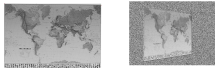


Framework Outline

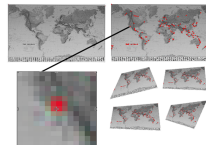
One Time Process



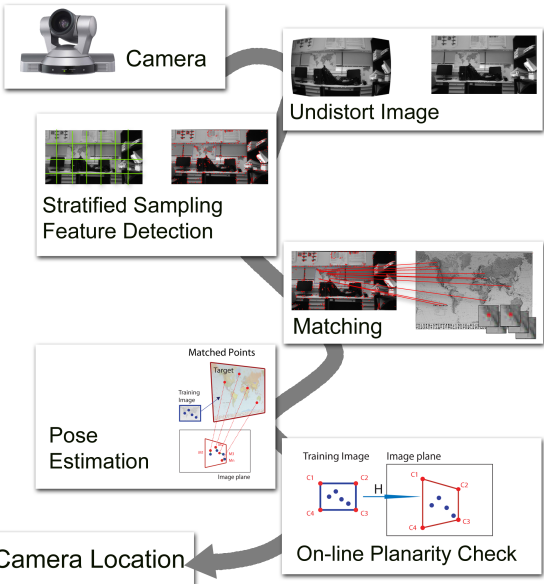
Camera Calibration



Target Acquiring & Evaluation



Target Training



Objective

- Evaluate natural landmarks to be used as targets in the system for robot localization.
- Aid the process of robot localization using natural landmarks using feature matching algorithms and the selected targets for indoor applications.

