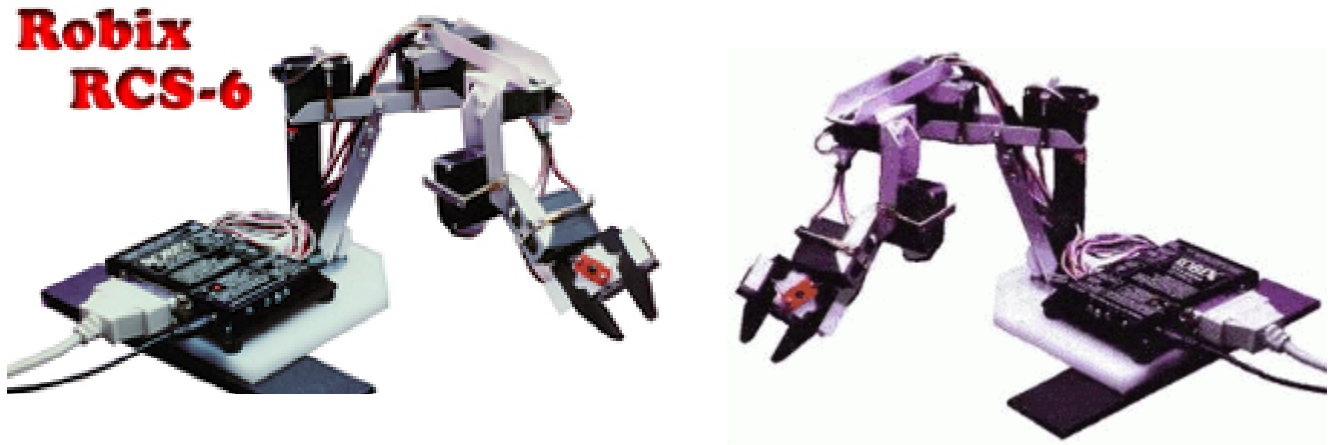


Second Experiment: Transfer of object

Several applications require fine robotic precision. Robots are indeed mainly used due to their fine movements. However, we must very often program these movements so that they can carry out the desired behaviour (for example, picking up an object).



Experiment:

- You must transfer an object from one Robix manipulator to another.
- You must synchronize the movements of the two arms so that the exchange is carried out smoothly.
- Start with a pen and move on to other objects.
- Do not forget to save your program.