 1, 5, 3\}$
- ▶ cardinality (size) = number of elements, $|X| = 4$.

A **k -subset** of a finite set X is a set $S \subseteq X$, $|S| = k$.

For example: $\{1, 3\}$ is a 2-subset of X .

● Finite List (or Tuple)

$$L = [1, 5, 2, 1, 3]$$

- ▶ ordered structure, repeats allowed
 - $[1, 5, 2, 1, 3] \neq [1, 1, 2, 3, 5] \neq [1, 2, 3, 5]$
- ▶ length = number of items, length of L is 5.

An **n -tuple** is a list of length n .

A **permutation** of an n -set X is a list of length n such that every element of X occurs exactly once.

Graphs

Definition

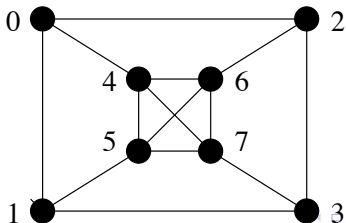
A **graph** is a pair (V, E) where:

V is a finite set (of **vertices**).

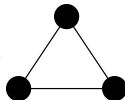
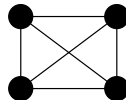
E is a finite set of 2-subsets (called **edges**) of V .

$$G_1 = (V, E)$$

$$V = \{0, 1, 2, 3, 4, 5, 6, 7\} \quad E = \{\{0, 4\}, \{0, 1\}, \{0, 2\}, \{2, 3\}, \{2, 6\}, \\ \{1, 3\}, \{1, 5\}, \{3, 7\}, \{4, 5\}, \{4, 6\}, \\ \{4, 7\}, \{5, 6\}, \{5, 7\}, \{6, 7\}\}$$



Complete graphs are graphs with all possible edges.

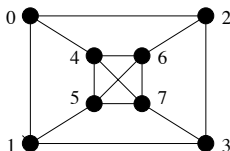
 K_1  K_2  K_3  K_4 

Substructures of a graph: hamiltonian cycle

Definition

A *hamiltonian cycle* is a closed path that passes through each vertex once.

The list $[0, 1, 5, 4, 6, 7, 3, 2]$ describes a hamiltonian cycle in the graph:
(Note that different lists may describe the same cycle.)



Problem (Traveling Salesman Problem)

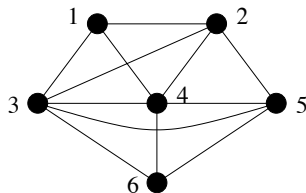
Given a weight/cost function $w : E \rightarrow \mathbb{R}$ on the edges of G , find a smallest weight hamiltonian cycle in G .

Substructures of a graph: cliques

Definition

A *clique* in a graph $G = (V, E)$ is a subset $C \subseteq V$ such that $\{x, y\} \in E$, for all $x, y \in C$ with $x \neq y$.

(Or equivalently: the subgraph induced by C is complete).



- Some cliques: $\{1, 2, 3\}$, $\{2, 4, 5\}$, $\{4, 6\}$, $\{1\}$, \emptyset
- Maximum cliques (largest): $\{1, 2, 3, 4\}$, $\{3, 4, 5, 6\}$, $\{2, 3, 4, 5\}$

Famous problems involving cliques

Problem (Maximum clique problem)

Find a clique of maximum cardinality in a graph.

Problem (All cliques problem)

Find all cliques in a graph without repetition.

Set systems/Hypergraphs

Definition

A *set system (or hypergraph)* is a pair (X, \mathcal{B}) where:

X is a finite set (of *points/vertices*).

\mathcal{B} is a finite set of subsets of X (*blocks/hyperedges*).

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- **Partition of a finite set:**

A partition is a set system (X, \mathcal{B}) such that

$B_1 \cap B_2 = \emptyset$ for all $B_1, B_2 \in \mathcal{B}$, $B_1 \neq B_2$, and $\cup_{B \in \mathcal{B}} B = X$.

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- **Steiner triple system (a type of combinatorial designs):**

\mathcal{B} is a set of 3-subsets of X such that for each $x, y \in X, x \neq y$, there exists exactly one block $B \in \mathcal{B}$ with $\{x, y\} \subseteq B$.

$X = \{0, 1, 2, 3, 4, 5, 6\}$

$\mathcal{B} = \{\{0, 1, 2\}, \{0, 3, 4\}, \{0, 5, 6\}, \{1, 3, 5\}, \{1, 4, 6\}, \{2, 3, 6\}, \{2, 4, 5\}\}$

Combinatorial algorithms

Combinatorial algorithms are algorithms for investigating combinatorial structures.

- **Generation**

Construct all combinatorial structures of a particular type.

- **Enumeration**

Compute the number of all different structures of a particular type.

- **Search**

Find at least one example of a combinatorial structures of a particular type (if one exists).

Optimization problems can be seen as a type of search problem.

● Generation

Construct all combinatorial structures of a particular type.

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- ▶ Generate all cliques of a graph.
- ▶ Generate all maximum cliques of a graph.
- ▶ Generate all Steiner triple systems of a finite set.

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● Enumeration

Compute the number of all different structures of a particular type.

- ▶ Compute the number of subsets/permutat./partitions of a set.
- ▶ Compute the number of cliques of a graph.
- ▶ Compute the number of maximum cliques of a graph.
- ▶ Compute the number of Steiner triple systems of a finite set.

● Search

Find at least one example of a combinatorial structures of a particular type (if one exists).

Optimization problems can be seen as a type of search problem.

- ▶ Find a Steiner triple system on a finite set. (feasibility)
- ▶ Find a maximum clique of a graph. (optimization)
- ▶ Find a hamiltonian cycle in a graph. (feasibility)
- ▶ Find a smallest weight hamiltonian cycle in a graph. (optimization)

Hardness of Search and Optimization

- Many search and optimization problems are **NP-hard** or their corresponding “decision problems” are **NP-complete**.

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- **P** = class of decision problems that can be **solved** in polynomial time. (e.g. Shortest path in a graph is in **P**)
NP = class of decision problems that can be **verified** in polynomial time. (e.g. Hamiltonian path in a graph is in **NP**)
Therefore, **P** \subseteq **NP**.
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- It is believed that **P** \neq **NP** which, if true, would mean that there exist no polynomial-time algorithm to solve an **NP-hard** problem.
- There are several approaches to deal with **NP-hard** problems.

Approaches for dealing with NP-hard problems

● Exhaustive Search

- ▶ exponential-time algorithms.
- ▶ solves the problem exactly

(Backtracking and Branch-and-Bound)

● Heuristic Search

- ▶ algorithms that explore a search space to find a feasible solution that is hopefully “close to” optimal, within a time limit
- ▶ approximates a solution to the problem

(Hill-climbing, Simulated annealing, Tabu-Search, Genetic Algorithms)

● Approximation Algorithms

- ▶ polynomial time algorithm
- ▶ we have a provable guarantee that the solution found is “close to” optimal.

(not covered in this course)

Types of Search Problems

1) Decision Problem:

A yes/no problem

Problem 1: Clique (decision)

Instance: graph $G = (V, E)$,
target size k

Question:

Does there exist a clique C
of G with $|C| = k$?

3) Optimal Value:

Find the largest target size.

Problem 3: Clique (optimal value)

Instance: graph $G = (V, E)$,

Find:

the maximum value of $|C|$,
where C is a clique

2) Search Problem

Find the guy.

Problem 2: Clique (search)

Instance: graph $G = (V, E)$,
target size k

Find:

a clique C of G
with $|C| = k$, if one exists.

4) Optimization:

Find an optimal guy.

Problem 4: Clique (optimization)

Instance: graph $G = (V, E)$,

Find:

a clique C such that
 $|C|$ is maximize (max. clique)

Topics for the Course

Kreher&Stinson, *Combinatorial Algorithms: generation, enumeration and search*

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① **Generating elementary combinatorial objects** [text Chap2]

Sequential generation (successor), rank, unrank.

Algorithms for subsets, k -subsets, permutations.

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② **Exhaustive Generation and Exhaustive Search** [text Chap4]

Backtracking algorithms (exhaustive generation, exhaustive search, optimization)

Branch-and-bound (exhaustive search, optimization)

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- 2 **Exhaustive Generation and Exhaustive Search** [text Chap4]
Backtracking algorithms (exhaustive generation, exhaustive search, optimization)
Branch-and-bound (exhaustive search, optimization)
- 3 **Heuristic Search** [text Chap 5]
Hill-climbing, Simulated annealing, Tabu-Search, Genetic Algs.

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 Backtracking algorithms (exhaustive generation, exhaustive search, optimization)
 Branch-and-bound (exhaustive search, optimization)
- ③ **Heuristic Search** [text Chap 5]
 Hill-climbing, Simulated annealing, Tabu-Search, Genetic Algs.
- ④ **Computing Isomorphism and Isomorph-free Exhaustive Generation** [text Chap 7 + Kaski&Ostergard's book Chap 3,4]
 Graph isomorphism, isomorphism of other structures.
 Computing invariants. Computing certificates.
 Isomorph-free exhaustive generation.

Course evaluation

- 24% Assignments
3 assignments, 8% each
covering: theory, algorithms, implementation
- 25% Midterm Test
- 25% Final Exam
- 26% Project: individual, chosen by student
3% Project proposal (up to 1 page)
15% Project paper (10-15 page)
8% Project presentation (15-20 minute talk)
research (reading papers related to course topics),
original work (involving one or more of: modelling, application,
algorithm design, implementation, experimentation, analysis)