

## ELG3125 Signal and System Analysis Lab

- **Lab8: Bode Plots**

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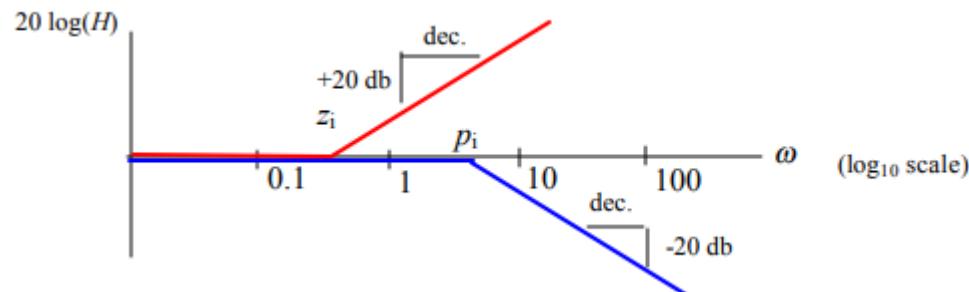
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## Effect of Individual Zeros and Poles Not at the Origin

The values  $z_i$  and  $p_i$  are called a critical frequency (or break frequency). They represent a ramp function of 20 db per decade. Zeros give a positive slope. Poles produce a negative slope.



$$H = \frac{1 + \frac{j\omega}{z_i}}{1 + \frac{j\omega}{p_i}}$$

# Plotting Bode Diagram with Matlab

The command `bode` computes magnitudes and phase angle of the frequency response of continuous-time, linear, time-invariant systems.

<code>bode(sys)</code>	Creates a Bode plot of the frequency response of a dynamic system model.
<code>bode(sys,w)</code>	Plots system response at frequencies determine by $w$
<code>[mag,phase,w]=bode(sys)</code>	Returns magnitudes, phase values, and frequency value $w$ corresponding to <code>bode(sys)</code>

The matrices `mag` and `phase` contain, respectively magnitudes and phase angles of the frequency response of the system, evaluated at user-specified frequency point.

The Phase angle is returned in degrees, the magnitude can be converted to decibels with the statement

$$\text{mag\_dB} = 20 * \log10(\text{mag})$$

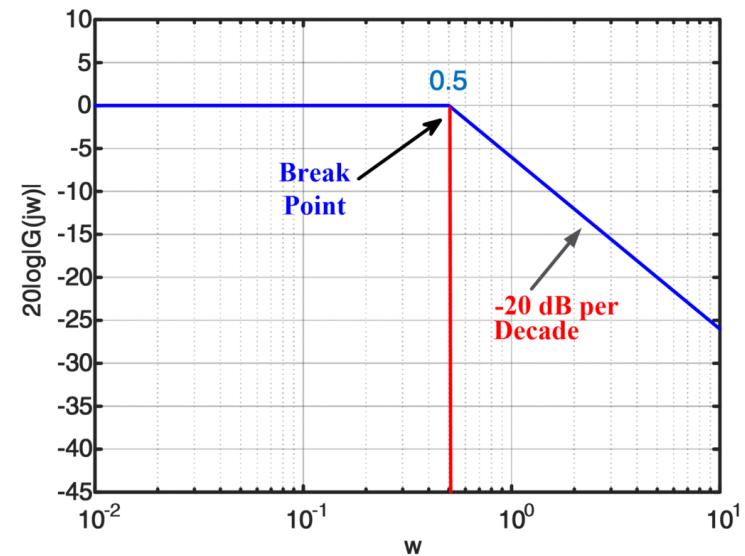
# Example

$$H(j\omega) = \frac{1}{2j\omega + 1} = \frac{1}{\frac{j\omega}{0.5} + 1}$$

From above expression, we can deduce the corner frequency or break point as:  $\omega=1/2$

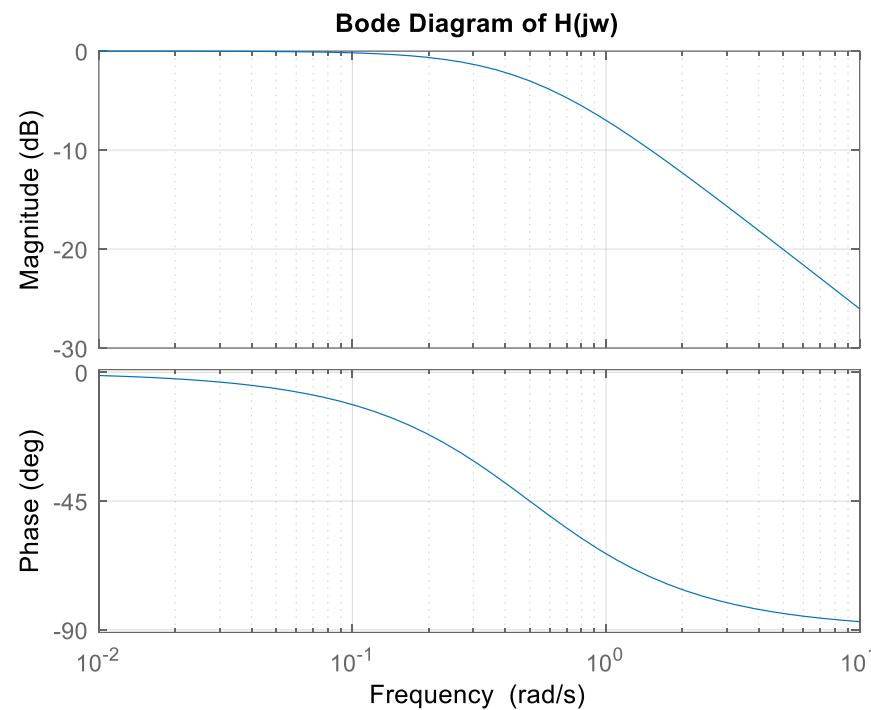
At  $\omega$  = (very very small value):

$$|G(j\omega)| \text{ dB} = 20 \log |G(j\omega)| = 20 \log(1) = 0$$



```
b = [0 1]; a = [1/0.5 1];  
bode(b, a); grid  
title('Bode Diagram of H(jw)')
```

$$H(j\omega) = \frac{1}{j\omega + 0.5}$$



# Theoretical Approximation

The frequency response is given below. What are the nature frequency and the damping factor? Obtain the Bode plot.

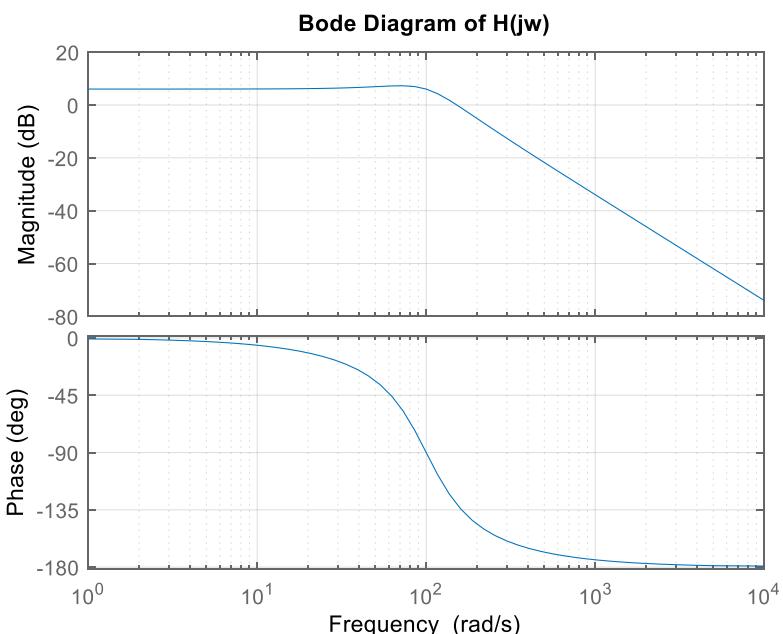
$$H(j\omega) = \frac{2 \times 10^4}{(j\omega)^2 + 100(j\omega) + 10^4}$$

(Standard form)  $H(j\omega) = \frac{\omega_n^2}{(j\omega)^2 + 2\xi\omega_n(j\omega) + \omega_n^2}$

**Solution:**

the nature frequency is  $\omega_n = 100$ , and the damping factor is

$$2\xi\omega_n = 100 \Rightarrow \xi = \frac{100}{2\omega_n} = \frac{100}{2 \times 100} = \frac{1}{2}, \text{ which } \angle 1, \text{ the system is underdamped}$$



To obtain its Bode plot, we change the expression

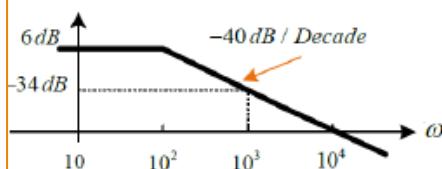
$$H(j\omega) = \frac{2 \times 10^4}{(j\omega)^2 + 100(j\omega) + 10^4} = \frac{2 \times 10^4}{10^4 \left[ \left( \frac{j\omega}{10^2} \right)^2 + \left( \frac{j\omega}{10^2} \right) + 1 \right]} = \frac{2 \times 1}{\left( \frac{j\omega}{10^2} \right)^2 + \left( \frac{j\omega}{10^2} \right) + 1}$$

Since  $20\log_{10} H(j\omega) = 20\log_{10} 2 + 20\log_{10} \frac{1}{\left( \frac{j\omega}{10} \right)^2 + \left( \frac{j\omega}{10} \right) + 1}$

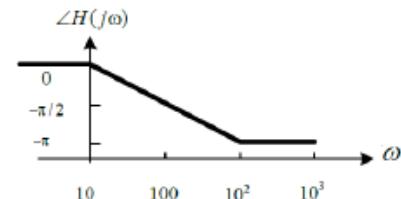
and  $20\log_{10} 2 = 6 \text{ dB}$ , the magnitude Bode plot would be the one of

$$20\log_{10} \frac{1}{\left( \frac{j\omega}{10} \right)^2 + \left( \frac{j\omega}{10} \right) + 1} \text{ shifted up by 6 dB, shown below}$$

$$20\log_{10}|H(j\omega)|$$



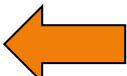
(a) magnitude Bode plot



(b) phase Bode plot

## MATLAB implementation

```
b = [0 0 2e4];
a = [1 100 1e4];
bode(b, a); grid
title('Bode Diagram of H(jw)')
```



# Exercise 1

Use MATLAB to draw the bode diagram for the following transfer function:

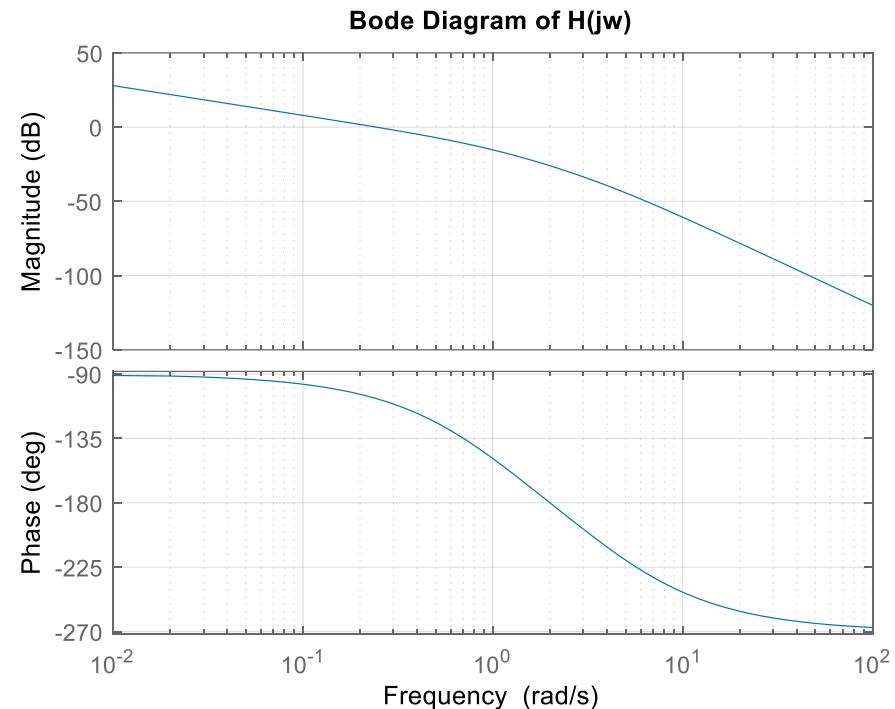
$$H(s) = \frac{s + 2}{s(s + 1)(s^2 + 6s + 8)}$$

Replace:  $s = j\omega$



# Solution

```
% H(s)=[ s+2 ]/[s(s+1) (s^2+6s+8) ]
%% Denominator
% s(s+1) (s^2+6s+8) = (s^2+s) (S^2+6s+8)
% (s^4 +7s^3 +14 s^2 +8s)
% a =[1 7 14 8 0]
% OR use distribution properties
a=conv([1 1 0],[1 6 8]);
%% Numerator
b=[1 2];
%% bode plot
bode(b, a); grid
title('Bode Diagram of H(jw) ')
```



Note: calculate it and compare your result with MATLAB simulation

# The END