

Robo-Garbage Monster

Application: Our robot compacts garbage into microscopic particles

Locomotive Strategy: It uses 6 wheels to move itself around the environment.

Sensory Suite: Light sensors to see, motion sensors to stop it from picking up something alive, heat sensors to see if what ever it is working with is alive or not, sound sensors to receive orders from the director.

Actuator Suite: Claws to pick up garbage and to drop it into the compacting chute, the compactor to compact the garbage.

