

# Truly Distributed and Ultra-Fast Microwave Photonic Fiber-Optic Sensor

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**Abstract**—Brillouin-based optical fiber sensing has gained considerable attention for the past few years thanks to its ability to offer distributed sensing. The major limitation of a Brillouin-based optical fiber sensor is its complexity because a time-consuming frequency-sweeping process is needed to obtain a local Brillouin gain spectrum (BGS) and to calculate the local Brillouin frequency shift (BFS). Thus, it is only suitable for static or slow-varying measurements. In this article, we propose an approach to achieve truly distributed and ultra-fast fiber-optic sensing based on an active and distributed bandpass microwave photonic filter (MPF) through stimulated Brillouin scattering (SBS). To obtain a truly distributed BFS, a counter-propagating single-shot pump pulse is launched into the fiber link and a microwave multi-tone (MMT) signal with a random initial phase distribution which is phase modulated on an optical carrier is launched into the fiber link from the other end. Due to the SBS effect, the  $-1$ st order sideband of the phase-modulated signal will experience Brillouin amplification while the  $+1$ st order sideband will experience Brillouin attenuation, and the phase-modulated signal is converted to an intensity-modulated signal. The entire operation is equivalent to a bandpass MPF. By detecting the optical signal at a photodetector (PD), a regenerated MMT signal with its magnitude and phase that are shaped by the MPF is obtained. By evaluating the regenerated MMT signal, the Brillouin information corresponding to the temperature or strain change at a specific location is revealed. The major advantage of the approach is that time-consuming frequency-sweeping process is avoided. Truly distributed strain, temperature, and vibration sensing with a 2 m spatial resolution over 49.5 m distance at a speed up to 83.3 kHz is experimentally demonstrated.

**Index Terms**—Microwave photonics, microwave filters, optical fiber sensors, temperature sensors.

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## I. INTRODUCTION

**F**IBER-OPTIC sensors have widely been researched in the last few decades which can find numerous applications such as health monitoring of civil infrastructure, geological hazards prevention and perimeter security protection [1]–[4]. In a distributed fiber-optic sensor, an optical fiber usually plays two roles: as a light transmission medium and as a distributed sensing element. Stimulated Brillouin scattering (SBS) [5], a prominent nonlinear-optical effect, is usually considered as a superior mechanism employed for optical fiber sensing because it can provide high accuracy and long-distance sensing [6], [7]. Generally, Brillouin-based optical fiber sensing is realized by using two counter-propagating optical waves, one as a pump and the other as a probe. When the frequency offset of the two optical waves is close to the Brillouin frequency shift (BFS)  $\nu_B \sim 11$  GHz [8], the energy of the high-frequency pump will be transferred to the low-frequency probe leading to effective narrowband amplification. Since the BFS corresponding to the central frequency of the Brillouin gain (or loss) spectrum (BGS or BLS) is temperature or strain sensitive, by monitoring the BFS change, the temperature or strain can be measured. The major limitation of the approach is that a time-consuming frequency-sweeping process is required to obtain the BGS or BLS. To quickly measure the distributed BGS or BLS, several Brillouin-based approaches have been proposed in which the measurements are done based on the SBS interaction in the optical correlation domain [9]–[12] and the optical time domain [13]–[20].

For the optical correlation-domain approach, two frequency or phase periodically modulated optical waves are counter-propagating from the two ends of a sensing fiber, which is referred to as an analysis scheme. A series of discrete correlation peaks are generated at the locations where the SBS occurs, and the locations of these peaks can be swept by controlling the time delay difference or the modulation frequency between two frequency-modulated optical waves for truly distributed sensing [9]. By sweeping the center frequency difference between the two frequency-modulated optical waves, the corresponding BGS can be obtained. An analysis scheme was implemented to detect a 200-Hz point vibration with a spatial resolution of 10 cm and a sampling rate of 1 kHz [10]. Dynamic strain measurements at arbitrary five points were obtained simultaneously at a sampling rate of 5,000 Hz with random accessibility by using a voltage-controlled oscillator to sweep the BGS and a higher-speed

lock-in amplifier to acquire the data [11]. Then, a truly distributed vibration measurement along a 100-m optical fiber was realized with a sampling rate of 20 Hz via differential frequency-modulating pump wave and probe wave to repeatedly sweep the peak location [12]. However, for these schemes, the truly distributed dynamic measurements were realized by both the frequency-sweeping and the position scanning process, which is again time-consuming and severely limits the sensing speed.

For the optical time-domain approach, Brillouin optical time-domain analysis (BOTDA) is widely reported. Typically, a distributed Brillouin signal can be obtained with a pulsed-pump and a counter-propagated continuous single-tone probe wave, and the position information can be easily identified through the round-trip time of the pump pulse which can avoid the position scanning process. Then, the distributed BGS can be achieved by sweeping the frequency difference between the pump pulse and the probe wave. To increase the sampling rate, techniques such as optical frequency-agile (OFA) technique [13], slope-assisted (SA) method [14], [15], orthogonal frequency-division multiplexing (OFDM) modulation [16], [17], [21] as well as digital optical frequency comb (DOFC) modulation [18], [19], and optical chirp chain (OCC) modulation [20] have been proposed and demonstrated. In the OFA technique, a combination of a 500 MHz arbitrary waveform generator (AWG) and a microwave vector signal generator was employed to generate an electrical frequency-agile signal resulting in fast switching of the optical frequency [13]. A distributed measurement of vibration with a frequency of 100 Hz along a 100-m fiber was achieved at a 10-kHz sampling rate, which was reported in reference [13]. However, the maximum sampling rate of this technique is still limited by the frequency-sweeping process. In the SA technique [14], the distributed BFS can be directly demodulated via the intensity of the Brillouin signal by setting the frequency of the probe wave at the middle of the slope of the BGS, which does not need the frequency-sweeping process. Without averaging, the maximum sampling rate of this technique is basically limited by the round-trip time of pump pulse with respect to the length of the sensing fiber, but the dynamic range is close to the linewidth of the BGS about 35 MHz ( $\sim 700 \mu\epsilon$ ) [14]. To extend the dynamic range, an improved SA-BOTDA was implemented via the OFA technique to generate the frequency-agile probe segments corresponding to multiple slopes, which can increase the dynamic range up to 241 MHz ( $\sim 5000 \mu\epsilon$ ) but sacrifice the sampling rate as it is inversely proportional to the number of the slopes in this approach [15]. In the OFDM method, an OFDM signal was used to generate a dual-polarization probe wave so that the polarization fading in a single-mode fiber can be eliminated leading to a long-distance measurement without the need for averaging. Then, a BGS can be obtained by just launching a single-shot pump pulse into the sensing fiber to interact with a complete broadband OFDM symbol, and the symbol period is inversely proportional to the subcarrier frequency spacing so as to recover the OFDM information symbol without intercarrier interference (ICI) [16], [21]. Furthermore, the BGS distribution can be obtained for a broadband OFDM probe wave that contains a large number of OFDM symbols in series. Although the maximum sampling rate of this technique is only limited by the fiber length,

the spatial resolution is limited by the symbol period of the OFDM symbol, corresponding to tens of meters [16], [17] which is too wide to meet the requirement for practical applications. In the OCC method, an electrical broadband frequency-agile signal whose duration is compressed to 20 ns was used to modulate the probe wave into a short optical chirp segment in which a BGS can be revealed by also counter-propagating a single-shot pump pulse. Then, the BGS distribution can be realized for an optical chirp chain probe wave that cascaded by several short optical chirp segments by a head-to-tail cohesion. A sampling rate up to MHz and a spatial resolution of 2 m had been experimentally demonstrated [20]. However, the BGS distribution in both the OFDM-based technique and the OCC-based technique are arranged symbol-by-symbol (or segment by segment), only quasi-distribution measurement is possible and the Brillouin information between two symbols cannot be demodulated. To sum up, the state-of-the-art approaches mentioned above have some trade-offs for truly distributed sensing, including measurement speed, dynamic range, and spatial resolution.

In this paper, we propose a novel microwave photonic fiber-optic sensor based on a distributed bandpass microwave photonic filter (MPF [22]–[24]) to achieve truly distributed and ultra-fast measurements with a wide dynamic range and a high spatial resolution. A continuous-wave probe wave in the sensing fiber is phase-modulated by a microwave multi-tone (MMT) signal to generate an optical carrier and  $\pm 1$ st order sidebands. For a phase modulated signal if detected directly by a photodetector (PD), since the beating between the optical carrier and the  $+1$ st order sideband and the beating between the optical carrier and the  $-1$ st order sideband have a  $\pi$  phase difference, the two beat signals will fully cancel, and no microwave signal is detected. Due to the SBS effect, however, the  $-1$ st order sideband of the phase-modulated signal will experience Brillouin amplification while the  $+1$ st order sideband will experience Brillouin attenuation, the phase-modulated signal is converted to an intensity-modulated signal [25]. The entire operation is equivalent to a bandpass MPF. By detecting the optical signal at a PD, a regenerated MMT signal with its magnitude and phase that are shaped by the MPF is obtained. By evaluating the MMT signal, the Brillouin information corresponding to the temperature or strain change along the sensing fiber is revealed. Without averaging, the sampling rate of the proposed sensor is only limited by the round-trip time of the pump pulse with respect to the length of the sensing fiber, and the dynamic range can be easily tuned by changing the bandwidth of the MMT signal. To test the performance of the proposed sensor, an experiment for static temperature, strain, and vibration measurement is performed. The results show that high spatial resolution sensing of 2 m over 49.5 m distance at a maximum sampling rate of 83.3 kHz is achieved.

## II. PRINCIPLE

### A. Operation Principle

The proposed sensor is implemented based on an active and distributed bandpass MPF. As shown in Fig. 1(a), both a pulsed-pump and a continuous probe wave are counter-propagated

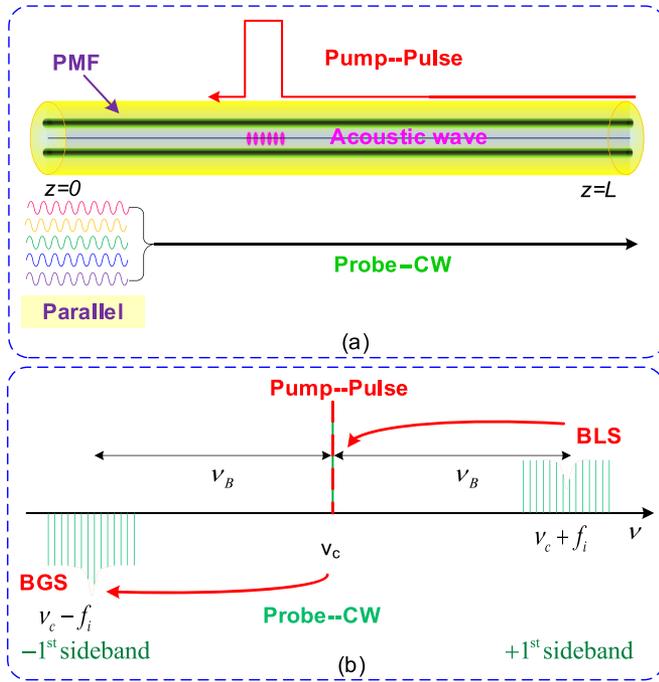


Fig. 1. Operation principle of the proposed sensor. (a) The time relationship between the pump pulse and the continuous probe wave; (b) The frequency relationship between the pump pulse and the phase-modulated probe wave. BGS: Brillouin gain spectrum; BLS: Brillouin loss spectrum; PMF: polarization maintaining fiber.

into a Panda type polarization-maintaining fiber (PMF) used as the sensing fiber to avoid the polarization-dependent fading. The two waves can interact with each other through an acoustic wave due to the SBS effect when their frequency difference is close to the BFS of the PMF. Unlike a conventional BOTDA system with a single-tone probe wave and the OFDM technique using discrete symbols, a continuous and broadband MMT signal with multiple tones is used. The MMT signal is modulated on the probe wave by phase modulation with a small modulation index, to generate an optical carrier and  $\pm 1$ st order sidebands. By detecting the phase-modulated probe wave without the pump pulse, no microwave is recovered due to the cancellation of the two-beat signals. As shown in Fig. 1(b), with a pump pulse that has a frequency equal to that of the optical carrier, the upper sideband of the phase-modulated probe wave is attenuated and the lower sideband is amplified, so that phase-modulation to intensity-modulation conversion for the probe wave is realized. As a result, a regenerated MMT signal containing the local environmental information is obtained by detecting the probe wave. The entire operation is equivalent to an active and distributed bandpass MPF whose local passband is dependent on the local BGS and the power spectrum of the transmitting pump pulse. By making a time-frequency analysis of the regenerated MMT signal, the distribution of the BGS and its BFS can be demodulated. The maximum sampling rate of the proposed sensor is only limited by the repetition rate of the single-shot pump pulse corresponding to the length of the PMF.

An MMT signal with a random initial phase distribution is generated by an AWG. Random initial phase distribution is needed to lower the peak to average power ratio (PAPR) and a more random time-frequency relation. Mathematically, the MMT signal is given

$$y_{\text{MMT}}(t) = \sum_{i=1}^N V_0 \sin(2\pi f_i t + \varphi_i) \quad (1a)$$

$$\varphi_i = \text{random}\{0, 2\pi\} \quad (1b)$$

where  $f_i = f_0 + (i-1)\Delta f$  is the frequency of the  $i^{\text{th}}$  tone and  $\Delta f$  is the frequency interval between two adjacent tones,  $\varphi_i$  is the initial phase of the  $i^{\text{th}}$  tone,  $V_0$  and  $N$  are amplitude and tone number of the MMT signal, respectively. Then, the MMT signal is applied to a phase modulator (PM) to phase-modulate the continuous probe wave. The phase-modulated probe wave is given by

$$\begin{aligned} E_{\text{PM}}(t) &= E_0 \exp \left[ j2\pi\nu_0 t + \sum_{i=1}^N j\gamma \sin(2\pi f_i t + \varphi_i) \right] \\ &= E_0 \exp(j2\pi\nu_c t) \prod_{i=1}^N \exp[j\gamma \sin(2\pi f_i t + \varphi_i)] \\ &= E_0 \exp(j2\pi\nu_c t) \prod_{i=1}^N \sum_{m=-\infty}^{\infty} J_m(\gamma) \\ &\quad \times \exp[jm(2\pi f_i t + \varphi_i)] \end{aligned} \quad (2)$$

where  $E_0$  and  $\nu_c$  are the amplitude of the electric field and the frequency of the optical carrier, respectively;  $j = \sqrt{-1}$ ;  $J_m(\gamma)$  is the  $m^{\text{th}}$  order Bessel function of the first kind,  $\gamma = \pi V_0/V_\pi$  is the modulation index, and  $V_\pi$  is the half-wave voltage of the PM.

For a small modulation index, the 2nd order sideband and the higher-order sidebands are small and can be ignored. As the modulation index increases, the 2nd order and the higher-order sidebands will be excited, resulting in a severe RF noise, which can be eliminated by a digital passband filter. Therefore, we just consider an optical carrier and  $\pm 1$ st order sidebands (i.e.,  $m = 0, \pm 1$ ). Then, Eq. (2) is simplified as

$$\begin{aligned} E_{\text{PM}}(t) &= E_0 J_0^N(\gamma) \exp(j2\pi\nu_c t) \\ &\quad - E_0 J_1(\gamma) \sum_{i=1}^N \exp[j2\pi(\nu_c - f_i t) - j\varphi_i] \\ &\quad + E_0 J_1(\gamma) \sum_{i=1}^N \exp[j2\pi(\nu_c + f_i t) + j\varphi_i] \end{aligned} \quad (3)$$

Since the beat signals generated by the optical carrier and the  $\pm 1$ st sidebands are equal in magnitude but out of phase, no microwave signal is detected at a PD. When both the pump pulse and the phase-modulated probe wave are launched into the PMF, the phase cancellation condition is no longer maintained due to the Brillouin amplification for the  $-1$ st order sideband and the Brillouin attenuation for the  $+1$ st order sideband. Then,

the output is given by

$$\begin{aligned}
 E'_{\text{PM}}(t) &= E_0 J_0^N(\gamma) \exp(j2\pi\nu_c t) \\
 &- E_0 J_1(\gamma) \sum_{i=1}^N H_{\text{BGS}}(f_i, z) \exp[j2\pi(\nu_c - f_i)t - j\varphi_i] \\
 &+ E_0 J_1(\gamma) \sum_{i=1}^N H_{\text{BLS}}(f_i, z) \exp[j2\pi(\nu_c + f_i)t + j\varphi_i]
 \end{aligned} \quad (4)$$

where the  $H_{\text{BGS}}(f_i, z)$  and  $H_{\text{BLS}}(f_i, z)$  are the complex BGS and the complex BLS at position  $z$ , respectively, which are given

$$H_{\text{BGS-BLS}}(f_i, z) = \exp\left\{\frac{\pm g_0 \Delta\nu_B}{\Delta\nu_B + 2j[f_i - \nu_B(z)]}\right\} \quad (5)$$

where  $+$  and  $-$  correspond to the complex BGS and BLS, respectively;  $g_0$  is the peak gain,  $\nu_B(z)$  is the local BFS of the PMF, and  $\Delta\nu_B$  is the linewidth of the BGS. Then, (5) can be approximated by [26]

$$H_{\text{BGS-BLS}}(f_i, z) \approx (1 \pm G_{\text{SBS}}(f_i, z)) \exp(\pm j\varphi_{\text{SBS}}(f_i, z)) \quad (6)$$

where  $G_{\text{SBS}}(f_i, z)$  and  $\varphi_{\text{SBS}}(f_i, z)$  are the BGS and the Brillouin phase-shift spectrum (BPS), respectively, which are given by

$$G_{\text{SBS}}(f_i, z) = \frac{g_0 \Delta\nu_B^2}{\Delta\nu_B^2 + 4[f_i - \nu_B(z)]^2} \quad (7a)$$

$$\varphi_{\text{SBS}}(f_i, z) = -\frac{2g_0 \Delta\nu_B [f_i - \nu_B(z)]}{\Delta\nu_B^2 + 4[f_i - \nu_B(z)]^2} \quad (7b)$$

When the phase-modulated optical probe wave is received at a high-speed PD, an MMT signal is regenerated, which is given by

$$y_{\text{R}}(t) \propto R_{\text{D}} \sum_{i=1}^N G_{\text{SBS}}(f_i, z) \cos(2\pi f_i t + \varphi_i - \varphi_{\text{SBS}}) \quad (8)$$

where  $R_{\text{D}}$  is the responsivity of the PD.

### B. Transfer Function of the Active Bandpass MPF

As the pump pulse is propagating over the sensing fiber, the transfer function of the MPF at position  $z$  can be expressed as

$$|H(f_i, z)| \propto G_{\text{SBS}}(f_i, z) * P_{\text{Pump\_pulse}}(f_i) \quad (9)$$

where  $P_{\text{Pump\_pulse}}(f_i, z)$  is the power spectrum of the pump pulse, and  $*$  is the convolution operator.

### C. Demodulation Process

Different from the OFDM technique which needs a complex demodulation process such as synchronization, fast Fourier transform (FFT), and channel estimation [16], the time-frequency analysis of the regenerated MMT in our proposed sensor will be calculated simply by a short-time Fourier transform (STFT). Finally, a reconstructed BGS is obtained,

given by

$$G'_{\text{SBS}}(f_i, z) = G_{\text{SBS}}(f_i, z) * P_{\text{Pump\_pulse}}(f_i) * P_{\text{window}}(f_i) \quad (10)$$

where  $P_{\text{window}}(f_i)$  is the spectrum of a time window for the STFT.

The center frequency of the reconstructed BGS corresponding to the BFS of the local PMF is a function of the strain and temperature [1],

$$\nu_B(z) = \nu_{B0}(z) + C_\varepsilon \Delta\varepsilon(z) + C_T \Delta T(z) \quad (11)$$

where  $\nu_{B0}(z)$ ,  $\Delta\varepsilon(z)$  and  $\Delta T(z)$  are the initial BFS, the strain change and the temperature change at position  $z$ , respectively.  $C_\varepsilon$  and  $C_T$  are the strain and temperature coefficients of the sensing fiber, respectively.

The measurement speed of the proposed sensor is given by

$$f_{\text{frame}} = \frac{1}{T_{\text{round\_trip}} N_{\text{average}}} \quad (12)$$

where  $T_{\text{round\_trip}}$  is the round-trip flight time over the sensing fiber for the pump pulse, which is given by  $T_{\text{round\_trip}} = 2n_{\text{eff}}L/c$ ,  $n_{\text{eff}}$  is the effective refractive index of the sensing fiber core,  $L$  is the length of the sensing fiber, and  $c$  is the speed of light in vacuum.  $N_{\text{average}}$  is the number of times of averaging. Without averaging, the distributed BGS along the sensing fiber can be obtained by injecting a single-shot pump pulse so that the maximum measurement speed of the proposed distributed sensor is only limited by the fiber length, making the sensor ultra-fast.

### D. Spatial Resolution

Different from an OFDM probe wave or an OCC probe wave which is formed by cascading some symbols, thus it is only able to demodulate one BGS per symbol. For the proposed approach, however, the input MMT signal consisting of multiple sinusoidal waves with a randomized initial phase distribution is continuous in time, thus the time window for calculating the STFT can be moved forward continuously, i.e., truly distributed measurement is possible. The spatial resolution of the proposed microwave photonic fiber-optic sensor is given by

$$\Delta z = \frac{c\Delta t_{\text{p}}}{2n_{\text{eff}}} + \frac{c\Delta t_{\text{window}}}{2n_{\text{eff}}} \quad (13)$$

where  $\Delta t_{\text{p}}$  is the width of the pump pulse,  $\Delta t_{\text{window}}$  is the time window of the STFT. The first term in the right-hand side is the spatial coverage of the pump pulse, and the second term in the right-hand side is the spatial coverage of the time window of the STFT. The interval of the demodulated spatial point is determined by the parameters of the STFT algorithm.

## III. EXPERIMENTAL SETUP

Fig. 2 depicts the schematic diagram of the microwave photonic fiber-optic sensor. A continuous-wave (CW) laser diode (LD) operating at 1550.054 nm with an output power of 15 dBm is employed as a light source. The output light is split into two branches by a 50:50 optical coupler (OC), with the light

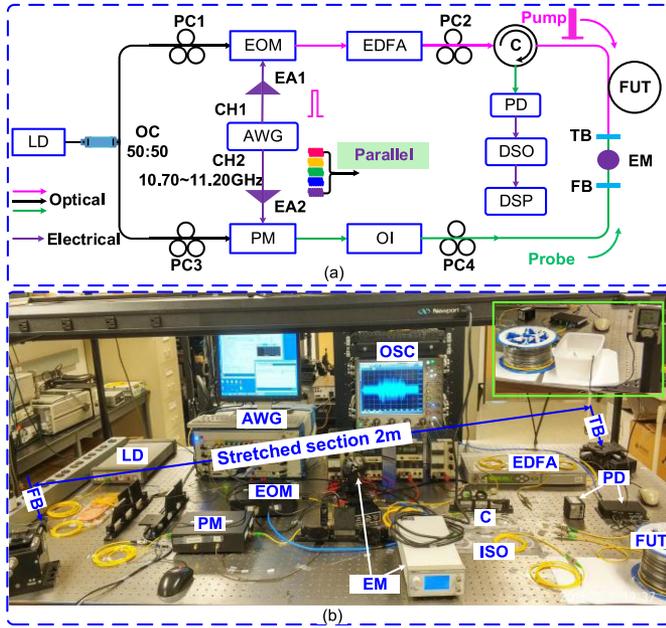


Fig. 2. (a) Schematic diagram of the proposed microwave photonic fiber-optic sensor. (b) A picture showing the experimental setup. Insert in (b) shows temperature measurement setup. LD, laser diode; PC, polarization controller; PM, phase modulator; EOM, electro-optic modulator; AWG, arbitrary waveform generator; EDFA, erbium-doped fiber amplifier; OI, optical isolator; FUT, fiber under test; C, optical circulator; PD, photodetector; DSO, digital storage oscilloscope; DSP, digital signal processing; EA, electrical amplifier; EM, electro-motor; FB, fixed base; TB, tunable base.

in the upper branch being used to generate the optical pump pulse while that in the lower-branch being used to generate the phase-modulated probe wave.

In the upper branch, the CW light wave is converted to an optical pulse by an electro-optic modulator (EOM) driven by a 10-ns electrical pulse generated by an AWG (Keysight M8195A). Then, the optical pulse is amplified up to 34 dBm by an erbium-doped fiber amplifier (EDFA) and used as the pump pulse. The light wave with a power of 1.70 dBm in the lower branch is modulated by an MMT signal, also generated by the AWG at a PM. Both the pump pulse and the phase-modulated probe wave are counter-propagating in a  $\sim 49.5$ -m PMF. The polarization of the light waves is all aligned along the x-polarization axis of the optical devices. Note that both the electrical pump pulse and the MMT signal output from the AWG are synchronized by a synchronization module (Keysight, M8197A).

The phase-modulated probe wave is transmitted via an optical circulator to a PD (OEQuest, LR-12-A-M, 0.01-15 GHz). The regenerated MMT signal from the PD is acquired by a digital storage oscilloscope (Keysight DSO-Z 504A) with a bandwidth of 63 GHz and a sampling rate of 160 GSa/s. Then, the MMT signal is offline-processed by a computer.

Based on (1), a waveform consisting of 51 sinusoidal microwave signals with the frequencies ranging from 10.700 to 11.200 GHz is edited and stored into the memory of the AWG. The output of the AWG is used as the MMT signal, as shown in Fig. 3(a). Then, the MMT signal is used to phase-modulate the

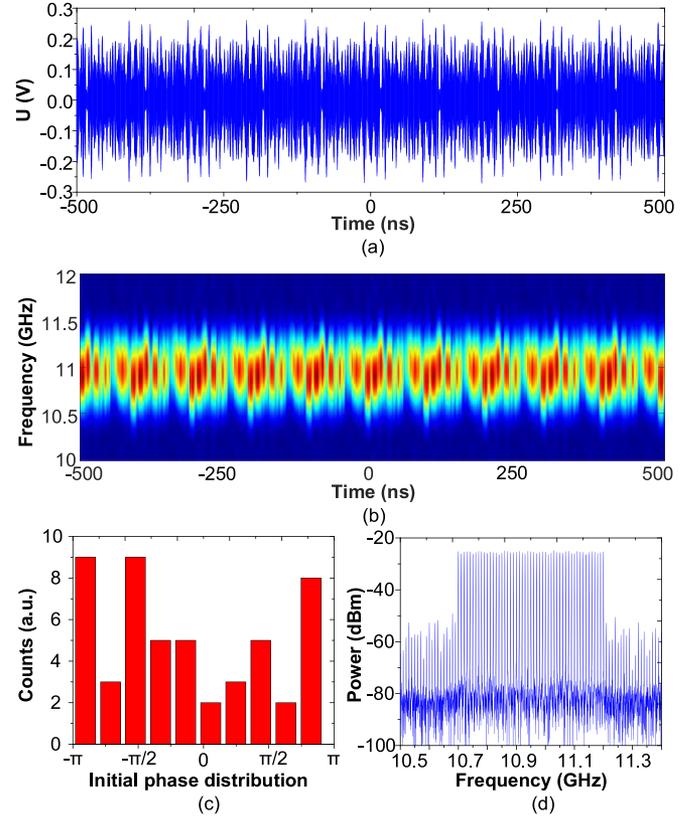


Fig. 3. (a) The waveform and (b) the short-time Fourier transform of the input MMT signal with (c) a randomized initial phase distribution and (d) its electrical power spectrum.

probe wave. As shown in Fig. 3(b), the power spectral density distribution of the short-time Fourier transform is random and uneven because the initial phase of each tone of the MMT signal is randomized, see the distribution in Fig. 3(c). A relatively low PAPR of 9.46 dB is obtained, and, ideally, it will be lower as the tone number increases. As can be seen from the electrical power spectrum in Fig. 3(d), the frequency span of the MMT signal is from 10.700 to 11.200 GHz with a frequency interval of 10 MHz.

The optical power spectrum of the phase-modulated probe wave is measured by an optical spectrum analyzer (OSA, Ando AQ6317B) as shown in Fig. 4. Compared to the optical carrier (blue line) without phase modulation, optical sidebands are generated. The 2nd-order sidebands are 8.8 dB lower than the 1st order sidebands and the higher-order sidebands are much lower than the 1st order sidebands. To eliminate the RF noise generated by the 2nd-order and higher-order sidebands, the regenerated MMT signal is processed by a digital passband filter in the demodulation process for BGS acquisition.

## IV. EXPERIMENTAL RESULTS

### A. Static Measurement of the Proposed Fiber-Optic Sensor

We evaluate the operation of the proposed fiber-optic sensor for static strain measurement. To measure the strain, a section of 2 m of the PMF is stretched by applying different levels of strain.

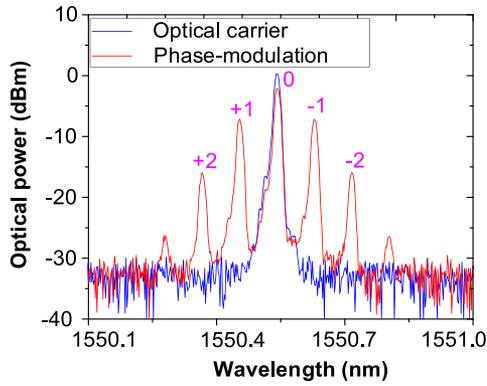


Fig. 4. The power spectrum of the phase-modulated optical probe wave.

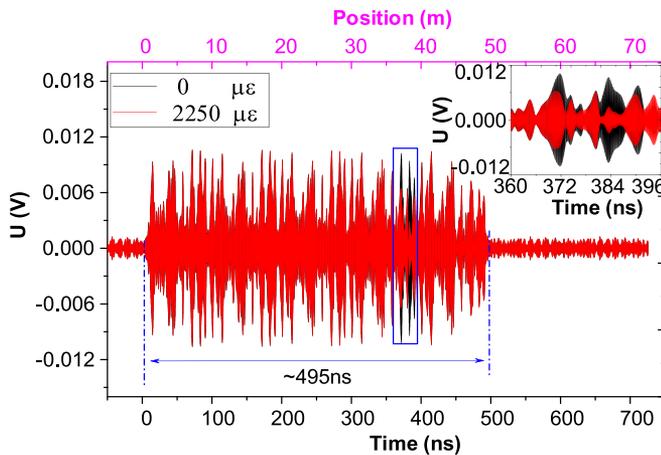


Fig. 5. The regenerated MMT signals corresponding to no strain (black line) and a strain of  $2250 \mu\epsilon$  (red line). Inset is a zoom-in view of the signals in the blue box.

The width of the pump pulse is set at 10 ns, which is small to ensure a high spatial resolution. The regenerated MMT signals are measured with 512 times averaging, and then it is filtered by a digital filter with a passband from 10.0 to 11.8 GHz, to increase the signal-to-noise ratio (SNR). Two regenerated MMT signals corresponding to no strain and a strain of  $2250 \mu\epsilon$  are shown in Fig. 5. Since the magnitude and the phase of the regenerated MMT signal are shaped by the complex BGS, the waveform of the regenerated MMT signal with a slightly lower PAPR of 9.24 dB is different from that in Fig. 3(b). It is clearly shown that the MMT signal is amplified from 0 ns to 495 ns corresponding to 49.5 m of the PMF. The two waveforms are overlapped except a portion in a blue box (a zoom-in view in the insert) corresponding to the PMF from 37 to 39 m where the fiber is stretched.

The regenerated MMT signals are demodulated to reconstruct the BGS by STFT with a time window of 10 ns. Based on Eq. (13), the spatial resolution of the proposed sensor is calculated to be 2 m. Two BGS distributions for the two cases of no strain and a strain of  $2250 \mu\epsilon$  are displayed in Fig. 6(a) and (c), respectively. The power fluctuation of the BGS along the PMF is induced by the non-uniform envelopes of the regenerated MMT

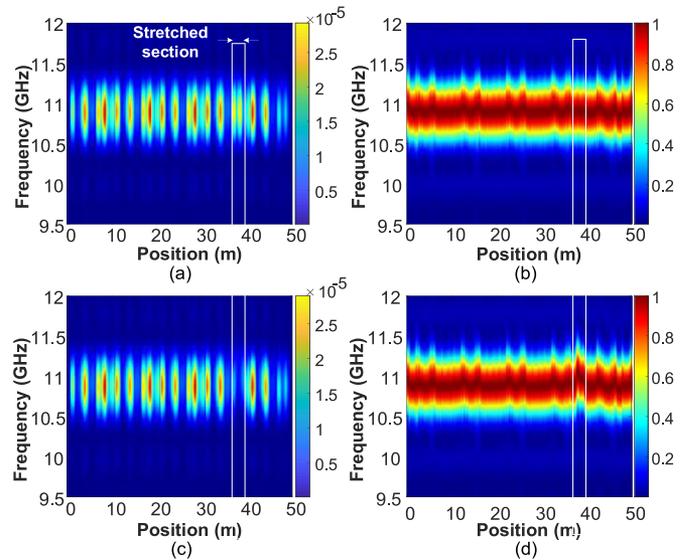


Fig. 6. (a) The BGS distribution and (b) its normalized distribution for the case of no strain; (c) The BGS distribution and (d) its normalized distribution for the case of a strain of  $2250 \mu\epsilon$ . The BGS distribution corresponding to the stretched section is located within the two white lines.

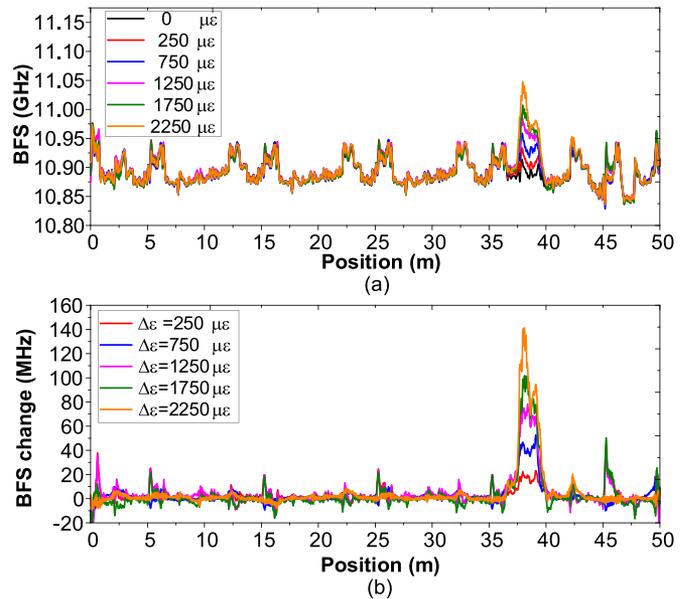


Fig. 7. (a) The BFS distributions versus the position for different strains applied to the PMF. (b) The distributions of the BFS by subtracting the initial BFS distribution.

signals. Then, the normalized BGS distributions are illustrated in Fig. 6(b) and (d). The stretched section is identified between the two white lines where the BGS is clearly up-shifted as the strain increases. It can be concluded that both the magnitude and the frequency span of the MMT signals are reshaped by the active Brillouin-based MPF when the strain applied to the PMF changes.

Subsequently, the BGSs are fitted based on a Lorentzian-curve function to obtain its center frequencies (i.e., the BFS). The BFS distributions are shown in Fig. 7(a), in which the BFSs at

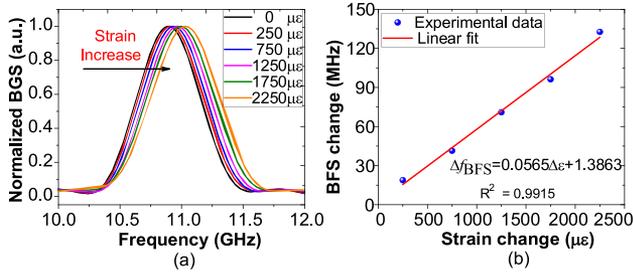


Fig. 8. (a) The BGSs versus the strain change, and (b) the BFS change versus the strain change.

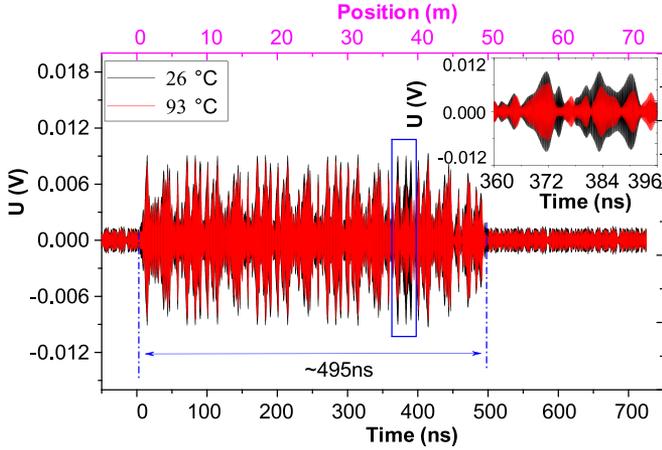


Fig. 9. The regenerated MMT signals for the section of 2 m fiber at a temperature of 26 °C (black line) and 93 °C (red line).

the stretched section are laterally shifted as the strain increases. To eliminate BFS fluctuations, the distributions of the BFSs are computed by subtracting the initial BFS distribution ( $0 \mu\epsilon$ ) from all the BFS distributions, which are shown in Fig. 7(b).

To observe the dependence of the BGS and the applied strain, the BGS with a 16-points averaging around the position 38.11 m are plotted in Fig. 8(a). It is clearly shown that the BGSs are right-shifted as the strain increase from 0 to 2250  $\mu\epsilon$ . Then, the dependence of the BFS change on the strain change is shown in Fig. 8(b). By linear fitting, a strain coefficient  $C_\epsilon = 0.0565 \text{ MHz}/\mu\epsilon$  and a high correlation coefficient ( $R^2$ ) of 0.9915 are obtained.

We also evaluate the static measurement of the proposed fiber-optic sensor for temperature sensing. To do so, the section of 2-m fiber without stretching is embedded in water in a water bath (shown in the inset of Fig. 2). The regenerated MMT signals for a temperature at 26 °C (black line) and 93 °C (red line) are shown in Fig. 9. The waveforms in the inset are apparently shifted as the temperature is increased.

Then, the regenerated MMT signals are demodulated by STFT, and the BGS distributions for the temperatures at 26 °C and 93 °C are shown in Fig. 10(a) and (c), respectively. Their normalized BGS distributions are illustrated in Fig. 10(b) and (d). The BGS between the two white lines (i.e., the heated section) is up-shifted as the temperature is increased from 26 °C to 93 °C.

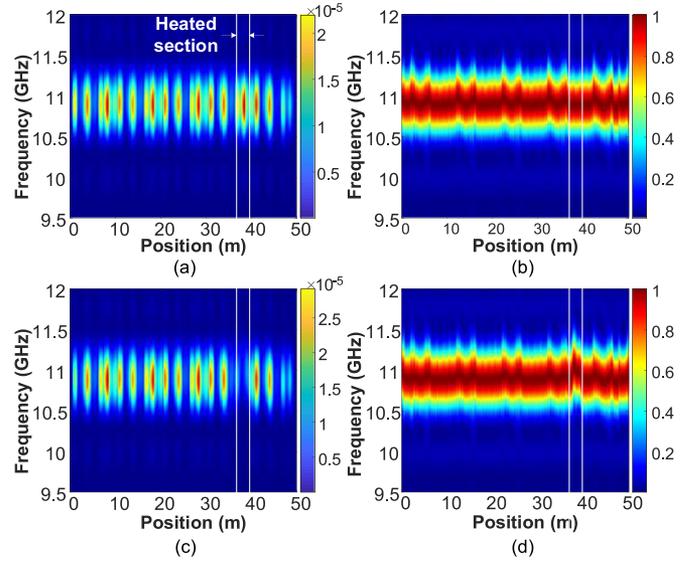


Fig. 10. (a) The BGS distribution and (b) its normalized distribution for the temperature at 26 °C; (c) The BGS distribution and (d) its normalized distribution for the temperature at 93 °C.

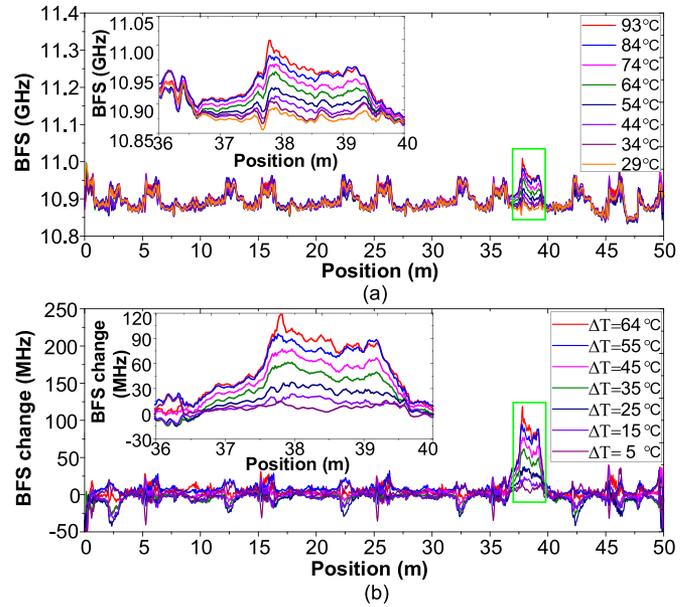


Fig. 11. (a) The BFS distribution and (b) the distribution of the BFS change versus the position for different temperature. Inset is the zoom-in view of the heated section.

Subsequently, the BGSs are fitted based on a Lorentzian-curve function to calculate the BFSs, as shown in Fig. 11(a), in which the BFSs at the heated section are up-shifted. To eliminate the unwanted fluctuation over the BFS distribution, the distributions of the BFS change with a much flat background are calculated by subtracting the initial BFS curve (29 °C) from all the BFS distributions, and they are shown in Fig. 11(b). Then, to further improve the SNR of the BGS, 16 BGS measurements near 38.11 m are averaged, and the averaged BGSs are plotted in Fig. 12(a), which shows a right shift as the temperature increases

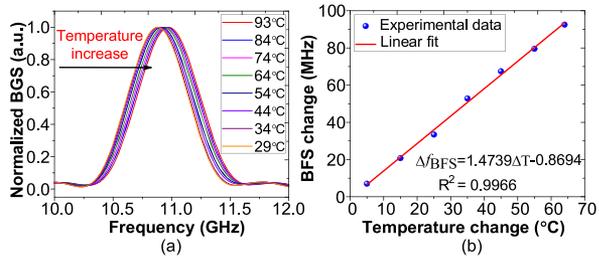


Fig. 12. (a) The BGSs and (b) the BFS changes versus temperature change.

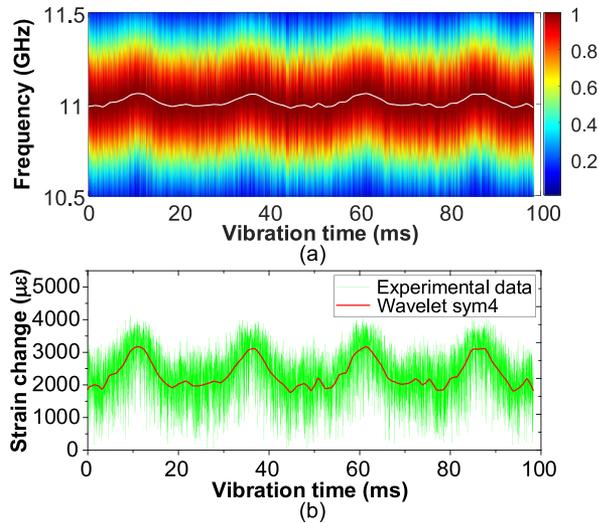


Fig. 13. (a) The time evolution of the BGS (the central white line is the BFS with a denoising method of wavelet sym4). (b) The demodulated vibration waveform.

from 29 °C to 93 °C. The BFS changes over the temperature changes are linearly fitted in Fig. 12(b) resulting in a temperature coefficient  $C_T = 1.4739 \text{ MHz}/^\circ\text{C}$  and a correlation coefficient ( $R^2$ ) of 0.9966.

### B. Vibration Measurement

To test the ability of the proposed sensor for ultra-fast measurements, an electrical motor (EM) is employed to apply a periodic mechanical vibration to the 2-m section of the PMF. Without averaging, the regenerated MMT signals are measured at a sampling rate of 83.3 kHz. It should be pointed out that the maximum sampling rate of this sensor can reach up to 2 MHz which is inversely proportional to the round-trip time of the PMF in theory, but it is limited by the repetition rate of the pump pulse output from the AWG in the experiment. As shown in Fig. 13(a), the time evolution of the BGS at one point within the vibration position is demodulated. It is clearly seen that the whole BGS is periodically shifted along the vibration time. The mechanical vibration waveform, i.e., the strain curve (green) is illustrated in Fig. 13(b), which has a vibration frequency of 33 Hz. Then, the demodulated BFS of the BGS and the strain curve are post-processed by a denoising method of wavelet sym4 with level 7, achieving an SNR improvement of 27 dB, which corresponds to the white line in Fig. 13(a) and the red line in Fig. 13(b).

## V. CONCLUSION AND DISCUSSION

In this work, a microwave photonic fiber-optic sensor has been proposed based on the distributed bandpass MPF to obtain truly distributed and ultra-fast measurement. An MMT signal was modulated on the probe wave and it can be filtered out by a counter-propagating active Brillouin-based MPF with its passband being the convolution between the local BGS of the sensing fiber and the power spectrum of the pump pulse, leading to a regenerated MMT signal. Without averaging, the single measurement can be completed by injecting one single-shot pump pulse so that the sampling rate is only limited by the sensing fiber length. The Brillouin information containing the local temperature or strain is down-converted from the optical domain to the microwave domain, and it can be demodulated by time-frequency analyzing the regenerated MMT signal with STFT. The dynamic range of the proposed sensor can be enlarged by increasing the bandwidth of the input MMT signal. Since the MMT signal consists of multiple single-tone signals with a random initial phase distribution, truly distributed strain and temperature measurements were realized at a high spatial resolution of 2 m which is an order of magnitude higher than that based on the OFDM scheme [17]. Finally, a periodical mechanical vibration with a vibration frequency of 33 Hz is measured at a high sampling rate of 83.3 kHz, with its strain curve being effectively denoised by wavelet sym4. Furthermore, some denoising methods such as image restoration [27] and video-BM3D algorithm [28] can also be used to improve the SNR for ultra-fast vibration measurements.

It should be pointed out that a trade-off between the time (or spatial) resolution and the frequency resolution (measurement errors) exists when using the STFT demodulation process. As shown in Fig. 14, the root mean squared error (RMSE) of the demodulated BFS for static strain measurements can be decreased as the time window of the STFT algorithm is increased. When the time window of the STFT algorithm is 10 ns (corresponding to a high spatial resolution of 2 m), a large RMSE of 22.9 MHz is resulted. When the time window of the STFT algorithm is increased to 200 ns (corresponding to a high spatial resolution of 21 m), a small RMSE of 1.5 MHz is achieved, which is comparable with an ordinary or a coherent BOTDA system and the optical frequency comb schemes such as the OFDM scheme [17] and the DOFC scheme [18], [19]. In the future work, by using a frequency-agile demodulation approach [29] instead of the STFT algorithm, a higher spatial resolution and higher frequency resolution measurements may be obtained. Furthermore, if the MMT signal has a narrower frequency interval and a more uniform initial phase distribution, the non-uniformity of the envelope of the regenerated MMT signal can be effectively mitigated and the unwanted BFS fluctuation could be reduced.

A comparative analysis with existing schemes is shown in Table I. For the regular Brillouin time-domain analysis (BOTDA), coherent BOTDA, and OFA-based BOTDA, multiple pump pulses and the corresponding probe frequency segments are injected into the sensing fiber to complete the frequency sweeping process, which is time-consuming. However, the frequency sweeping process can be realized by launching a

TABLE I  
COMPARATIVE ANALYSIS OF THE EXISTING SCHEMES

Schemes	Frequency switch time	Pump pulse number	Dynamic range	Limitation of the spatial resolution	Truly distribution
Ordinary BOTDA [1]	~ms	~50	~100 MHz	Pulse width (1 m)	Yes
Coherent BOTDA [30]	~ms	51	200 MHz	Pulse width (3 m)	Yes
OFA-based BOTDA [13]	~ns	100	200 MHz	Pulse width (1.3 m)	Yes
Single-slope-assisted BOTDA [14]	0	1	~35 MHz	Pulse width (3 m)	Yes
Multi-slope-assisted BOTDA [15]	~ns	~5	330 MHz	Pulse width (1 m)	Yes
OFDM-BOTDA [17]	0	1	1250 MHz	Symbol period (20.48 m)	No
OCC-BOTDA [20]	~ns	1	400 MHz	Chirp duration (2 m)	No
The proposed BOTDA	0	1	500 MHz	Pulse width and time window (2 m)	Yes

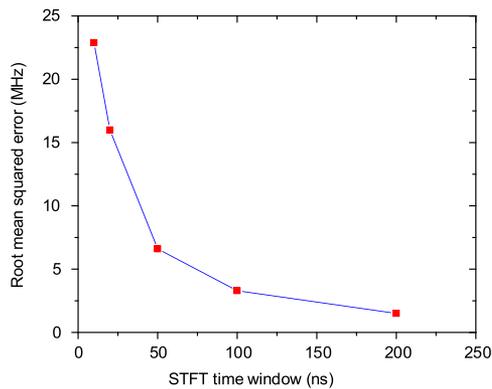


Fig. 14. The RMSE of the demodulated BFS versus the time window of the STFT algorithm.

single-shot pump pulse for the proposed sensor. The slope-assisted BOTDAs have suffered from the tradeoff between sampling rate and wide dynamic range while the single-shot measurement with a wide dynamic range can be obtained by the proposed sensor. Unlike the symbol-by-symbol BGS distribution for the OFDM-BOTDA and the OCC-BOTDA, a truly distributed measurement with a 2-m spatial resolution is obtained for the proposed sensor by moving the time window of the STFT algorithm, and its spatial resolution can be easily tuned by changing the time window of the STFT algorithm.

We believe that the proposed sensor can provide ultra-fast truly distributed measurement with a wide dynamic range and high spatial resolution for practical applications such as health monitoring of large infrastructure, geological hazards prevention, and perimeter security protection.

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