Replace this file with prentcsmacro.sty for your meeting, or with entcsmacro.sty for your meeting. Both can be found at the ENTCS Macro Home Page.

Proofs as Polynomials

Esfandiar Haghverdi^{1,??}

School of Informatics Indiana University Bloomington, Indiana, 47408, USA

Philip J. Scott??

Department of Mathematics & Statistics University of Ottawa Ottawa, Ontario, K1N 6N5, CANADA

Abstract

Girard's Geometry of Interaction (GoI) develops a mathematical framework for modelling the dynamics of cut-elimination. In previous work we introduced a typed version of GoI, called Multiobject GoI (MGoI) for multiplicative linear logic [22]. This was later extended to cover the exponentials by the first author [23]. Our development of MGoI depends on a new theory of partial traces, as well as an abstract notion of orthogonality (related to work of Hyland and Schalk.) In this paper, we recall the MGoI semantics for MLL, and give a detailed discussion of how it relates to denotational semantics of MLL in *-autonomous categories. Finally, we prove characterization theorems for the MGoI interpretation of MLL in partially traced categories with an orthogonality, and for the original untyped GoI interpretation of MLL in a traced unique decomposition category.

 ${\it Keywords:} \ \ {\it Geometry of Interaction, traced categories, Unique Decomposition Categories, Characterization Theorems.}$

1 Introduction

Geometry of Interaction (GoI) is an interpretation of linear logic, introduced by Girard in a fundamental series of papers beginning in the late 80's [13,11,14] and continued recently in [15], and [16]. One striking feature of this work is that it provides a mathematical framework for modelling cut-elimination (normalization) as a dynamical process of information flow, independent of logical syntax. Girard introduces methods from functional analysis and operator algebras to model proofs and their dynamical behaviour.

¹ Thanks to everyone who should be thanked

² Email: ehaghver@indiana.edu

³ Email: phil@site.uottawa.ca

In Girard's Geometry of Interaction, the dynamics of cut-elimination is captured in a solution of a system of feedback equations, summarized in an operator $Ex(u,\sigma)$ (the $Execution\ Formula$). We remark that our general categorical framework (based on partial traces) permits a structured approach to solving such feedback equations and deriving properties of the Execution formula. The main feature is that for GoI interpretations of proofs $(u=\theta(\Pi))$ of appropriate types in multiplicative, exponential linear logic (MELL), [13,20], and proofs in System F, [13], $Ex(\theta(\Pi),\sigma)$ is an invariant of cut-elimination.

Categorical foundations of GoI were initiated in the 90's in lectures by M. Hyland and by S. Abramsky. An early categorical framework was given in [4]. Recent work has stressed the role of Joyal-Street-Verity's traced monoidal categories [25] (with additional structure). For example, Abramsky's GoI situations [1,18,3] provide a basic algebraic foundation for GoI MELL. We used a special kind of GoI situation (with traced unique decomposition categories) to axiomatize the details of Girard's original GoI 1 paper [20].

In our previous papers, we emphasized several important aspects of Girard's early GoI papers, especially from the categorical viewpoint:

- (i) The original Girard framework is essentially *untyped*: there is a reflexive object U in the underlying model (with various retractions and/or domain isomorphisms, e.g. $U \otimes U \triangleleft U$).
- (ii) Cut-elimination is interpreted by *feedback*, which can be naturally represented in traced monoidal categories. The execution formula can be defined via a trace and provides an invariant for cut-elimination.
- (iii) Girard introduced an *orthogonality* operation \bot on endomaps of U together with the notion of types (as sets of endomaps equal to their biorthogonal) to interpret the formulas of logic. Orthogonalities have been studied abstractly by Hyland and Schalk [24].
- (iv) Proofs with cuts are thought-of as *algorithms*. One runs these algorithms by applying the Execution formula, a formal power series representing the dynamics of cut-elimination. The convergence of this execution/trace formula leads to cut-free proofs, thought-of as *data*.
- (v) We also emphasize that Girard's GoI, and MGoI in this paper, form a novel interpretation of proofs: one which explicitly incorporates the cuts. For us, the associated mathematical models of MGoI, and their theory of dynamical invariants, form a fundamental structure separate from the denotational literature. However, one can make meaningful comparisons with this literature. We include some basic results of such a comparison here. We show the denotational versus GoI interpretations (when defined) are quite different in general, although in a precise sense they agree on cut-free proofs (but not on formulas!).

Points (i) and (ii) above were already emphasized in the Abramsky program, as well as in the work of Danos and Regnier [1,3,20,7]. The points (1)–(5), especially the last two, are crucial to our overall program of axiomatizing Girard's GoI categorically in [20,21] and to the technical developments in this paper.

The contributions of this paper can be summarized as follows:

- We give a detailed discussion comparing (M)GoI interpretation to denotational semantics.
- We prove a characterization theorem for our MGoI interpretation of MLL in arbitrary partially traced categories with an appropriate orthogonality relation.
- We prove a characterization theorem for the untyped GoI semantics of MLL (fully described in [20]) in a traced UDC-based GoI Situation.

2 Trace Class

The notion of categorical trace was introduced by Joyal, Street and Verity in an influential paper [25]. The motivation for their work arose in algebraic topology and knot theory, although there have been many applications recently in Computer Science. For references and history, see [1,3,20].

In [22] we went one step further and looked at partial traces. The idea of generalizing the abstract trace of [25] to the partial setting is not new. For example, partial traces were already studied in work of Abramsky, Blute, and Panangaden [2], in unpublished lecture notes of Gordon Plotkin [28], work of Blute, Cockett, and Seely [5], and others. For a comparative account, see [22]. We shall briefly recall the notion of partial trace from [22].

Recall, following Joyal, Street, and Verity [25], a (parametric) trace in a symmetric monoidal category $(\mathcal{C}, \otimes, I, s)$ is a family of maps

$$Tr_{X,Y}^U: \mathcal{C}(X \otimes U, Y \otimes U) \to \mathcal{C}(X,Y),$$

satisfying various well-known naturality equations. A partial (parametric) trace requires instead that each $Tr_{X,Y}^U$ be a partial map (with domain denoted $\mathbb{T}_{X,Y}^U$) and satisfy various closure conditions.

Definition 2.1 (Trace Class) Let (C, \otimes, I, s) be a symmetric monoidal category. A *(parametric) trace class* in C is a choice of a family of subsets, for each object U of C, of the form

$$\mathbb{T}^U_{X|Y}\subseteq\mathcal{C}(X\otimes U,Y\otimes U)$$
 for all objects X , Y of \mathcal{C}

together with a family of functions, called a (parametric) partial trace, of the form

$$Tr_{X,Y}^U: \mathbb{T}_{X,Y}^U o \mathcal{C}(X,Y)$$

subject to the following axioms. Here the parameters are X and Y and a morphism $f \in \mathbb{T}_{X,Y}^U$, by abuse of terminology, is said to be *trace class*.

• Naturality in X and Y: For any $f \in \mathbb{T}_{X,Y}^U$ and $g: X' \to X$ and $h: Y \to Y'$,

$$(h \otimes 1_U) f(g \otimes 1_U) \in \mathbb{T}^U_{X',Y'},$$

and
$$Tr_{X',Y'}^{U}((h \otimes 1_U)f(g \otimes 1_U)) = h Tr_{X,Y}^{U}(f) g.$$

• Dinaturality in U: For any $f: X \otimes U \to Y \otimes U'$, $g: U' \to U$,

$$(1_Y\otimes g)f\in \mathbb{T}_{X,Y}^U$$
 iff $f(1_X\otimes g)\in \mathbb{T}_{X,Y}^{U'},$

and

$$Tr_{X,Y}^{U}((1_Y \otimes g)f) = Tr_{X,Y}^{U'}(f(1_X \otimes g)).$$

• Vanishing I: $\mathbb{T}^I_{X,Y} = \mathcal{C}(X \otimes I, Y \otimes I)$, and for $f \in \mathbb{T}^I_{X,Y}$

$$Tr_{X,Y}^I(f) = \rho_Y f \rho_X^{-1}.$$

Here $\rho_A: A \otimes I \to A$ is the right unit isomorphism of the monoidal category.

• Vanishing II: For any $g: X \otimes U \otimes V \to Y \otimes U \otimes V$, if $g \in \mathbb{T}^{V}_{X \otimes U, Y \otimes U}$, then

$$g \in \mathbb{T}_{X,Y}^{U \otimes V} \text{ iff } Tr_{X \otimes U,Y \otimes U}^{V}(g) \in \mathbb{T}_{X,Y}^{U},$$

and

$$Tr_{X,Y}^{U\otimes V}(g) = Tr_{X,Y}^{U}(Tr_{X\otimes U,Y\otimes U}^{V}(g)).$$

• Superposing: For any $f \in \mathbb{T}_{X,Y}^U$ and $g: W \to Z$,

$$g\otimes f\in \mathbb{T}^{U}_{W\otimes X,Z\otimes Y},$$

and

$$Tr_{W\otimes X,Z\otimes Y}^{U}(g\otimes f)=g\otimes Tr_{X,Y}^{U}(f).$$

• Yanking:

$$s_{UU} \in \mathbb{T}_{U,U}^U$$
, and $Tr_{U,U}^U(s_{U,U}) = 1_U$.

A symmetric monoidal category $(\mathcal{C}, \otimes, I, s)$ with such a trace class is called a partially traced category, or a category with a trace class. If we let X and Y be I (the unit of the tensor), we get a family of operations $Tr_{I,I}^U: \mathbb{T}_{I,I}^U \to \mathcal{C}(I,I)$ defining what we call a non-parametric (scalar-valued) trace.

2.1 Examples of Partial Traces

(a) Finite Dimensional Vector Spaces

The category $\mathbf{Vec_{fd}}$ of finite dimensional vector spaces and linear transformations is a symmetric monoidal, indeed an additive, category (see [26]), with monoidal product taken to be \oplus , the direct sum (biproduct). Hence, given $f: \oplus_I X_i \to \oplus_J Y_j$ with |I| = n and |J| = m, we can write f as an $m \times n$ matrix $f = [f_{ij}]$ of its components, where $f_{ij}: X_j \to Y_i$ (notice the switch in the indices i and j).

We give a trace class structure on the category $(\mathbf{Vec_{fd}}, \oplus, \mathbf{0})$ as follows. We shall say an $f: X \oplus U \to Y \oplus U$ is trace class iff $(I - f_{22})$ is invertible, where I is the identity matrix, and I and f_{22} have size dim(U). In that case, we write

(1)
$$Tr_{X,Y}^{U}(f) = f_{11} + f_{12}(I - f_{22})^{-1}f_{21}$$

This definition is motivated by a generalization of the fact that for a matrix A, $(I-A)^{-1} = \sum_i A^i$, whenever the infinite sum converges. Clearly this sum converges when the matrix norm of A is strictly less than 1, or when A is nilpotent, but in both cases the general idea is the desire to have (I-A) invertible. If the infinite sum for $(I-f_{22})^{-1}$ exists, the above formula for $Tr_{X,Y}^U(f)$ becomes the usual "particlestyle" trace in [1,3,20]. One advantage of formula (1) is that it does not a priori

assume the convergence of the sum, nor even that $(I - f_{22})^{-1}$ be computable by iterative methods.

Proposition 2.2 (Vec_{fd}, \oplus , 0) is partially traced, with trace class as above.

The proof of Proposition 2.2 uses the following standard facts from linear algebra, a connection which we find very interesting:

Lemma 2.3 Let
$$M = \begin{bmatrix} A & B \\ C & D \end{bmatrix}$$
 be a partitioned matrix with blocks $A \ (m \times m)$,

 $B\ (m \times n), C\ (n \times m)$ and $D\ (n \times n)$. If $D\ is$ invertible, then $M\ is$ invertible iff $A-BD^{-1}C$ (the Schur Complement of D) is invertible.

Lemma 2.4 Given A $(m \times n)$ and B $(n \times m)$, $(I_m - AB)$ is invertible iff $(I_n - BA)$ is invertible. Moreover $(I_m - AB)^{-1}A = A(I_n - BA)^{-1}$.

The category $(\mathbf{Vec_{fd}}, \oplus)$ is *not* partially traced in the sense of [2].

(c) Metric Spaces

Consider the category **CMet** of complete metric spaces with non-expansive maps. Define $f:(M,d_M) \to (N,d_N)$ to be non-expansive iff $d_N(f(x),f(y)) \leq d_M(x,y)$, for all $x,y \in M$. Note that the tempting collection of complete metric spaces and contractions $(d_N(f(x),f(y)) < d_M(x,y)$, for all $x,y \in M$.) is not a category: there are no identity morphisms! **CMet** has products, namely given (M,d_M) and (N,d_N) we define $(M \times N, d_{M \times N})$ with $d_{M \times N}((m,n),(m',n')) = max\{d_M(m,m'),d_N(n,n')\}$.

We define the trace class structure on **CMet** (where $\otimes = \times$) as follows. We say that a morphism $f: X \times U \to Y \times U$ is in $\mathbb{T}^U_{X,Y}$ iff for every $x \in X$ the induced map $\pi_2 \lambda u. f(x,u): U \to U$ has a unique fixed point; in other words, iff for every $x \in X$, there is a unique u, and a y, such that f(x,u) = (y,u). Note that in this case y is necessarily unique. Also, note that contractions have unique fixed points, by the Banach fixed point theorem.

Suppose $f \in \mathbb{T}_{X,Y}^U$. We define $Tr_{X,Y}^U(f): X \to Y$ by $Tr_{X,Y}^U(f)(x) = y$, where f(x,u) = (y,u) for the unique u. Equivalently, $Tr_{X,Y}^U(f)(x) = \pi_1 f(x,u)$ where u is the unique fixed point of $\pi_2 \lambda t. f(x,t)$.

Proposition 2.5 (CMet, \times , {*}) is a partially traced category with trace class as above.

(d) Total Traces

Of course, all (totally-defined) traces in the usual definition of a traced monoidal category yield a trace class, namely the entire homset is the domain of Tr.

Remark 2.6 (A Non-Example) Consider the structure (CMet, \times). Defining the trace class morphisms as those f such that $\pi_2 \lambda u. f(x, u) : U \to U$ is a contraction, for every $x \in X$, does not yield a partially traced category: all axioms are true except for dinaturality and Vanishing II.

3 Orthogonality Relations

Girard introduced orthogonality relations into linear logic for several reasons; one was to model formulas (or types) as sets equal to their biorthogonal (see [9], [11]). Recently M. Hyland and A. Schalk gave an abstract approach to orthogonality relations in symmetric monoidal closed categories [24]. They also point out that an orthogonality on a traced symmetric monoidal category \mathcal{C} can be obtained by first considering their axioms applied to $Int(\mathcal{C})$, the compact closure of \mathcal{C} , and then translating them down to \mathcal{C} . We follow our treatment in [22].

An axiom involving a partial trace should be read with the proviso: "whenever all traces exist". Finally hereafter, without loss of generality and for readability we consider strict monoidal categories. It is well known that every monoidal category is equivalent to a strict one.

Definition 3.1 Let \mathcal{C} be a traced symmetric monoidal category. An *orthogonality* relation on \mathcal{C} is a family of relations \perp_{UV} between maps $u:V\to U$ and $x:U\to V$

$$V \xrightarrow{u} U \perp_{UV} U \xrightarrow{x} V$$

subject to the following axioms:

(i) $Isomorphism : \text{Let } f: U \otimes V' \to V \otimes U' \text{ and } \hat{f}: U' \otimes V \to V' \otimes U \text{ be such that } Tr^{V'}(Tr^{U'}((1\otimes 1\otimes s_{U',V'})\alpha^{-1}(f\otimes \hat{f})\alpha)) = s_{U,V} \text{ and } Tr^{V}(Tr^{U}((1\otimes 1\otimes s_{U,V})\alpha^{-1}(\hat{f}\otimes \hat{f})\alpha)) = s_{U',V'}. \text{ Here } \alpha = (1\otimes 1\otimes s)(1\otimes s\otimes 1) \text{ with } s \text{ at appropriate types. Note that this simply means that } f: (U,V) \to (U',V') \text{ and } \hat{f}: (U',V') \to (U,V) \text{ are inverses of each other in } \mathcal{G}(\mathcal{C}).$

Then for all $u: V \to U$ and $x: U \to V$,

$$u \perp_{UV} x$$
 iff $Tr_{V',U'}^{U}(s_{U,U'}(u \otimes 1_{U'})fs_{V',U}) \perp_{U'V'} Tr_{U',V'}^{V}((1_{V'} \otimes x)\hat{f});$

that is, orthogonality is invariant under isomorphism.

(ii) Precise Tensor : For all $u: V \to U, v: V' \to U'$ and $h: U \otimes U' \to V \otimes V'$.

$$(u \otimes v) \perp_{U \otimes U', V \otimes V'} h$$

iff

$$u\perp_{UV} Tr_{U,V}^{U'}((1_V\otimes v)h)$$
 and $v\perp_{U'V'} Tr_{U',V'}^U(s_{U,V'}(u\otimes 1_{V'})hs_{U',U}).$

(iii) Identity: For all $u: V \to U$ and $x: U \to V$,

$$u \perp_{UV} x$$
 implies $1_I \perp_{II} Tr_{I,I}^V(xu)$.

(iv) Symmetry: For all $u: V \to U$ and $x: U \to V$,

$$u \perp_{UV} x$$
 iff $x \perp_{VU} u$.

In the context of GoI, we will be working with orthogonality relations on endomorphism sets of objects in the underlying categories. Biorthogonally closed subsets (i.e. $X = X^{\perp \perp}$) of certain endomorphism sets are important as they define *types* (the GoI interpretation of formulae.) We have observed that all the orthogonality

relations that we work with in this paper can be characterized using trace classes. This suggests the following, which seems to cover many known examples.

Example 3.2 [Orthogonality as trace class] Let (C, \otimes, I, Tr) be a partially traced category where \otimes is the monoidal product with unit I, and Tr is the partial trace operator as in Section 2. Let A and B be objects of C. For $f: A \to B$ and $g: B \to A$, we can define an orthogonality relation by declaring $f \perp_{BA} g$ iff $gf \in \mathbb{T}_{I,I}^A$. Axioms can be checked easily, which we omit. It turns out that this is a variation of the notion of Focussed orthogonality of Hyland and Schalk [24].

Hence, from our previous discussion on traces, we obtain the following examples:

- **Vec**_{fd}. For $A \in \mathbf{Vec}_{\mathbf{fd}}$, $f, g \in End(A)$, define $f \perp g$ iff I gf is invertible. Here I is the identity matrix of size dim(A).
- CMet. Let $M \in$ CMet. For $f, g \in End(M)$, define $f \perp g$ iff gf has a unique fixed point.

4 The MGoI Interpretation of MLL

We quickly review the multiobject Geometry of Interaction (MGoI) semantics for multiplicative linear logic without units (MLL) in a partially traced symmetric monoidal category $(\mathcal{C}, \otimes, I, Tr, \perp)$ equipped with an orthogonality relation \perp as in the previous section. Here \otimes is the monoidal product with unit I and Tr is a partial trace operator as in Section 2. We do not require that the category \mathcal{C} have a reflexive object U, so uni-object GoI semantics ([13,20]) may not be possible to carry out in \mathcal{C} .

The MGoI semantics, denoted θ , interprets formulas and proofs inductively in a structure $(\mathcal{C}, \otimes, I, Tr, \bot)$. The ideas below were inspired by Girard's original uniobject GoI semantics referred to above.

Interpreting formulas:

Let A be an object of C and let $f, g \in End(A)$. We say that f is orthogonal to g, denoted $f \perp g$, if $(f, g) \in \bot$. Also given $X \subseteq End(A)$ we define

$$X^{\perp} = \{ f \in End(A) \mid \forall g \in X, f \perp g \}.$$

We now define an operator on the objects of \mathcal{C} as follows: given an object A, $\mathcal{T}(A) = \{X \subseteq End(A) \mid X^{\perp \perp} = X\}$. Elements of $\mathcal{T}(A)$ are often called *types*.

We first define a "compact" interpretation map $[\![-]\!]$ on the formulas of MLL as follows. Given the value of $[\![-]\!]$ on the atomic propositions as objects of \mathcal{C} , we extend it to all formulas by:

- $[A^{\perp}] = [A]$
- $[A \ \ B] = [A \otimes B] = [A] \otimes [B].$

We then define the MGoI-interpretation θ for formulas as follows.

- $\theta(\alpha) \in \mathcal{T}(\llbracket \alpha \rrbracket)$, where α is an atomic formula.
- $\theta(\alpha^{\perp}) = \theta(\alpha)^{\perp}$, where α is an atomic formula.

- $\theta(A \otimes B) = \{a \otimes b \mid a \in \theta(A), b \in \theta(B)\}^{\perp \perp}$
- $\theta(A \otimes B) = \{a \otimes b \mid a \in \theta(A)^{\perp}, b \in \theta(B)^{\perp}\}^{\perp}$

Easy consequences of the definition are: (i) for any formula A, $(\theta A)^{\perp} = \theta(A^{\perp})$, (ii) $\theta(A) \subseteq End(\llbracket A \rrbracket)$, and (iii) $\theta(A)^{\perp \perp} = \theta(A)$. Hence, θ interprets formulas as types.

Interpreting proofs:

We define the MGoI interpretation for proofs of MLL without units, as in [22] (cf. also [20]). Every MLL sequent will be of the form $\vdash [\Delta]$, Γ where Γ is a sequence of formulas and Δ is a sequence of cut formulas that have already been made in the proof of $\vdash \Gamma$ (see [13,20]). This device is used to keep track of the cuts in a proof of $\vdash \Gamma$. A proof Π of $\vdash [\Delta]$, Γ is represented by a morphism $\theta(\Pi) \in End(\otimes \llbracket \Gamma \rrbracket \otimes \llbracket \Delta \rrbracket)$. With $\Gamma = A_1, \dots, A_n, \otimes \llbracket \Gamma \rrbracket$ stands for $\llbracket A_1 \rrbracket \otimes \dots \otimes \llbracket A_n \rrbracket$, similarly for Δ . We drop the double brackets wherever there is no danger of confusion. We also define $\sigma = s \otimes \dots \otimes s$ (m-copies) where s is the symmetry map at different types (omitted for convenience), and $|\Delta| = 2m$. The morphism σ represents the cuts in the proof of $\vdash \Gamma$, i.e. it models Δ . In the case where Δ is empty (that is for a cut-free proof), we define $\sigma: I \to I$ to be 1_I where I is the unit of the monoidal product in \mathcal{C} .

Let Π be a proof of $\vdash [\Delta], \Gamma$. We define the MGoI interpretation of Π , denoted by $\theta(\Pi)$, by induction on the length of the proof as follows.

- (i) Π is an $axiom \vdash A, A^{\perp}, \theta(\Pi) := s_{V,V}$ where $\llbracket A \rrbracket = \llbracket A^{\perp} \rrbracket = V$.
- (ii) Π is obtained using the *cut* rule on Π' and Π'' that is,

$$\begin{array}{ccc} \Pi' & \Pi'' \\ \vdots & \vdots \\ \vdash [\Delta'], \Gamma', A & \vdash [\Delta''], A^{\perp}, \Gamma'' \\ \vdash [\Delta', \Delta'', A, A^{\perp}], \Gamma', \Gamma'' \end{array} cut$$

Define $\theta(\Pi) = \tau^{-1}(\theta(\Pi') \otimes \llbracket \Pi'' \rrbracket) \tau$, where τ is the permutation $\Gamma' \otimes \Gamma'' \otimes \Delta' \otimes \Delta'' \otimes A \otimes A^{\perp} \xrightarrow{\tau} \Gamma' \otimes A \otimes \Delta' \otimes A^{\perp} \otimes \Gamma'' \otimes \Delta''$.

(iii) Π is obtained using the *exchange* rule on the formulas A_i and A_{i+1} in Γ' . That is Π is of the form

$$\begin{array}{c}
\Pi' \\
\vdots \\
\vdash [\Delta], \Gamma' \\
\vdash [\Delta], \Gamma
\end{array}
exchange$$

where $\Gamma' = \Gamma'_1, A_i, A_{i+1}, \Gamma'_2$ and $\Gamma = \Gamma'_1, A_{i+1}, A_i, \Gamma'_2$. Then, $\theta(\Pi) = \tau^{-1}\theta(\Pi')\tau$, where $\tau = 1_{\Gamma'_1} \otimes s \otimes 1_{\Gamma'_2 \otimes \Delta}$.

(iv) Π is obtained using an application of the par rule, that is Π is of the form:

$$\Pi'$$

$$\vdots$$

$$\frac{\vdash [\Delta], \Gamma', A, B}{\vdash [\Delta], \Gamma', A \ \Re \ B} \ \Re \qquad . \ \text{Then } \theta(\Pi) = \theta(\Pi').$$

(v) Π is obtained using an application of the *times* rule, that is Π is of the form:

$$\begin{array}{ccc} \Pi' & \Pi'' \\ \vdots & \vdots \\ \vdash [\Delta'], \Gamma', A & \vdash [\Delta''], \Gamma'', B \\ \vdash [\Delta', \Delta''], \Gamma', \Gamma'', A \otimes B \end{array} \otimes$$

Then $\theta(\Pi) = \tau^{-1}(\theta(\Pi') \otimes \theta(\Pi''))\tau$, where τ is the permutation $\Gamma' \otimes \Gamma'' \otimes A \otimes B \otimes \Delta' \otimes \Delta'' \xrightarrow{\tau} \Gamma' \otimes A \otimes \Delta' \otimes \Gamma'' \otimes B \otimes \Delta''$.

When Δ' and Δ'' are empty sequences, this corresponds to the definition of tensor product in Abramsky's $\mathcal{G}(\mathcal{C})$ (see Appendix A and [1,18].)

Example 4.1 (a) Let Π be the following proof:

$$\frac{\vdash A, A^{\perp} \quad \vdash A, A^{\perp}}{\vdash [A^{\perp}, A], A, A^{\perp}} \ cut$$

Then the MGoI semantics of this proof is given by

$$\theta(\Pi) = \tau^{-1}(s \otimes s)\tau = s_{V \otimes V, V \otimes V}$$

where $\tau = (1 \otimes 1 \otimes s)(1 \otimes s \otimes 1)$ and $\llbracket A \rrbracket = \llbracket A^{\perp} \rrbracket = V$.

(b) Now consider the following proof

$$\begin{array}{c|c} \vdash B, B^{\perp} & \vdash C, C^{\perp} \\ \hline \vdash B, C, B^{\perp} \otimes C^{\perp} \\ \hline \vdash B, B^{\perp} \otimes C^{\perp}, C \\ \hline \vdash B^{\perp} \otimes C^{\perp}, B, C \\ \hline \vdash B^{\perp} \otimes C^{\perp}, B \not\ni C \end{array}.$$

Its denotation is $s_{V \otimes W, V \otimes W}$, where $[B] = [B^{\perp}] = V$ and $[C] = [C^{\perp}] = W$.

Interpreting cut-elimination (dynamics)

Dynamics is at the heart of the GoI interpretation as compared to denotational semantics and it is hidden in the cut-elimination process. The mathematical model of cut-elimination is given by the so called *execution formula* defined as follows:

(2)
$$EX(\theta(\Pi), \sigma) = Tr_{\otimes \Gamma, \otimes \Gamma}^{\otimes \Delta}((1 \otimes \sigma)\theta(\Pi))$$

where Π is a proof of the sequent $\vdash [\Delta], \Gamma, \sigma = s \otimes \cdots \otimes s$ (m times) models Δ , and 2m is the number of formulas in Δ . Note that $EX(\theta(\Pi), \sigma)$ is a morphism from $\otimes \Gamma \to \otimes \Gamma$, when it exists. We shall prove below (see Theorem 5.4) that the execution formula always exists for any MLL proof Π .

Example 4.2 Consider the proof Π in Example 4.1 above. Recall also that $\sigma = s$ in this case (m = 1). Then $EX(\theta(\Pi), \sigma) = Tr((1 \otimes s_{V,V}) s_{V \otimes V,V \otimes V}) = s_{V,V}$.

Note that in this case we have obtained the MGoI interpretation of the cut-free proof of $\vdash A, A^{\perp}$, obtained by applying Gentzen's Hauptsatz to the proof Π .

9

4.1 MGoI versus Denotational Semantics

In the original paper on traced monoidal categories [25], the authors construct a notion of "free compact closure" of a traced monoidal category, $Int(\mathcal{C})$, in which composition is given by the trace. An isomorphic notion (in the symmetric case) was introduced by Abramsky, in his construction $\mathcal{G}(\mathcal{C})$. For an exposition, see [3]. In this subsection we assume the reader is familiar with these constructions, which we call "Int" constructions.

There have been several works interpreting various logics in *Int*-like "GoI" categories, beginning with the Abramsky-Jagadeesan paper [4] as well as unpublished lectures of Hyland, to more recent (and interesting) interpretations of classical logic by Fuhrman and Pym [8]. In all cases, cut is interpreted as composition in an *Int* category.

Let us see to what extent we can compare two obvious kinds of GoI interpretations in a category $\mathcal{G}(\mathcal{C})$: denotational [-] vs our GoI interpretation θ . We shall roughly follow Abramsky and Jagadeesan [4].

Denotational Interpretation of formulas:

Formulas will be interpreted as diagonal objects in $\mathcal{G}(\mathcal{C})$, that is as pairs of objects in \mathcal{C} of the form (V,V). We shall indicate the denotational semantics in $\mathcal{G}(\mathcal{C})$ as $[\![-]\!]_D$ to distinguish it from $\theta(-)^4$, which is used in the MGoI interpretation of formulas and proofs given earlier. We assign arbitrary objects to atomic formulas: $[\![p]\!]_D = (V,V)$, where V is an object in \mathcal{C} . Relative to such an assignment, we define $[\![A^\perp]\!]_D = [\![A]\!]_D$. Also, we define $[\![A \otimes B]\!]_D = [\![A]\!]_D \otimes [\![B]\!]_D$. Note that $[\![A^\perp]\!]_D = [\![A]\!]_D$ for every formula A; indeed suppose $[\![A]\!]_D = (V,V)$, then $[\![A^\perp]\!]_D = (V,V)^\perp = (V,V)$.

Remark 4.3 Notice that if we choose $[\![p]\!]_D = ([\![p]\!], [\![p]\!])$ for atomic formulas p, then $[\![A]\!]_D = ([\![A]\!], [\![A]\!])$ for any formula A, (see Proposition 4.4 below.) This is as far as the resemblance goes, however, since the MGoI interpretation of formulas is $\theta(A)$, not $[\![A]\!]$.

Interpreting proofs: In the denotational semantics into the category $\mathcal{G}(\mathcal{C})$ we shall ignore the information collected in Δ . Let Π be a proof of $\vdash [\Delta], \Gamma$, with $\Gamma = A_1, \dots, A_n$. Then $\llbracket \Pi \rrbracket_D : I \to \otimes \llbracket A_i \rrbracket_D$ in $\mathcal{G}(\mathcal{C})$; in other words, $\llbracket \Pi \rrbracket_D : V_1 \otimes V_2 \otimes \dots \otimes V_n \to V_1 \otimes V_2 \otimes \dots \otimes V_n$ in \mathcal{C} , where $\llbracket A_i \rrbracket_D = (V_i, V_i)$. For a morphism $h : A \otimes B \to C$ in $\mathcal{G}(\mathcal{C})$, let $\Lambda(f) : A \to B^* \otimes C$ denote its transpose.

- $Axiom \vdash A, A^{\perp}$. Then $\llbracket\Pi\rrbracket_D = \Lambda(1_{\llbracket A\rrbracket_D})$. Let $\llbracket A\rrbracket_D = (V, V)$. Then, when translated into \mathcal{C} , we have $\llbracket\Pi\rrbracket_D = s_{V,V}$.
- Cut: Suppose Π is obtained by applying the cut rule on A, A^{\perp} to proofs Π' and Π'' . Suppose also that $\llbracket \Pi' \rrbracket_D = f : I \to \otimes \llbracket \Gamma' \rrbracket_D \otimes \llbracket A \rrbracket_D$ and $\llbracket \Pi'' \rrbracket_D = g : I \to \llbracket A^{\perp} \rrbracket_D \otimes \llbracket \Gamma'' \rrbracket_D$. Then

$$\llbracket \Pi \rrbracket_D : I \to \llbracket \Gamma' \rrbracket_D \otimes \llbracket \Gamma'' \rrbracket_D = \Lambda(\Lambda^{-1}(g)\Lambda^{-1}(f)) .$$

Let
$$\Gamma' = A'_1, \dots, A'_n$$
 and $\Gamma'' = A''_1, \dots, A''_m$, $[\![A'_i]\!]_D = (V'_i, V'_i)$ and $[\![A''_i]\!]_D =$

⁴ changed from [-]!

 (V_i'', V_i'') , and $[\![A]\!]_D = (V, V)$. When translated into \mathcal{C} we get: $\Lambda^{-1}(f): V_1' \otimes \cdots \otimes V_n' \otimes V \to V_1' \otimes \cdots \otimes V_n' \otimes V \text{ and } \Lambda^{-1}(g): V \otimes V_1'' \otimes \cdots \otimes V_m'' \to V \otimes V_1'' \otimes \cdots \otimes V_m''. \text{ So}$

$$\Lambda^{-1}(g): V \otimes V_1'' \otimes \cdots \otimes V_m'' \to V \otimes V_1'' \otimes \cdots \otimes V_m''$$
. So

$$\llbracket \Pi \rrbracket_D = Tr^{V \otimes V}((1_{\Gamma'} \otimes 1_{\Gamma''} \otimes s_{V,V}) \rho^{-1}(\Lambda^{-1}(f) \otimes \Lambda^{-1}(g)) \rho)$$

where ρ is the permutation, $\rho: \llbracket \Gamma' \rrbracket_D \otimes \llbracket \Gamma'' \rrbracket_D \otimes V \otimes V \to \llbracket \Gamma' \rrbracket_D \otimes V \otimes V \otimes \llbracket \Gamma'' \rrbracket_D$

- Exchange: Given $\llbracket \Pi' \rrbracket_D : I \to \otimes \llbracket \Gamma' \rrbracket_D$ with $\Gamma' = \Gamma'_1, A_i, A_{i+1}, \Gamma'_2, \Gamma'_1 = A_1, \dots, A_{i-1}, \Gamma'_2 = A_{i+2}, \dots, A_n$, and $\llbracket A_i \rrbracket_D = (V_i, V_i)$ for all i. We define $[\![\Pi]\!]_D = (1_{\Gamma_1'} \otimes s_{V_i,V_{i+1}} \otimes 1_{\Gamma_2'}) [\![\Pi']\!]_D$. When we translate this into \mathcal{C} we get: given $\llbracket \Pi' \rrbracket_D : V_1 \otimes \cdots \otimes V_i \otimes V_{i+1} \otimes \cdots \otimes V_n \to V_1 \otimes \cdots \otimes V_i \otimes V_{i+1} \otimes \cdots \otimes V_n$, $[\![\Pi]\!]_D = \rho^{-1} [\![\Pi']\!]_D \rho$ where $\rho = 1_{\Gamma'_1} \otimes s_{V_{i+1}, V_i} \otimes 1_{\Gamma'_2}$.
- Tensor: Given $[\![\Pi']\!]_D = f: I \to \otimes [\![\Gamma']\!]_D \otimes [\![A]\!]_D$ and $[\![\Pi'']\!]_D = g: I \to I$ $\otimes \llbracket \Gamma'' \rrbracket_D \otimes \llbracket B \rrbracket_D$, then we define

$$\llbracket \Pi \rrbracket_D : I \to \otimes \llbracket \Gamma' \rrbracket_D \otimes \llbracket \Gamma'' \rrbracket_D \otimes \llbracket A \rrbracket_D \otimes \llbracket B \rrbracket_D = \rho(f \otimes g)$$

where ρ is the permutation $\rho: \otimes \llbracket \Gamma' \rrbracket_D \otimes \llbracket \Gamma'' \rrbracket_D \otimes \llbracket A \rrbracket_D \otimes \llbracket B \rrbracket_D \to \llbracket \Gamma' \rrbracket_D \otimes \llbracket \Gamma' \rrbracket_D$ $[\![A]\!]_D \otimes [\![\Gamma'']\!]_D \otimes [\![B]\!]_D$. Let $\Gamma' = A_1', \cdots, A_n'$ and $\Gamma'' = A_1'', \cdots, A_m''$, $[\![A_i']\!]_D = A_1''$ (V_i', V_i') and $[\![A_j'']\!]_D = (V_j'', V_j'')$, $[\![A]\!]_D = (V, V)$, and $[\![B]\!]_D = (W, W)$. When translated into \mathcal{C} we get $f: V_1' \otimes \cdots \otimes V_n' \otimes V \to V_1' \otimes \cdots \otimes V_n' \otimes V$ and g: $V_1'' \otimes \cdots \otimes V_m'' \otimes W \to V_1'' \otimes \cdots \otimes V_m'' \otimes W$. Then

$$\llbracket \Pi \rrbracket_D = \rho^{-1}(f \otimes g)\rho$$

where ρ is the permutation, $\rho = 1_{\Gamma'} \otimes s_{\Gamma'',V} \otimes 1_W$

• Par: Given $\llbracket \Pi' \rrbracket_D : I \to \otimes \llbracket \Gamma' \rrbracket_D \otimes \llbracket A \rrbracket_D \otimes \llbracket B \rrbracket_D$, define $\llbracket \Pi \rrbracket_D = \llbracket \Pi' \rrbracket_D$.

Proposition 4.4 Let Π be an MLL proof of $\vdash [\Delta], \Gamma$ and σ model Δ . Suppose $\llbracket p \rrbracket_D = (\llbracket p \rrbracket, \llbracket p \rrbracket)$ for all atomic formulas p. Then,

- (i) $[A]_D = ([A], [A])$, for any formula A.
- (ii) $EX(\theta(\Pi), \sigma) = \llbracket \Pi \rrbracket_D$. In particular, if Π is cut-free, (i.e., $|\Delta| = 0, \sigma = 1_I$.) Then, $\theta(\Pi) = \llbracket \Pi \rrbracket_D$.

Example 4.5 Observe that even at the simple level of two axioms joined by a cut, the MGoI and denotational interpretations differ. For let Π be the proof obtained by applying the cut rule to two axioms $\vdash A, A^{\perp}$, and suppose $[\![A]\!]_D = (V, V)$ with $V = [\![A]\!]$ an object of \mathcal{C} . Then the denotational semantics of Π , $[\![\Pi]\!]_D = s_{VV}$. On the other hand, for the MGoI semantics of Π , $\theta(\Pi) = s_{V \otimes V, V \otimes V}$. Note however that we do have: $EX(\theta(\Pi), s_{V,V}) = EX(s_{V \otimes V, V \otimes V}, s_{V,V}) = s_{V,V}$.

Remark 4.6 As we have seen above, the two semantics are entirely different regarding the way they interpret the formulas, and the proof interpretations are related by the Proposition above. In particular, (but only for cut-free proofs), the MGoI and Denotational interpretations into the Int category $\mathcal{G}(\mathcal{C})$ coincide.

In our paper [21] we discussed a noncompact *-autonomous category whose objects are Girard types and whose morphisms arise from the GoI interpretation of proofs. The same construction could be done here. This might be a more natural domain for a denotational modelling than the compact category $\mathcal{G}(\mathcal{C})$ which we worked with above. We shall examine this in the full version of this paper ⁵.

Note that Denotational semantics does not normally keep track of the cuts and has no separate formulation (interpretation) for the removal of cuts (i.e., the execution formula). The removal of cuts is hidden in the composition in the model category. In this paper we want to have cut-elimination steps incorporated directly into the interpretation, but we can compare this with the denotational view as in Proposition 4.4 above.

5 Soundness of the MGoI Interpretation

In this section we recall, without proof, one of the main results of [22]: the soundness of the MGoI interpretation. We show that if a proof Π is reduced (via cut-elimination) to another proof Π' , then $EX(\theta(\Pi), \sigma) = EX(\theta(\Pi'), \tau)$; that is, $EX(\theta(\Pi), \sigma)$ is an invariant of reduction. In particular, if Π' is cut-free (i.e. a normal form) we have $EX(\theta(\Pi), \sigma) = \theta(\Pi')$. Intuitively this says that if one thinks of cut-elimination as computation then $\theta(\Pi)$ can be thought of as an algorithm. The computation takes place as follows: if $EX(\theta(\Pi), \sigma)$ exists then it yields a datum (cf. cut-free proof). This intuition will be made precise below (Theorems 5.4 & 5.6).

The next fundamental lemma (also in several of Girard's papers) is a version of the Church-Rosser theorem. It follows directly from the axioms of trace.

Lemma 5.1 (Associativity of cut) Let Π be a proof of $\vdash [\Gamma, \Delta], \Lambda$ and σ and τ be the morphisms representing the cut-formulas in Γ and Δ respectively. Then

$$EX(\theta(\Pi), \sigma \otimes \tau) = EX(EX(\theta(\Pi), \tau), \sigma) = EX(EX((1 \otimes s)\theta(\Pi)(1 \otimes s), \sigma), \tau),$$

whenever all traces exist.

The next definitions are analogous to concepts arising in realizability and Girard's method of *candidats* (cf. [10]). We work in a partially traced symmetric monoidal category equipped with an orthogonality relation. We suppress mentioning the use of the Symmetry axiom of the orthogonality relation.

Definition 5.2 Let
$$\Gamma = A_1, \dots, A_n$$
 and $V_i = [A_i]$.

• A datum of type $\theta\Gamma$ is a morphism $M: \otimes_i V_i \to \otimes_i V_i$ such that for any $a_i \in \theta(A_i^{\perp})$, we have $\otimes_i a_i \perp M$ and both $M \cdot a_1$ and $M \cdot$ below exist, where

$$M \cdot a_1 := Tr^{V_1}(s_{\otimes_{i \neq 1} V_i, V_1}^{-1}(a_1 \otimes 1_{V_2} \otimes \cdots \otimes 1_{V_n}) M s_{\otimes_{i \neq 1} V_i, V_1})$$
$$M \cdot (a_2 \otimes \cdots \otimes a_n) := Tr^{V_2 \otimes \cdots \otimes V_n}((1 \otimes a_2 \otimes \cdots \otimes a_n) M)$$

• An algorithm of type $\theta\Gamma$ is a morphism $M: \otimes_i V_i \otimes \llbracket \Delta \rrbracket \to \otimes_i V_i \otimes \llbracket \Delta \rrbracket$ for some $\Delta = B_1, B_2, \dots, B_{2m}$ with m a nonnegative integer and $B_{2i} = B_{2i-1}^{\perp}$ for $i = 1 \cdots, m$, such that if $\sigma: \otimes_{j=1}^{2m} \llbracket B_j \rrbracket \to \otimes_{j=1}^{2m} \llbracket B_j \rrbracket$ is $\otimes_{j=1}^m s_{\llbracket B_{2j-1} \rrbracket, \llbracket B_{2j} \rrbracket}$, $EX(M,\sigma)$ exists and is a datum of type $\theta\Gamma$. (Here σ is defined to be 1_I for m = 0, that is when Δ is empty.)

⁵ Added

Lemma 5.3 Let $\widetilde{\Gamma} = A_2, \dots, A_n$ and $\Gamma = A_1, \widetilde{\Gamma}$. Let $V_i = [\![A_i]\!]$, and $M : \otimes_i V_i \to \otimes_i V_i$, for $i = 1, \dots, n$. Then, M is a datum of type $\theta(\Gamma)$ iff for all $a_i \in \theta(A_i^{\perp})$, $M \cdot a_1$ and $M \cdot (a_2 \otimes \cdots \otimes a_n)$ (defined as above) exist and are in $\theta(\widetilde{\Gamma})$, and $\theta(A_1)$, respectively.

Theorem 5.4 (Proofs as algorithms) Let Π be an MLL proof of a sequent $\vdash [\Delta], \Gamma$. Then $\theta(\Pi)$ is an algorithm of type $\theta\Gamma$.

Corollary 5.5 (Existence of Dynamics) Let Π be an MLL proof of a sequent $\vdash [\Delta], \Gamma$. Then $EX(\theta(\Pi), \sigma)$ exists.

Theorem 5.6 (EX is an invariant) *Let* Π *be an MLL proof of a sequent* $\vdash [\Delta], \Gamma$. Then,

- If Π reduces to Π' by any sequence of cut-eliminations, then $EX(\theta(\Pi), \sigma) = EX(\theta(\Pi'), \tau)$. So $EX(\theta(\Pi), \sigma)$ is an invariant of reduction.
- In particular, if Π' is any cut-free proof obtained from Π by cut-elimination, then $EX(\theta(\Pi), \sigma) = \theta(\Pi')$.

6 Proofs as Polynomials

6.1 Proofs as Permutations in MGoI

In this section we prove a characterization theorem for the MGoI interpretations of proofs as special permutations. This is similar to familiar representations of proofs in **MLL** via permutations, [12] although the details here will be used in the next section to give a characterization of **MLL** proofs in untyped GoI via formal polynomials.

Proposition 6.1 Let Π be an MLL proof of $\vdash [\Delta]$, Γ where $|\Delta| = 2m$ and $|\Gamma| = n$ (counting occurrences of propositional variables). Then $\theta(\Pi)$ is a fixed-point free involutive permutation on n + 2m objects of C. That is $\theta(\Pi) : V_1 \otimes \cdots \otimes V_{n+2m} \to V_1 \otimes \cdots \otimes V_{n+2m}$ induces a permutation π on $\{1, 2 \cdots, n+2m\}$ and

- $\pi^2 = 1$
- For all $i \in \{1, 2, \dots, n+2m\}, \ \pi(i) \neq i$.
- For all $i \in \{1, 2, \dots, n+2m\}, V_i = V_{\pi(i)}$.

Proof. By induction on the length of the proof Π .

So the above Proposition 6.1 shows that the denotation of a proof $\theta(\Pi)$ induces a fixed-point free involutive permutation. We now seek a converse.

Theorem 6.2 (Characterization) Let M be a fixed-point free involutive permutation from $V_1 \otimes \cdots \otimes V_n \to V_1 \otimes \cdots \otimes V_n$ (induced by a permutation μ on $\{1, 2, \dots, n\}$) where n > 0 is an even integer, $V_i = [\![A_i]\!]$, and $V_i = V_{\mu(i)}$ for all $i = 1, \dots, n$. Then there is a provable MLL formula ϕ built from the A_i , with a cut-free proof Π such that $\theta(\Pi) = M$.

Proof. We define a formula ϕ out of the A_i and $A_i^{\perp} = A_{\mu(i)}$ and show that it is provable by constructing a proof net for it. The proof Π in sequent calculus is

then completely determined by ϕ . Here is the algorithm for the construction of the formula ϕ .

- (i) Initialize $\phi := A_1$
- (ii) For i := 2 to n do
- (iii) If $\mu(i) < i$ then $\phi := (\phi \Re A_i)$,
- (iv) else, $\phi := (\phi \otimes A_i)$

In order to construct the proof structure for ϕ , we first arrange the A_i in increasing order of their indices. Note that the proof structure for ϕ is uniquely determined: given the permutation μ , the axiom links are uniquely specified by connecting A_i to $A_i^{\perp} = A_{\mu(i)}$. In the full paper we show that it is a proof net. The proof Π is cut-free by construction. It remains to show that $\theta(\Pi) = M$. Note that $\theta(\Pi)$ is an endomorphism on $V_1 \otimes \cdots \otimes V_n$ as the variables in ϕ occur in increasing order from A_1 to A_n . The permutation induced by $\theta(\Pi)$ on $\{1, \dots, n\}$ is uniquely determined by the location of formulas (as they occur in ϕ) connected by axiom link specifications, which are given by μ . Thus we have that $\theta(\Pi) = M$.

Let's consider an example:

Example 6.3 Suppose μ is given by (1,4)(2,3) on the set $\{1,2,3,4\}$. Then following the algorithm above we get

$$\phi(A_1, A_2, A_3, A_4) = \phi(A_1, A_2, A_2^{\perp}, A_1^{\perp}) = ((A_1 \otimes A_2) \ \Re \ A_2^{\perp}) \ \Re \ A_1^{\perp}$$

and one possible Π is (ignoring exchange):

$$\frac{ \begin{matrix} \vdash A_1, A_1^{\bot} & \vdash A_2, A_2^{\bot} \\ \vdash A_1 \otimes A_2, A_1^{\bot}, A_2^{\bot} \\ \vdash (A_1 \otimes A_2) \ \ \ A_2^{\bot}, A_1^{\bot} \end{matrix}}{\vdash ((A_1 \otimes A_2) \ \ \ \ A_2^{\bot}) \ \ \ \ A_1^{\bot}}$$

As an application of this result, in the final section we prove a characterization theorem for MLL in any traced Unique Decomposition Category with a reflexive object U, under (uni-object) GoI semantics [20].

6.2 A Characterization Theorem For Uni-GoI Semantics

Theorem 6.2 in Section 6.1 may be applied to give a characterization theorem for the untyped (i.e. uni-object) GoI semantics for MLL, as discussed in our papers [20,21]. The theorem below is related to work of Danos and Regnier on *path-based computing* [7] ⁶: we hope in future work to detail these connections. We shall recall only the definitions that we use in the theorem below and refer the reader to [20] for details about GoI semantics in UDCs.

Let C be a traced UDC and U be a reflexive object in C with retraction pair (j,k), that is $U \otimes U \triangleleft U$ (j,k). We shall use j_1, j_2, k_1, k_2 to denote the components of j and k respectively, (In Girard's terminology [13] $j_1 = p, j_2 = q, k_1 = p^*, k_2 = q^*$.)

 $^{^6}$ added

Definition 6.4 Formal polynomials are defined as the set \mathcal{E} of expressions built on the set $\mathcal{A} = \{0, 1, j_1, j_2, k_1, k_2\}$ using binary operations + and \cdot (which we shall omit writing) subject to the axioms:

- (i) $(\mathcal{E}, +, \cdot, 0, 1)$ is a commutative semiring, and
- (ii) $k_1j_1 = 1, k_2j_2 = 1, k_2j_1 = 0$, and $k_1j_2 = 0$.

Note that these are formal expressions and when interpreted in $\mathcal{C}(U,U)$, for some \mathcal{C} and U, 0 and 1 are interpreted as 0_{UU} (the zero morphism in $\mathcal{C}(U,U)$) and 1_U (the identity morphism on U), respectively. Also j_1, j_2, k_1 , and k_2 are interpreted by their namesakes (as morphisms in $\mathcal{C}(U,U)$). It should be noted that given a polynomial $\psi \in \mathcal{E}$, its interpretation in $\mathcal{C}(U,U)$ may not exist, that is the summands in the polynomial ψ may not form a summable family in the Σ -monoid $\mathcal{C}(U,U)$ (see [20] for the definition of a Σ -monoid.)

We next define an operation, ()* on \mathcal{E} , as follows: $0^* = 0$, $1^* = 1$, $j_1^* = k_1$, $j_2^* = k_2$, $k_1^* = j_1$ and $k_2^* = j_2$ and we extend ()* to words by induction: $(w\alpha)^* = \alpha^* w^*$, $(w+v)^* = w^* + v^*$ for $w, v \in \mathcal{E}$ and $\alpha \in \mathcal{A}$. In a word w = uv we say that v occurs before u, or equivalently that u occurs after v. Note that words w on \mathcal{A} cannot have k's occurring after j's because of equations $k_1j_1 = k_2j_2 = 1$ and $k_2j_1 = k_1j_2 = 0$. Thus words w on \mathcal{A} are of the form w = uv where v is a word on \mathcal{A} consisting of k_1, k_2 only and u a word on \mathcal{A} consisting of j_1, j_2 only (either u or v can be 1). We call v the k-part and u, the j-part of w. For example, the k part of $j_1j_2k_2k_1^2$ is $k_2k_1^2$ and its j-part is j_1j_2 .

Given a polynomial $\psi \in \mathcal{E}$ we define a k-tree which gives a tree representation of the k-parts of summands in ψ , as follows: given a summand w in ψ , we associate a path (from the root to a leaf) in the k-tree to w, such that the path corresponds to the k-part of w, when read from right to left. Similarly we define a j-tree, except that each path in the j-tree corresponds to the respective j-part, when read from left to right. Trees are grown upwards, at every branching point in a j-tree, the left branch is labelled j_1 and the right branch j_2 , similarly in a k-tree, the left branch is labelled k_1 and the right branch k_2 . For this representation to be well-defined one requires that the k-parts be mutually incomparable with respect to the prefix ordering relation, a similar requirement is demanded for the j-parts.

Here is an example : consider the polynomial $\psi = j_1^3 k_2 + j_2 k_1^3 + j_1 j_2 k_2 k_1^2 + j_1^2 j_2 k_2 k_1$, the j and k trees are shown below.

Fig. 1. j and k-trees

Note that a k-tree will have the same number, n, of leaves as the number of summands in ψ with nonempty k-parts. A similar argument holds for a j-tree.

Note that by construction every path from the root of the k-tree to the root of the j-tree is a term built out of j_1, j_2, k_1, k_2 . Not all such terms will be summands in a given ψ , however every summand in ψ can be obtained in this way.

Theorem 6.5 Let C be a traced UDC, U a reflexive object in C and $U \otimes U \triangleleft U$ (j, k). Consider a polynomial $\psi \in E$. Then, ψ is the denotation of an MLL proof iff

• ψ exists when interpreted in C(U, U),

- ψ has an even number n > 0 of summands,
- For each summand w, $w^2 = 0$ and w^* is a summand in ψ ,
- The k-tree of ψ is a binary tree with n leaves.

The proof of Theorem 6.5 below uses the Characterization Theorem 6.2 and the following lemma:

Lemma 6.6 Let Γ be a provable **MLL** sequent of length (counting the variable occurrences) n and Π be a proof of $\vdash \Gamma$. Then $\llbracket \Pi \rrbracket_G = J\theta(\Pi)K$, where $\llbracket \Pi \rrbracket_G$ is the GoI interpretation of Π and $\theta(\Pi)$ is the MGoI interpretations of Π restricted to the single reflexive object U. Here $J:U^n \to U$ is a morphism built from j and 1_U by tensoring and composition whose tree representation is a binary tree with n leaves, and $K = J^*$. Here ()* is as defined above and $U \otimes U \triangleleft U(j,k)$.

Proof. By induction on proofs. We refer the reader to [20] for the untyped GoI interpretation of proofs. The difference is that in that work, as in [13], we used matrices to interpret proofs. Here, instead we view those matrices as morphisms from $U \to U$, using appropriate morphisms built from j and k that we denote by \hat{J} and \hat{K} respectively, below. We give two cases; the remaining cases will appear in the full journal version.

- (i) Suppose Π is an axiom (we restrict to propositional variables), then $[\![\Pi]\!]_G = \hat{J}s_{UU}\hat{K} = js_{UU}k = j\theta(\Pi)k$.
- (ii) Suppose Π is obtained by an application of the cut rule to subproofs Π' and Π'' .

$$\begin{split} & [\![\Pi]\!]_G = \hat{J}(\tau^{-1}([\![\Pi']\!]_G \otimes [\![\Pi'']\!]_G)\tau)\hat{K} \text{ by definition of GoI semantics} \\ & = \hat{J}(\tau^{-1}(J'\theta(\Pi')K' \otimes J''\theta(\Pi'')K'')\tau)\hat{K} \text{ by ind. hypothesis} \\ & = \hat{J}(\tau^{-1}(J' \otimes J'')(\theta(\Pi') \otimes \theta(\Pi''))(K' \otimes K'')\tau)\hat{K} \\ & = \hat{J}(\tilde{J}(\tau^{-1}(\theta(\Pi') \otimes \theta(\Pi''))\tau)\tilde{K})\hat{K} \\ & = \hat{J}(\tilde{J}(\theta(\Pi))\tilde{K})\hat{K} \\ & = J\theta(\Pi)K \end{split}$$

where \tilde{J} and \tilde{K} are appropriate morphisms $U^n \to U$ built from j's (resp. k's) and 1_U by tensoring and composition.

Proof. (of Theorem 6.5) Recall that as we are working in a traced UDC, the MGoI interpretations of proofs restricted to a single object U can be represented by matrices of their components. As such they are symmetric permutation matrices with zero diagonal entries, by Proposition 6.1.

Suppose ψ is the denotation of an MLL proof Π of $\vdash \Gamma$, the existence of ψ as a morphism in $\mathcal{C}(U,U)$, for any traced UDC \mathcal{C} and reflexive object U in \mathcal{C} is one of the main results in [20], namely Theorem 20, page 21. Let M denote $\theta(\Pi)$ where $\theta(\Pi)$ is as defined in Lemma 6.6. Note that $\psi = JMK$. Recall that M is $n \times n$ permutation matrix with n even, and all n entries of J (as a $1 \times n$ matrix) are nonzero; thus there will be n summands in ψ . The k-tree of ψ is just the tree representation of

the morphism K which by Lemma 6.6 is a binary tree with n leaves.

Hereafter we shall use J and K to refer to their tree representations.

Every summand in ψ can be obtained by following a path u in K from root to a leaf and continuing on with a path, (specified by M) in J from a leaf to the root of J.

Let w be a summand in ψ , then so will be w^* , because $K = J^*$ and M is symmetric. Finally, we show that any path w in ψ , has the property that $w^2 = 0$. Consider a path u in K; u cannot be connected to u^* in J, because that connection, leading to a summand $w = u^*u$ will imply a nonzero diagonal entry for M. On the other hand, u starts either with k_1 or k_2 ; consider the first case, the second case is similar. In this case, we have $u = u'k_1$, any summand obtained from u by following it with a path v in J that ends with a j_2 will produce a w with $w^2 = 0$, as $k_1j_2 = 0$. Hence, suppose that $w = vu = j_1v'u'k_1$, with v' in J. There are two cases: (1) $|u| \leq |v|$, (2) |u| > |v|. Here, |u| denoted the length of u. We discuss (1), (2) is similar. Suppose |u| = |v|, and $w^2 \neq 0$, then $v = u^*$, but this case is not possible, as discussed above. Assume, |u| < |v|, and $w^2 \neq 0$, then $v = u^*v''$ for some path v'' in J. But, by definition of J and K, we will then have a path $v^* = v''^*u$ in K. This is impossible, as u is a path in K.

Conversely, suppose $\psi \in \mathcal{E}$ satisfies the properties stated in the theorem. We will show that $\psi = JMK$, with M a symmetric permutation matrix with zero diagonal entries and $K = J^*$. Then by Theorem 6.2 and Lemma 6.6, we conclude that it is the denotation of a proof in MLL.

Note that the j and k-trees of ψ will be exactly the same (save for labelling), because for every summand w in ψ , w^* is in ψ . We enumerate the leaves of each tree from 1 to n from left to right.

Recall that every summand in ψ can be obtained by following a path from the root of the k-tree to the root of the j-tree. Every such path has to pass from a leaf of the k-tree to a leaf of the j-tree and continue to the root of the j-tree. We prove that for the paths in ψ , the leaf-to-leaf connections form a fixed-point free involutive permutation on $\{1, \dots, n\}$ whose matrix we denote by M. The leaf number i in the k-tree cannot be connected to leaf number i in the j-tree, otherwise we get a path $w = u^*u$ and $w^2 = u^*u$ a contradiction to $w^2 = 0$. The leaf number i cannot be connected to more than one leaf in the *j*-tree, since all summands in ψ have distinct k parts. Similarly, two leaves i, i' in the k-tree cannot connect to the same node in the j-tree because terms in ψ have distinct j-parts (as they have distinct k-parts and w in ψ implies w^* in ψ .) Moreover, every leaf in the j-tree has to connect to some leaf in the k-tree, by definition of the i and k-trees. Therefore we have a fixed-point free permutation. Finally, suppose leaf number i in the k-tree connects to leaf number i' in the j-tree and that this corresponds to the summand w in ψ , as w^* is also in ψ and by definition of the k and j-trees, we must connect the i' labelled leaf of the k-tree to i labelled leaf of the j-tree. Thus we get an involution. We define $J:U^n\to U$ by letting the 1lth entry be the path on the j tree from the leaf labelled l to the root, writing it from right to left as a morphism, for all $l = 1 \cdots, n$. Let $K = J^* : U \to U^n$, then $\psi = JMK$. Now, $\psi = JMK = J\theta(\Pi)K = [\![\Pi]\!]_G$, the last equality follows from Lemma 6.6, and the one before last follows from Theorem 6.2.

Example 6.7 For example, let $\psi = j_1^3 k_2 + j_2 k_1^3 + j_1 j_2 k_2 k_1^2 + j_1^2 j_2 k_2 k_1$, then

$$M = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}.$$

Moreover, following the construction in the proof above, $J:U^4\to U=[j_1^3,j_1^2j_2,j_1j_2,j_2]=j(j\otimes 1)(j\otimes 1\otimes 1)$ and $K=J^*=(k\otimes 1\otimes 1)(k\otimes 1)k$.

The permutation above is $\mu = (1,4)(2,3)$ on $\{1,2,3,4\}$ and using Theorem 6.2, and the discussion in Example 6.3, we see that ψ is the denotation of the proof (ignoring exchange): ⁷

$$\frac{ \begin{matrix} \vdash A_1, A_1^{\perp} & \vdash A_2, A_2^{\perp} \\ \vdash A_1 \otimes A_2, A_1^{\perp}, A_2^{\perp} \end{matrix}}{ \vdash (A_1 \otimes A_2) \ \Re \ A_2^{\perp}, A_1^{\perp}} \\ \begin{matrix} \vdash ((A_1 \otimes A_2) \ \Re \ A_2^{\perp}) \ \Re \ A_1^{\perp} \end{matrix}}$$

Here are some more examples:

Example 6.8 Let $\psi = j_2 j_1 k_1^4 + j_2^2 k_2 k_1^3 + j_1 j_2 k_2 k_1^2 + j_1^2 j_2 k_2 k_1 + j_1^4 k_1 k_2 + j_1^3 j_2 k_2^2$. Then we have $\mu = (1,5)(2,6)(3,4)$, $J = j(j\otimes 1)(j\otimes 1\otimes 1)(j\otimes 1\otimes 1)$ and $K = J^*$. Then by Theorem 6.2, we get that $\psi(A_1,A_2,A_3,A_4,A_5,A_6) = \psi(A_1,A_2,A_3,A_3^{\perp},A_1^{\perp},A_2^{\perp}) = (((A_1 \otimes A_2) \otimes A_3) \ \Re \ A_3^{\perp}) \ \Re \ A_2^{\perp} \ \text{and} \ \Pi \ \text{(ignoring exchange rule) is:}$

$$\frac{ \begin{array}{c|c} \vdash A_{1}, A_{1}^{\perp} & \vdash A_{2}, A_{2}^{\perp} \\ \hline \vdash A_{1} \otimes A_{2}, A_{1}^{\perp}, A_{2}^{\perp} & \vdash A_{3}, A_{3}^{\perp} \\ \hline \vdash (A_{1} \otimes A_{2}) \otimes A_{3}, A_{1}^{\perp}, A_{2}^{\perp}, A_{3}^{\perp} \\ \hline \vdash ((A_{1} \otimes A_{2}) \otimes A_{3}) \ \ \ & A_{3}^{\perp}, A_{1}^{\perp}, A_{2}^{\perp} \\ \hline \vdash (((A_{1} \otimes A_{2}) \otimes A_{3}) \ \ \ & A_{3}^{\perp}) \ \ \ & A_{1}^{\perp}, A_{2}^{\perp} \\ \hline \vdash ((((A_{1} \otimes A_{2}) \otimes A_{3}) \ \ \ & A_{3}^{\perp}) \ \ \ & A_{1}^{\perp}) \ \ \ & A_{2}^{\perp} \end{array}$$

Example 6.9 Let $\psi = j_1 j_2 k_2^2 + j_1^2 k_1 k_2 + j_2^2 k_2 k_1 + j_2 j_1 k_1^2$. Then we have $\mu = (1,3)(2,4), \ J = j(j \otimes j)$ and $K = J^*$. Then by Theorem 6.2, we get that $\psi(A_1,A_2,A_3,A_4) = \psi(A_1,A_2,A_1^{\perp},A_2^{\perp}) = ((A_1 \otimes A_2) \ \Re \ A_1^{\perp}) \ \Re \ A_2^{\perp}$ and Π (ignoring exchange rule) is:

$$\frac{ \begin{matrix} \vdash A_1, A_1^{\perp} & \vdash A_2, A_2^{\perp} \\ \vdash A_1 \otimes A_2, A_1^{\perp}, A_2^{\perp} \end{matrix}}{ \vdash (A_1 \otimes A_2) \ \ \Re \ \ A_1^{\perp}, A_2^{\perp}} \\ \vdash ((A_1 \otimes A_2) \ \ \Re \ \ A_1^{\perp}) \ \ \Re \ \ A_2^{\perp} \end{matrix}}$$

Example 6.10 Let $\psi = j_2 j_1 k_1^3 + j_1 j_2 j_1 k_2^2 + j_1^2 j_2 k_2^2 k_1 + j_1 j_2^2 k_2 k_1^2 + j_2^2 k_1 k_2 k_1 + j_1^3 k_1 k_2$. Incidentally this is the definition of combinator B in the linear combinatory algebra $\mathcal{C}(U,U)$ where \mathcal{C} is a traced UDC. See [3] for the development of such algebras.

⁷ In all our examples we choose to arrange the axioms in increasing index order of the A_i .

7 Conclusion and Future Work

In this work we recalled a new semantical interpretation called Multiobject Geometry of Interaction (MGoI), from [22]. This semantics, while inspired by GoI, differs from it in significant points: (i) it is defined on endomorphism monoids of objects (and there is no reflexive object U); (ii) the execution formula is based on a new theory of partial traces and trace classes. Moreover, there is an orthogonality relation linked to the notion of trace class, which allows us to develop Girard's theory of types, data and algorithms in our setting. This permits a structured approach to Girard's concept of solving feedback equations [15], and an axiomatization of the critical features needed for showing that the execution formula is an invariant of cut-elimination. Computationally, GoI provides a kind of algorithm for normalization based on the execution formula. In future work, we hope to explore the algorithmic and convergence properties of the execution formula in various models, independently of the syntax.

An obvious direction for future research is to extend our MGoI interpretation to the exponentials and additives of linear logic. First steps in this program, at the level of exponentials, are in [23]. As mentioned above, we are also examining the intrinsic *-autonomous category of types and terms from our [21] in this new multiobject setting as perhaps a better "target" for a denotational semantics.

It is natural to seek examples of traces that are induced by more general notions of orthogonalities, especially those arising in functional analysis. We hope this may lead to new classes of MGoI models, perhaps connected to von Neumann algebras and general solutions to feedback equations, as in [15,16].

References

- [1] Abramsky, S. (1996), Retracing Some Paths in Process Algebra. In CONCUR 96, $Springer\ LNCS$ 1119, 1-17.
- [2] Abramsky, S., Blute, R. and Panangaden, P. (1999), Nuclear and trace ideals in tensored *-categories, J. Pure and Applied Algebra vol. 143, 3–47.
- [3] Abramsky, S., Haghverdi, E. and Scott, P.J. (2002), Geometry of Interaction and Linear Combinatory Algebras. MSCS, vol. 12(5), 2002, 625-665, CUP.
- [4] Abramsky, S. and Jagadeesan, R. (1994), New Foundations for the Geometry of Interaction. Information and Computation 111 (1), 53-119.

Haghverdi, Scott

- [5] Blute, R., Cockett, R., and Seely RAG. (2000), Feedback for linearly distributive categories: traces and fixpoints Bill(Lawvere)Fest, *Journal of Pure and Applied Algebra*, vol. 154, pp 27-69.
- [6] Danos, V. (1990), La logique linéaire appliquée à l'étude de divers processus de normalisation et principalement du λ -calcul. PhD thesis, Université Paris VII.
- [7] Danos, V. and Regnier, L. (1995), Proof-nets and the Hilbert Space. In: Advances in Linear Logic, London Math. Soc. Notes, 222, CUP, 307–328.
- [8] C. Fuhrman and D. Pym, On the Geometry of Interaction for Classical Logic (Extended Abstract). Proc. LICS 04, IEEE Computer Society Press, 2004, pp. 211-220.
- [9] Girard, J.-Y. (1987), Linear Logic. Theoretical Computer Science 50 (1), pp. 1-102.
- [10] J.-Y. Girard, Y. Lafont, P.Taylor. Proofs and Types, Cambridge Tracts in Theoretical Computer Science 7, 1989.
- [11] Girard, J.-Y. (1988), Geometry of Interaction II: Deadlock-free Algorithms. In Proc. of COLOG'88, LNCS 417, Springer, 76–93.
- [12] Girard, J.-Y., Multiplicatives, in Lolli, ed. Logic and computer science, new trends and applications, in Rend. del seminario matematica dell'universita de Torino, special issue, 1988, 11–34.
- [13] Girard, J.-Y. (1989a) Geometry of Interaction I: Interpretation of System F. In Proc. Logic Colloquium 88, North Holland, 221–260.
- [14] Girard, J.-Y. (1995), Geometry of Interaction III: Accommodating the Additives. In: Advances in Linear Logic, LNS 222, CUP, 329–389,
- [15] Girard, J.-Y. (2007). Le Point Aveugle I, II, Hermann Éditeurs, Paris, 567 + pp.
- [16] Girard, J.-Y. (2008). Geometry of Interaction V: logic in the hyperfinite factor. Manuscript.
- [17] Gonthier, G., Abadi, M. and Lévy, J.-J. (1992), The geometry of optimal lambda reduction. In Proceedings of Logic in Computer Science, vol. 9 pp. 15-26.
- [18] Haghverdi, E. A Categorical Approach to Linear Logic, Geometry of Proofs and Full Completeness, PhD Thesis, University of Ottawa, Canada 2000.
- [19] Haghverdi, E. Unique Decomposition Categories, Geometry of Interaction and combinatory logic, Math. Struct. in Comp. Science, vol. 10, 2000, 205-231.
- [20] Haghverdi, E. and P.J.Scott. A categorical model for the Geometry of Interaction, Theoretical Computer Science Volume 350, Issues 2-3, Feb 2006, pp. 252-274. (Preliminary Version in: in Automata, Languages, Programming(ICALP 2004), Springer LNCS 3142, pp. 708-720).
- [21] Haghverdi, E. and P.J.Scott. From Geometry of Interaction to Denotational Semantics. Proceedings of CTCS2004. In ENTCS, vol. 122, pp. 67-87. Elsevier.
- [22] Haghverdi, E. and P.J.Scott. Towards a Typed Geometry of Interaction, CSL2005 (Computer Science Logic), Luke Ong, Ed. SLNCS 3634, pp. 216-231.
- [23] Haghverdi, E. Typed GoI for Exponentials. in: M. Bugliesi et al. (Eds.): Proc. of ICALP 2006, Part II, LNCS 4052, pp. 384-395, 2006. Springer Verlag.
- [24] Hyland, M and Schalk, A. (2003), Glueing and Orthogonality for Models of Linear Logic. Theoretical Computer Science vol. 294, pp. 183–231.
- [25] Joyal, A., Street, R. and Verity, D. (1996), Traced Monoidal Categories. Math. Proc. Camb. Phil. Soc. 119, 447-468.
- [26] Mac Lane, S. (1998), Categories for the Working Mathematician, 2nd Ed. Springer.
- [27] Malacaria, P. and Regnier. L. (1991), Some Results on the Interpretation of λ -calculus in Operator Algebras. *Proc. LICS* pp. 63-72, IEEE Press.
- [28] Plotkin, G. Trace Ideals, MFPS 2003 invited lecture, Montreal.
- [29] Regnier, L. (1992), Lambda-calcul et Réseaux, PhD Thesis, Université Paris VII.