

ELG3150: Chapter 3

Problem E3.19

A single-input, single output system has the matrix equations

$$\dot{X} = \begin{bmatrix} 0 & 1 \\ -3 & -4 \end{bmatrix} X + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$$
$$y = [10 \ 0] X$$

Determine the transfer function $G(s) = \frac{Y(s)}{U(s)}$.

Solution

Take Laplace transform of both sides, to get

$$s X(s) = AX(s) + BU(s)$$

$$Y(s) = C X(s)$$

where A , B and C are given as follows

$$A = \begin{bmatrix} 0 & 1 \\ -3 & -4 \end{bmatrix} \text{ and } B = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \text{ and } C = [10 \ 0]$$

then

$$(sI - A) X(s) = BU(s)$$

$$X(s) = (sI - A)^{-1} BU(s)$$

$$Y(s) = C(sI - A)^{-1} BU(s)$$

Hence

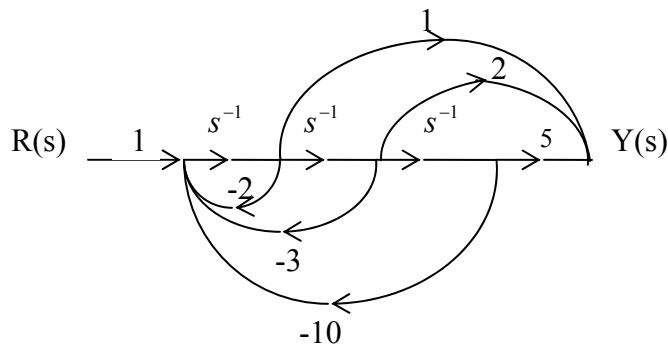
$$G(s) = C(sI - A)^{-1} B = [10 \ 0] \begin{bmatrix} s & -1 \\ 3 & s+4 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \frac{10}{s^2 + 4s + 3}$$

Problem 3.4 (Solution)

$$T(s) = \frac{Y(s)}{R(s)} = \frac{5s^{-3} + 2s^{-2} + s^{-1}}{10s^{-3} + 3s^{-2} + 2s^{-1} + 1}$$

(a) Phase Variables

Note: In this set of exercises, we always take the output of integrators as state variables, with the convention that to start from the right hand side. So in the following figure, x_1 represents the output of the first integrator from right, and x_2 is the output of the middle one, and x_3 is the output of the left hand side integrator.



$$\begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = x_3 \\ \dot{x}_3 = -10x_1 - 3x_2 - 2x_3 + r(t) \\ y(t) = 5x_1 + 2x_2 + x_3 \end{cases}$$

$$\dot{X} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -10 & -3 & -2 \end{bmatrix} X + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} r(t)$$

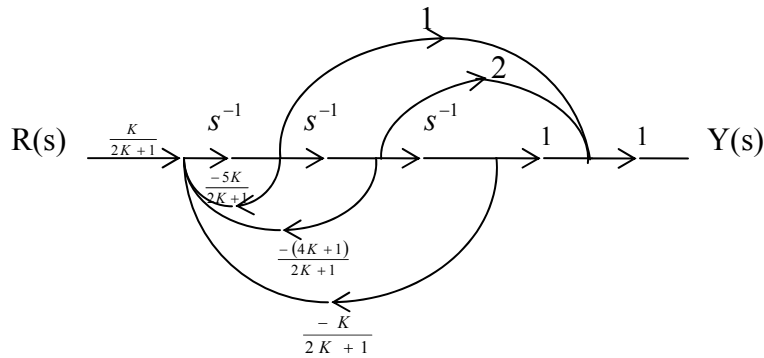
$$y(t) = [5 \quad 2 \quad 1]X$$

Problem 3.7 (Solution)

(a)

$$\frac{Y(s)}{R(s)} = \frac{\frac{K}{s}G(s)}{1 + \frac{K}{s}G(s)} = \frac{K(s^2 + 2s + 1)}{(2K + 1)s^3 + 5Ks^2 + (4K + 1)s + K}$$

$$\frac{Y(s)}{R(s)} = \frac{\frac{K}{2K + 1}(s^{-3} + 2s^{-2} + s^{-1})}{\frac{K}{2K + 1}s^{-3} + \frac{4K + 1}{2K + 1}s^{-2} + \frac{5K}{2K + 1}s^{-1} + 1}$$



$$\begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = x_3 \\ \dot{x}_3 = \frac{-K}{2K+1}x_1 - \frac{4K+1}{2K+1}x_2 - \frac{5K}{2K+1}x_3 + \frac{K}{2K+1}r \\ y(t) = (x_1 + 2x_2 + x_3) \end{cases}$$

$$\dot{X} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ \frac{-K}{2K+1} & \frac{-(4K+1)}{2K+1} & \frac{-5K}{2K+1} \end{bmatrix} X + \begin{bmatrix} 0 \\ 0 \\ \frac{K}{2K+1} \end{bmatrix} r(t)$$

$$y(t) = [1 \quad 2 \quad 1]X$$

(b) Characteristic equation

$$\Delta(s) = (2K + 1)s^3 + 5Ks^2 + (4K + 1)s + K = 0 \quad ; \quad K = 1$$

$$\Delta(s) = 3s^3 + 5s^2 + 5s + 1 = 0$$

$$\begin{cases} s_1 = -0.2551 \\ s_{2,3} = -0.7058 \pm 0.8991j \end{cases}$$

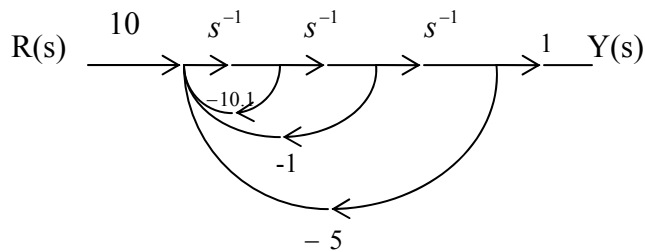
Problem 3.9 (Solution)

(a)

$$T(s) = \frac{10}{s^3 + 10.1s^2 + s + 5}$$

(b)

$$T(s) = \frac{10s^{-3}}{5s^{-3} + s^{-2} + 10.1s^{-1} + 1}$$



$$\begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = x_3 \\ \dot{x}_3 = -5x_1 - x_2 - 10.1x_3 + 10r(t) \\ \omega(t) = x_1 \end{cases}$$

$$\dot{X} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -5 & -1 & -10.1 \end{bmatrix} X + \begin{bmatrix} 0 \\ 0 \\ 10 \end{bmatrix} r(t)$$

$$\omega(t) = [1 \ 0 \ 0]X$$

(c)

$$\Delta(s) = |sI - A| = \begin{vmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 5 & 1 & s+10.1 \end{vmatrix} = s^3 + 10.1s^2 + s + 5 = 0$$

$$\begin{cases} s_1 = -10.05 \\ s_{2,3} = -0.025 \pm j0.7049 \end{cases}$$

Problem 3.18 (Solution)

$$\dot{X} = \begin{bmatrix} 1 & 1 & -1 \\ 4 & 3 & 0 \\ -2 & 1 & 10 \end{bmatrix} X + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u$$

$$y(t) = [20 \ 30 \ 10]X$$

$$\begin{cases} \dot{X} = AX + Bu \\ Y = CX \end{cases}$$

$$Y(s) = C(sI - A)^{-1} B U(s)$$

$$G(s) = \frac{Y(s)}{U(s)} = C(sI - A)^{-1} B = [20 \ 30 \ 10] \begin{bmatrix} s-1 & -1 & +1 \\ -4 & s-3 & 0 \\ 2 & -1 & s-10 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$G(s) = \frac{10s^2 - 60s - 70}{s^3 - 14s^2 + 37s + 20}$$