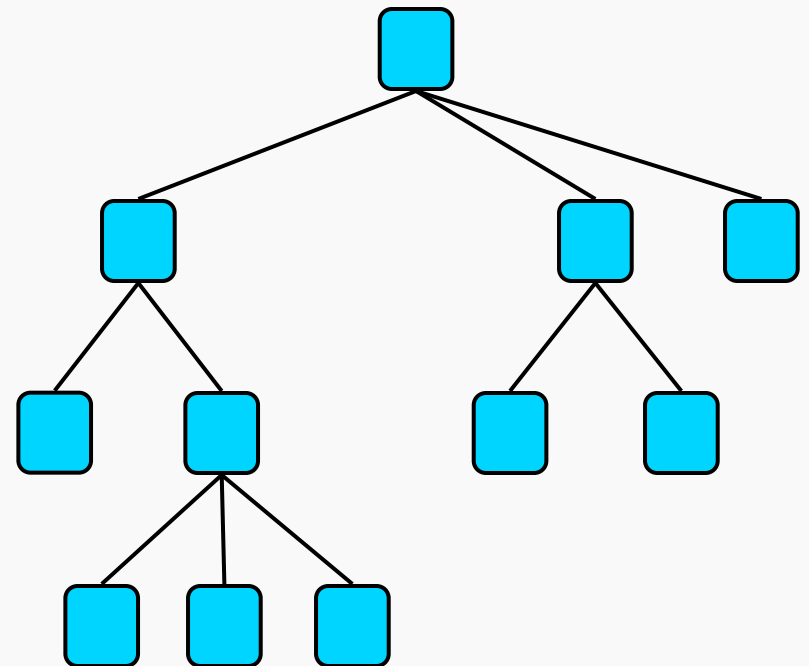


---

# Computations in Trees

---

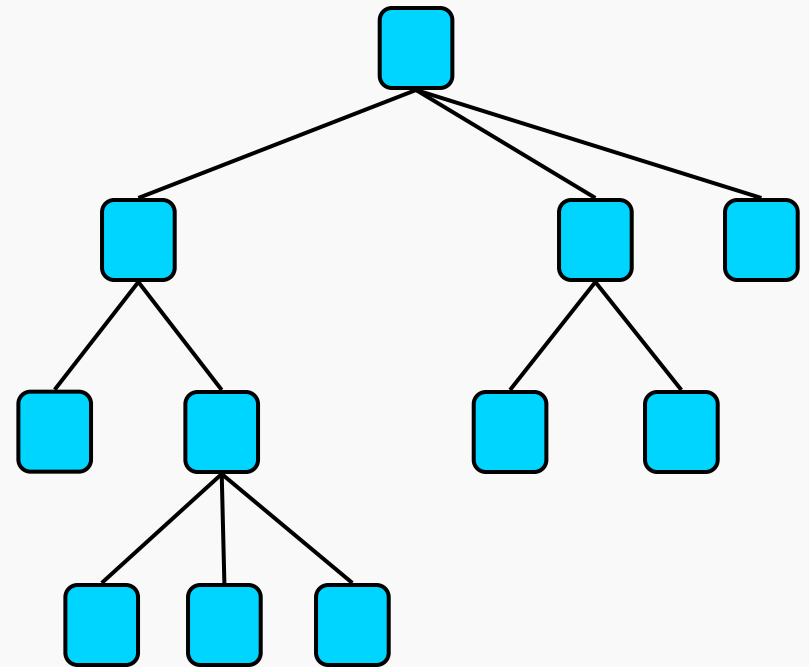
Saturation  
Minimum Finding  
Eccentricity  
Center  
Ranking



# Trees

---

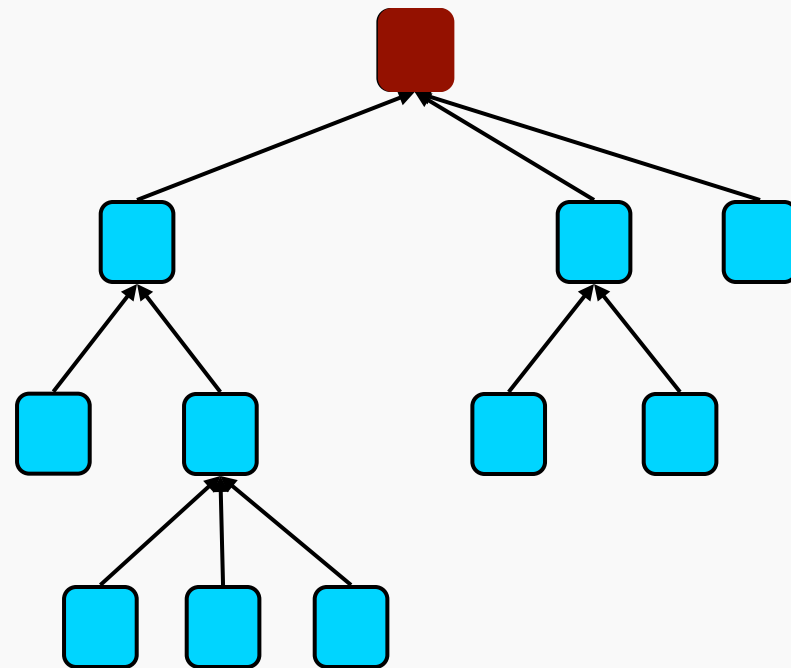
- Acyclic graph
- $n$  entities
- $n - 1$  links



# Rooted Trees

---

- Acyclic graph
- $n$  entities
- $n - 1$  links



Rooted

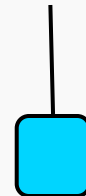
# Saturation Technique

---

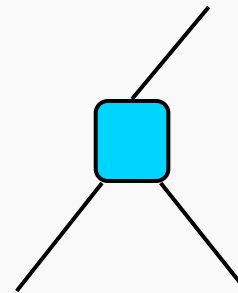
- Bidirectional links
- Ordered messages
- Full Reliability
- Knowledge of the topology

Note:

Each entity knows whether  
it is a leaf:



or an internal node:



# SATURATION: A Basic Technique

---

$S = \{\text{available, awake, processing}\}$

At the beginning, all entities are available

Arbitrary entities can start the computation (multiple initiators)

# SATURATION: A General Technique

---

- **Activation phase:**

started by the initiators: all nodes are activated

wake-up

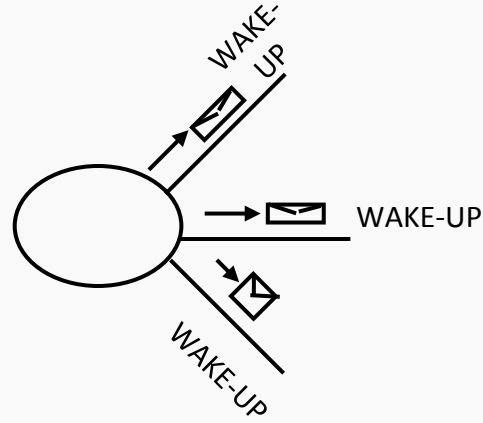
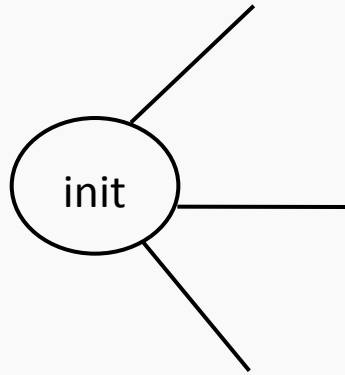
- **Saturation Phase:**

started by the leaves: a unique pair of neighbours is identified (saturated nodes)

- **Resolution Phase:**

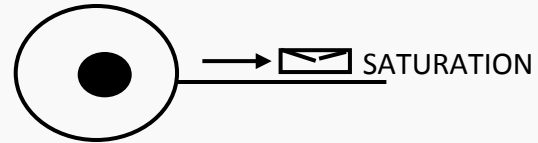
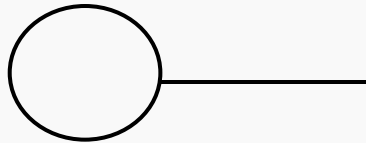
started by the saturated nodes

1)

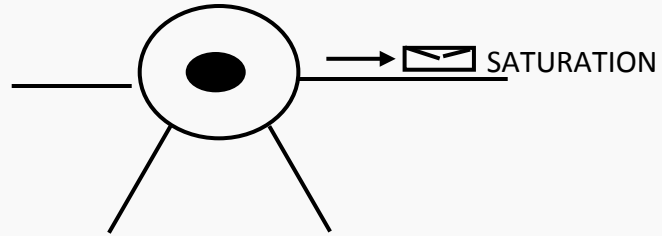
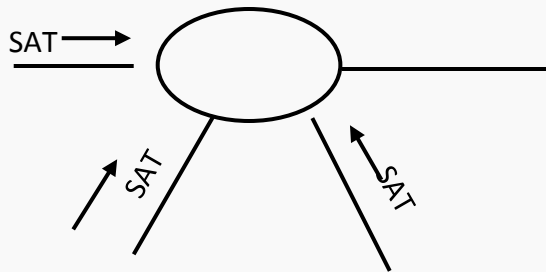


2)

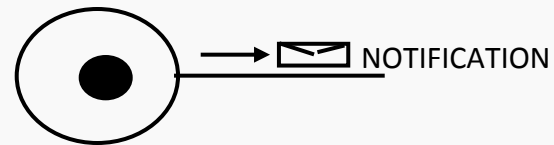
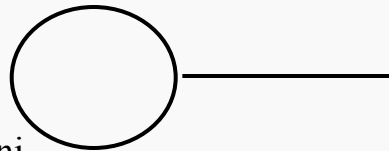
leaf



internal



3)



S = {AVAILABLE, ACTIVE, PROCESSING,  
SATURATED}

Sinit = AVAILABLE

**AVAILABLE**

**I haven't been activated yet**

*Spontaneously*

**send(Activate) to N(x);**

Neighbours := N(x)

if |Neighbours|=1 then

    M:="Saturation");

    parent ← Neighbours;

**send(M) to parent;**

**become PROCESSING;**

else

**become ACTIVE;**

/\* special case if  
I am a leaf \*/



*Receiving(Activate)*

**send(Activate) to N(x) – {sender};**

Neighbours := N(x);

if |Neighbours|=1 then

    M := ("Saturation");

    parent ← Neighbours;

**send(M) to parent;**

**become PROCESSING;**

else

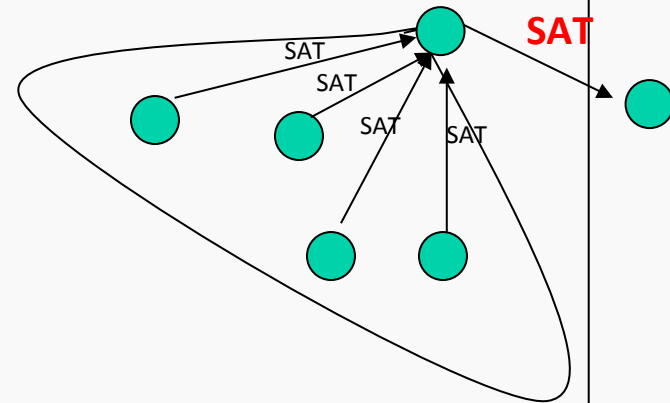
**become ACTIVE;**

I am awake but I haven't started sending Saturation messages yet

## ACTIVE

*Receiving(M)*

```
Neighbours := Neighbours - {sender};  
if |Neighbours| = 1 then  
  M := ("Saturation");  
  parent ← Neighbours;  
  send(M) to parent;  
  become PROCESSING;
```

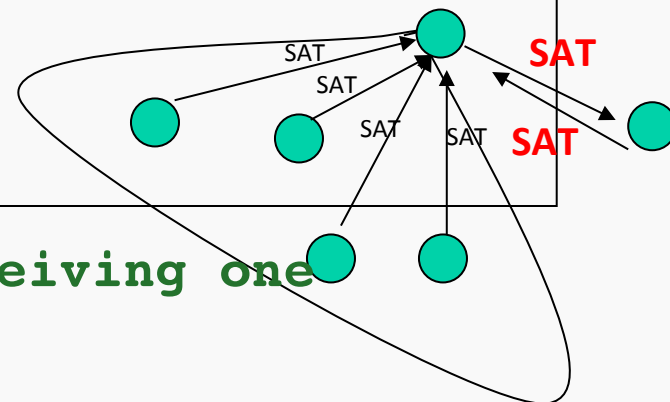


## PROCESSING

*receiving(M)*

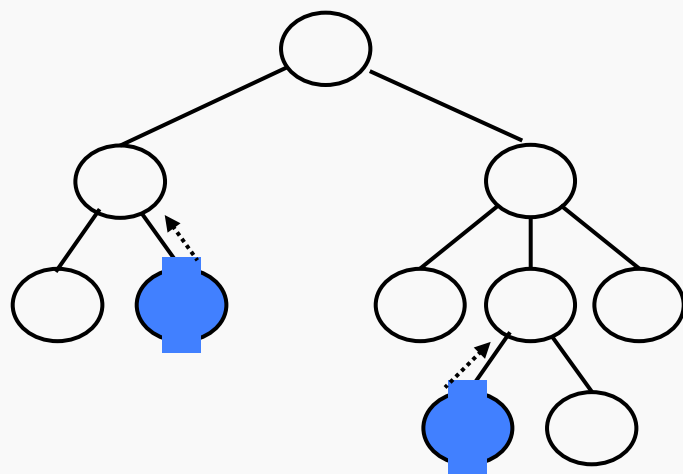
```
become SATURATED;
```

I have already sent my saturation message

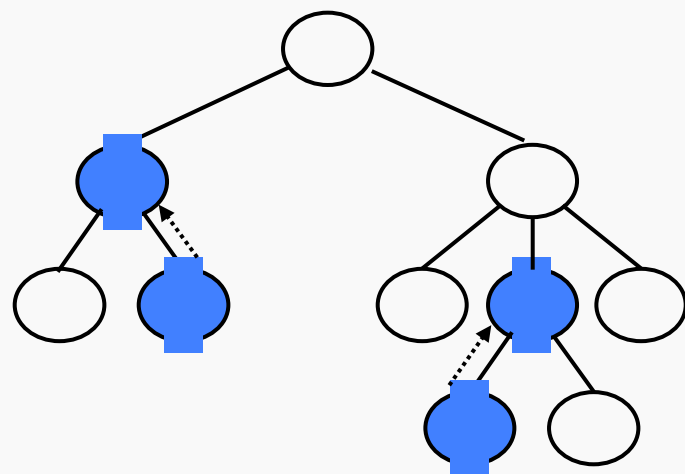


And now I am receiving one

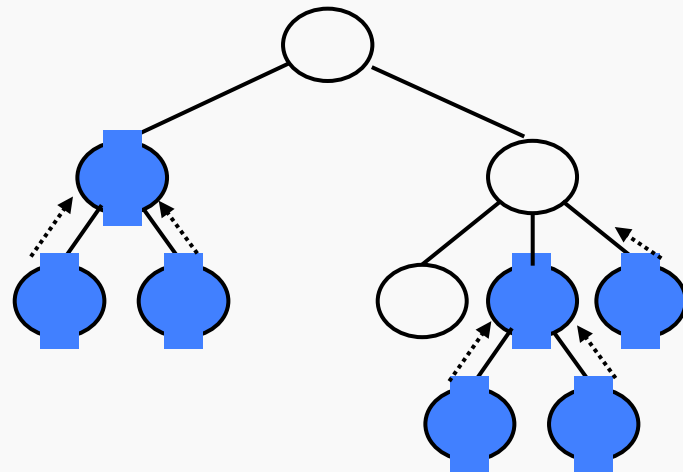
# Example of Saturation Phase (started by some leaves)



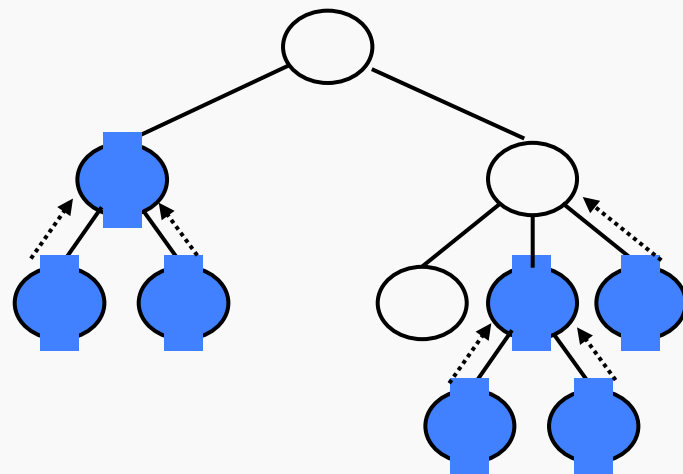
## Example of Saturation



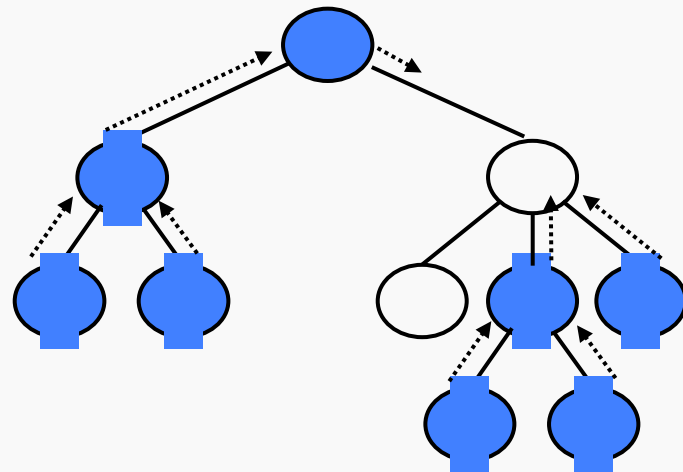
## Example of Saturation



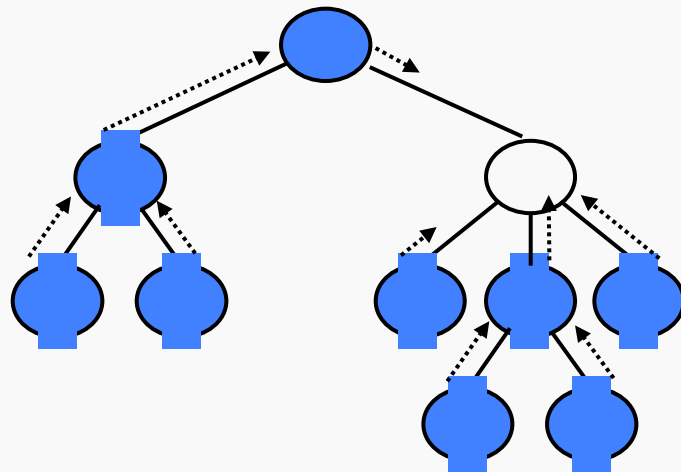
## Example of Saturation



## Example of Saturation

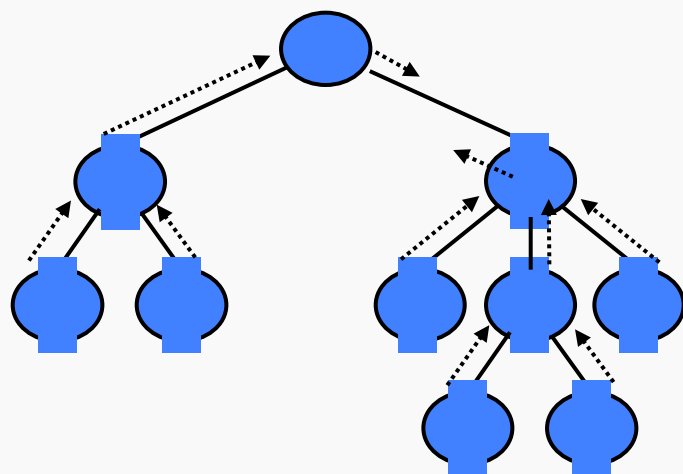


## Example of Saturation

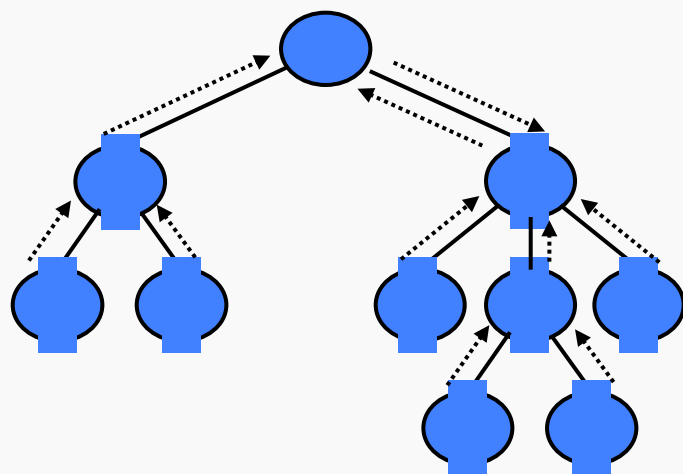




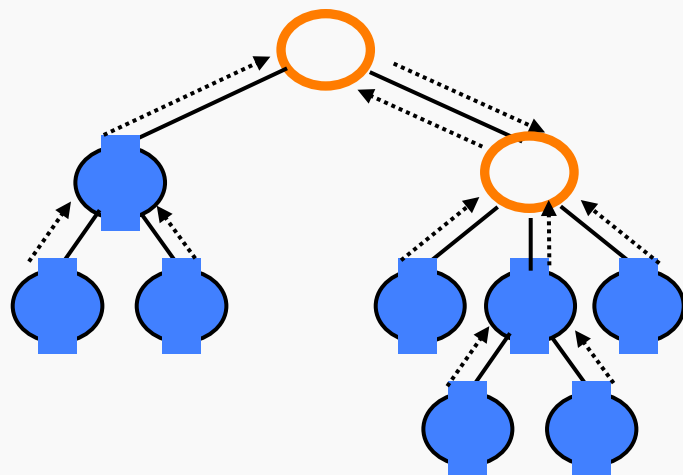
# Example of Saturation



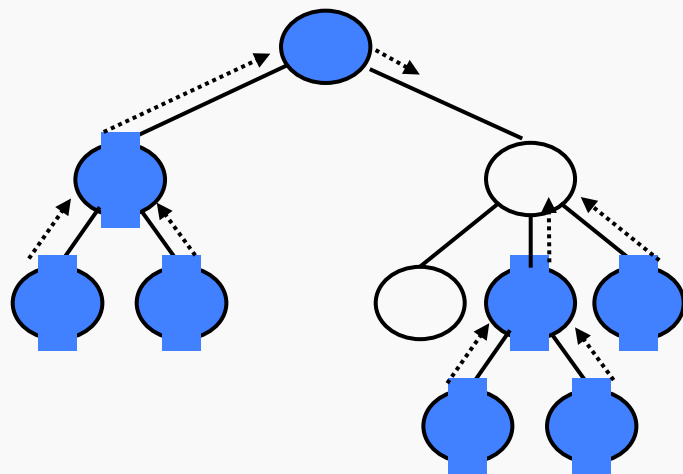
## Example of Saturation



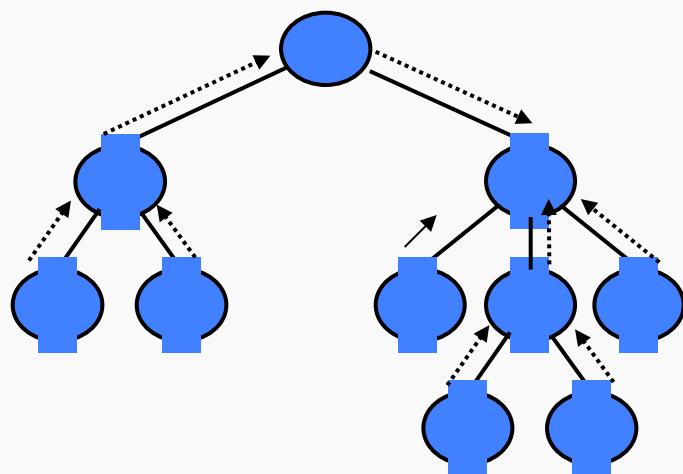
# Example of Saturation



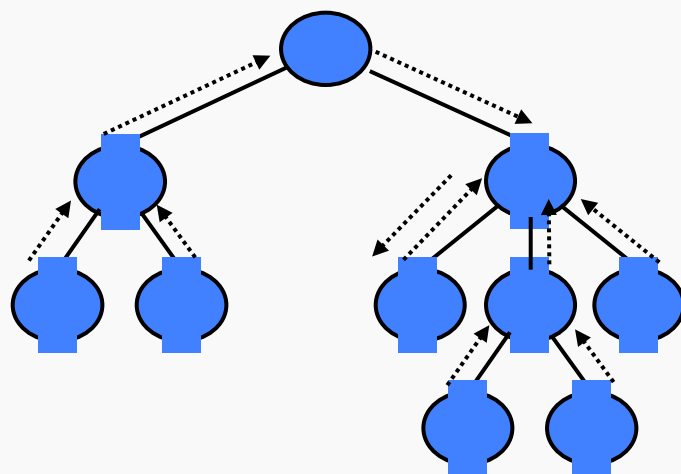
# Example of Saturation - different ending



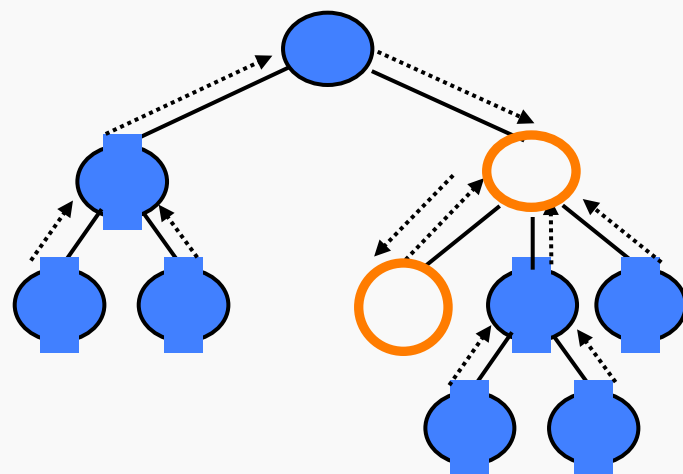
# Example of Saturation - different ending



# Example of Saturation - different ending

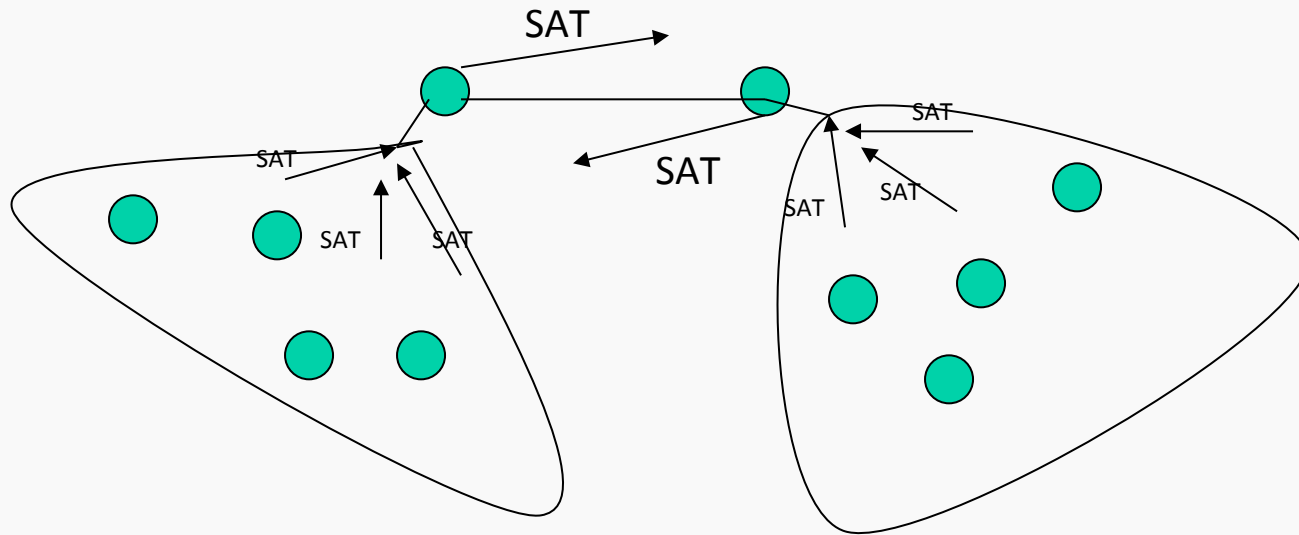


# Example of Saturation - different ending



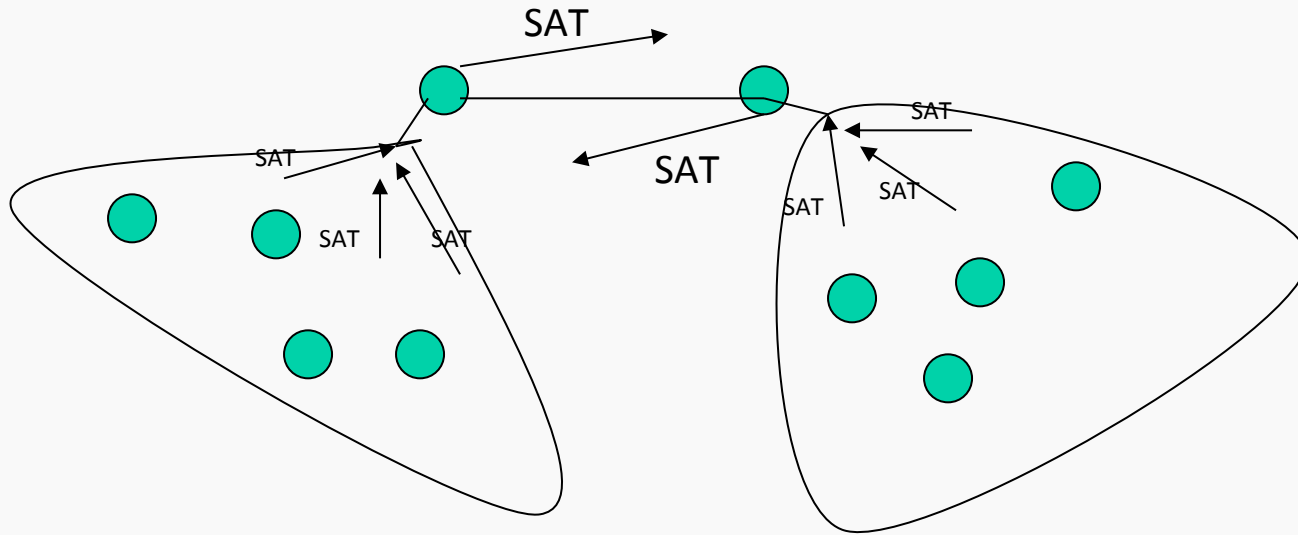
**Property:**

Exactly two processing nodes become saturated, and they are neighbours.





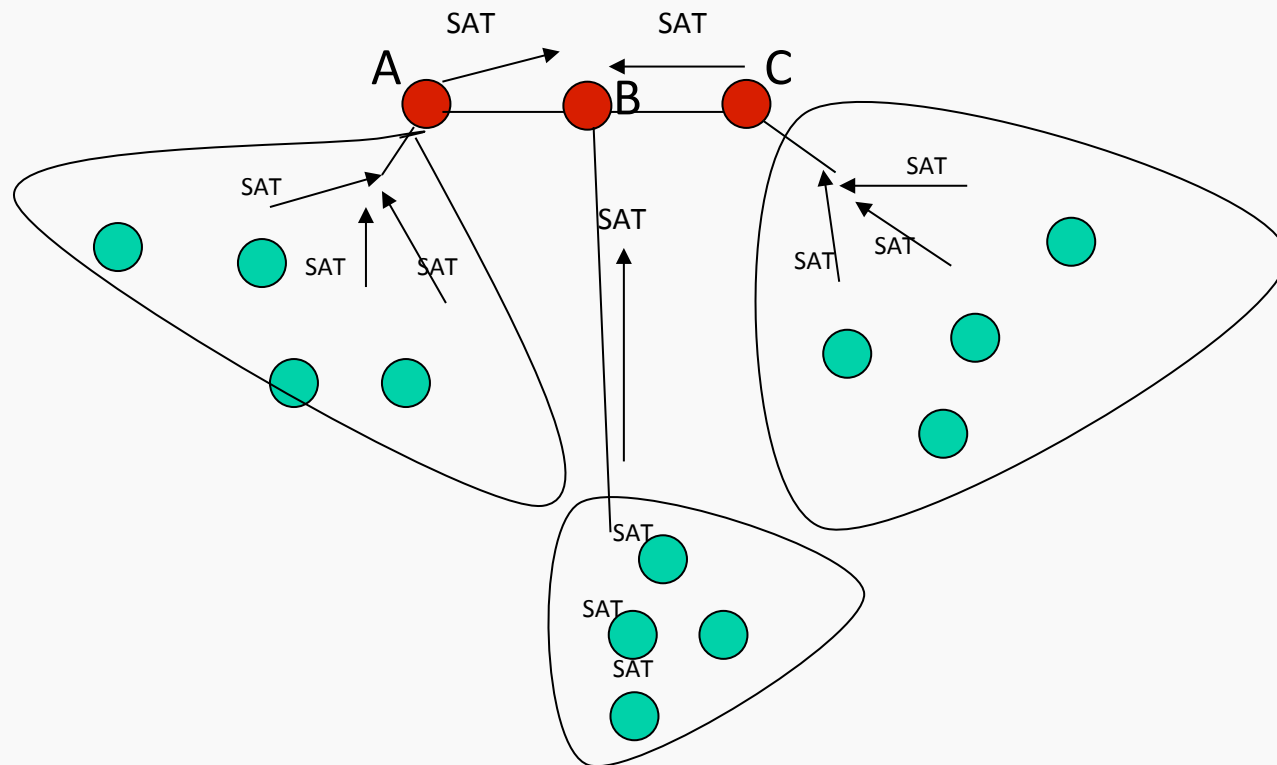
A node becomes PROCESSING only after sending saturation to its parent. Each node sends **only ONE Saturation** message.

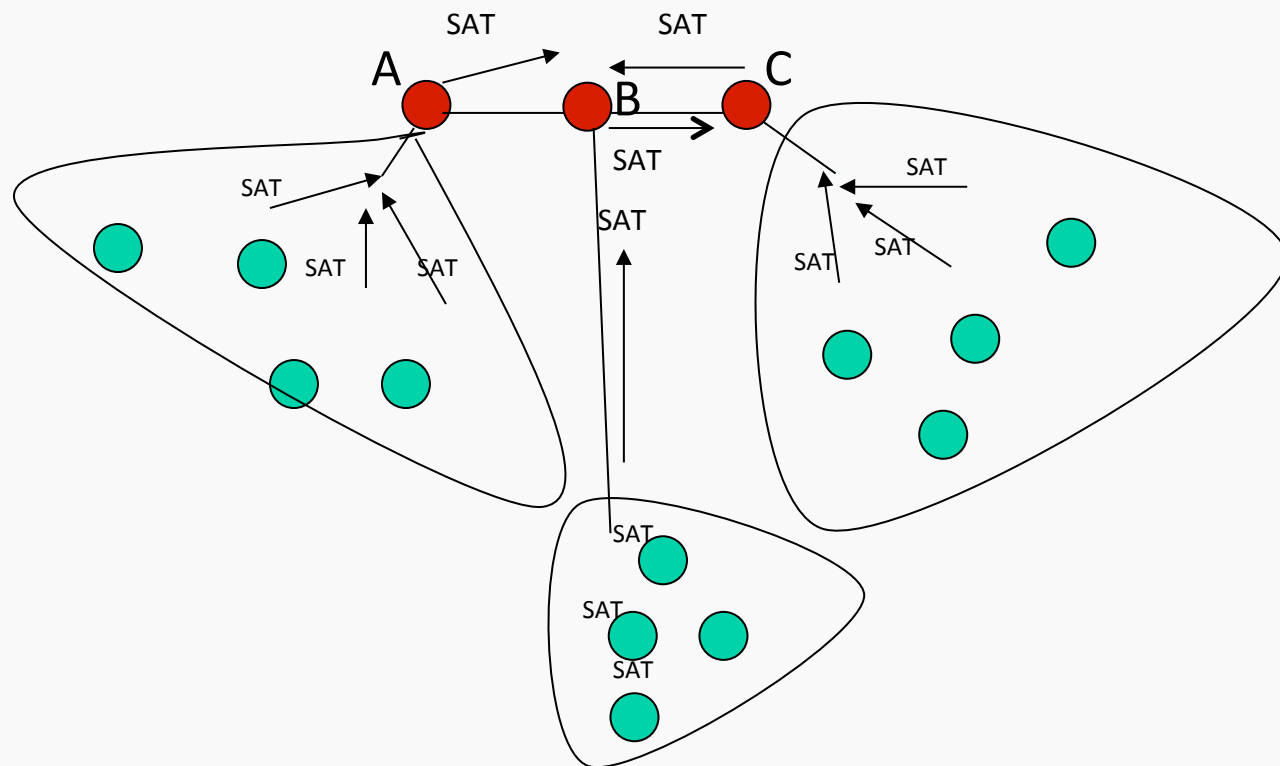


A node become SATURATED only after receiving a message in the state PROCESSING from its parent

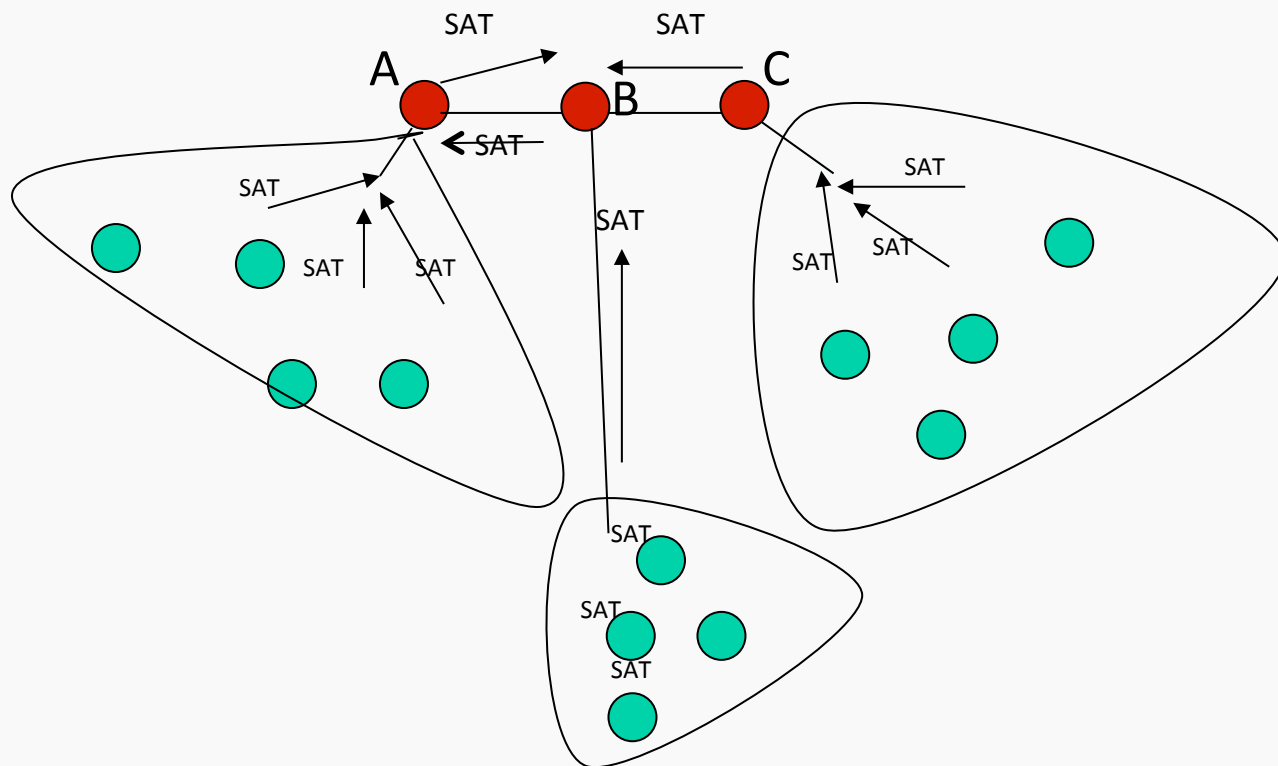
**TWO** neighbouring entities become saturated

By contradiction: say that three neighbouring entities become saturated:





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---

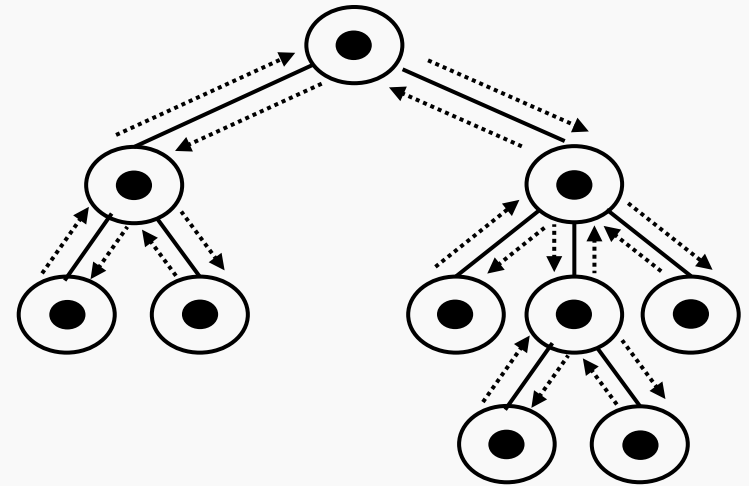
Which entities become saturated  
depends on the unpredictable delays

Observations and Examples

# Message Complexity

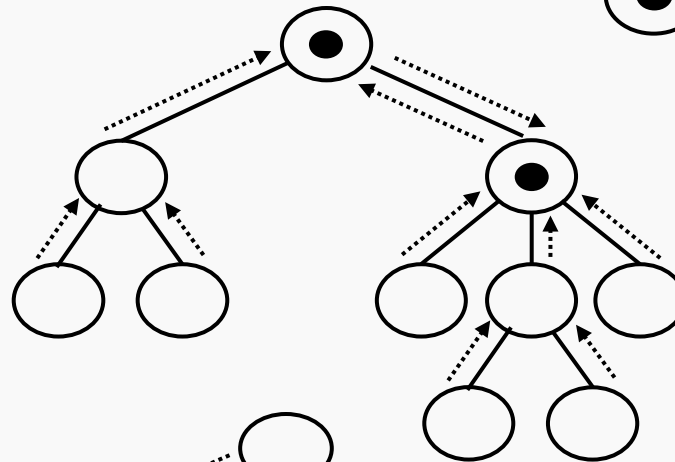
**Activation:** Worst case - n initiators

$$2(n-1)$$



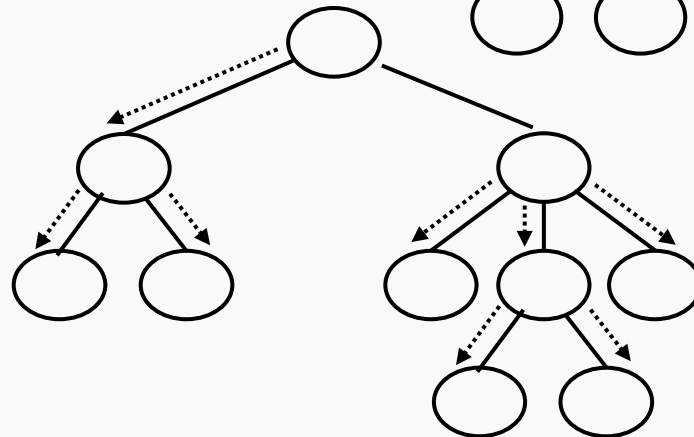
**Saturation:**

$$n$$



**Notification:**

$$n-2$$



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$$\text{Tot: } 2n - 2 + n + n - 2 = 4n - 4$$

# Message Complexity

**Activation:** In general -  $k^*$  initiators

$$n + k^* - 2$$

(wake-up in the tree)

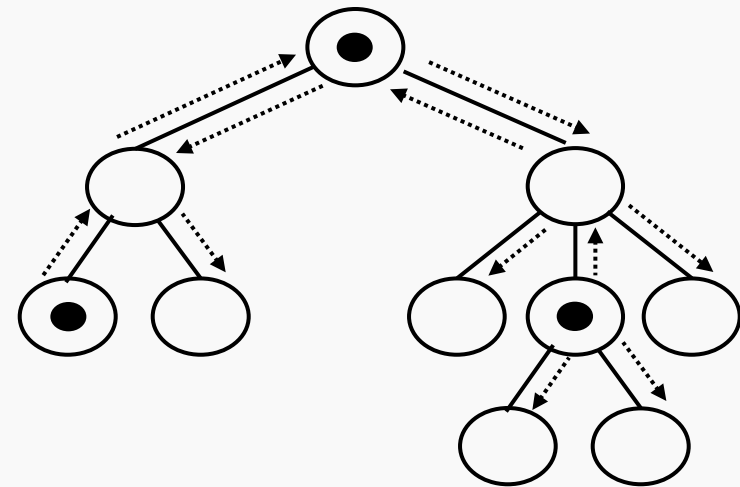
Let  $S$  be the set of initiators

$$\sum_{x \in S} |N(x)| + \sum_{x \notin S} (|N(x)| - 1)$$

$$= \sum_x |N(x)| - \sum_{x \notin S} 1 = 2(n-1) - (n-k^*)$$

$$= 2n - 2 - n + k^*$$

$$= n + k^* - 2$$



# Message Complexity

---

**Activation:** In general -  $k^*$  initiators

$$n + k^* - 2$$

**Saturation:**  $n$  does not depend on number of initiators

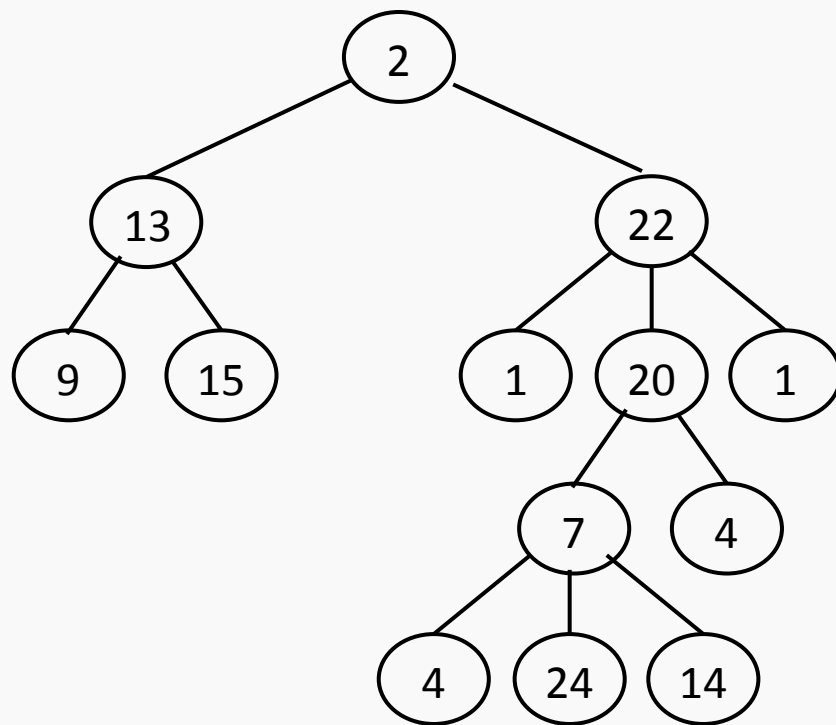
**Notification:**  $n - 2$

$$\text{TOT: } 3n + k^* - 4$$



Put information in the saturation message

## Minimum Finding



Entity x has in input  
 $value(x)$

At the end each entity  
should know whether it is  
the minimum or not.

States  $S$  {AVAILABLE, ACTIVE, PROCESSING,  
SATURATED}    Sinit = AVAILABLE

## AVAILABLE

*Spontaneously*

**send**(Activate) **to** N(x);

**min := v(x);**

Neighbours := N(x)

if |Neighbours|=1 then

**M:=("Saturation", min);**

parent  $\leftarrow$  Neighbours;

**send**(M) **to** parent;

**become** PROCESSING;

else **become** ACTIVE;

*Receiving(Activate )*

**send(Activate) to**  $N(x) - \{\text{sender}\}$ ;

**min:=v(x);**

Neighbours:=  $N(x)$ ;

if  $|N(x)|=1$  then

**M:=("Saturation", min);**

parent  $\leftarrow$  Neighbours;

**send(M) to** parent;

**become** PROCESSING;

else **become** ACTIVE;

## ACTIVE

*Receiving(M)*

**min** := MIN{min, M}

Neighbours := Neighbours - {sender};

**if** |Neighbours| = 1 **then**

**M** := ("Saturation", min);

parent  $\leftarrow$  Neighbours;

**send**(M) **to** parent;

**become** PROCESSING;

## PROCESSING

*receiving(M)*

```
min:= MIN{min, M}  
Notification:= (“Resolution”, min)  
send (Notification) to N(x) -parent  
if v(x)=min then  
    become MINIMUM  
else  
    become LARGE
```

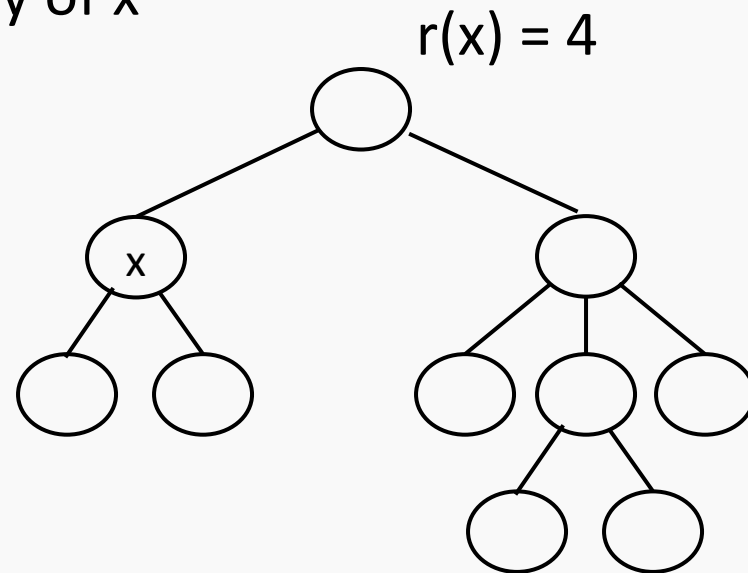
*receiving(Notification)*

```
send(Notification) to N(x) -parent  
if v(x)=Received_Value then  
    become MINIMUM;  
else  
    become LARGE;
```

# Finding Eccentricities

$d(x,y)$  = distance between  $x$  and  $y$

$\text{Max}_{y} \{d(x,y)\} = r(x)$       eccentricity of  $x$



How to find the eccentricity of all nodes

## Idea 1:

---

- 1) EVERY NODE BROADCASTS A REQUEST,
- 2) THE LEAVES SEND UP A MESSAGE TO COLLECT THE DISTANCES.

Complexity:  $O(n^2)$

## Other Idea:

---

Based on the saturation technique:

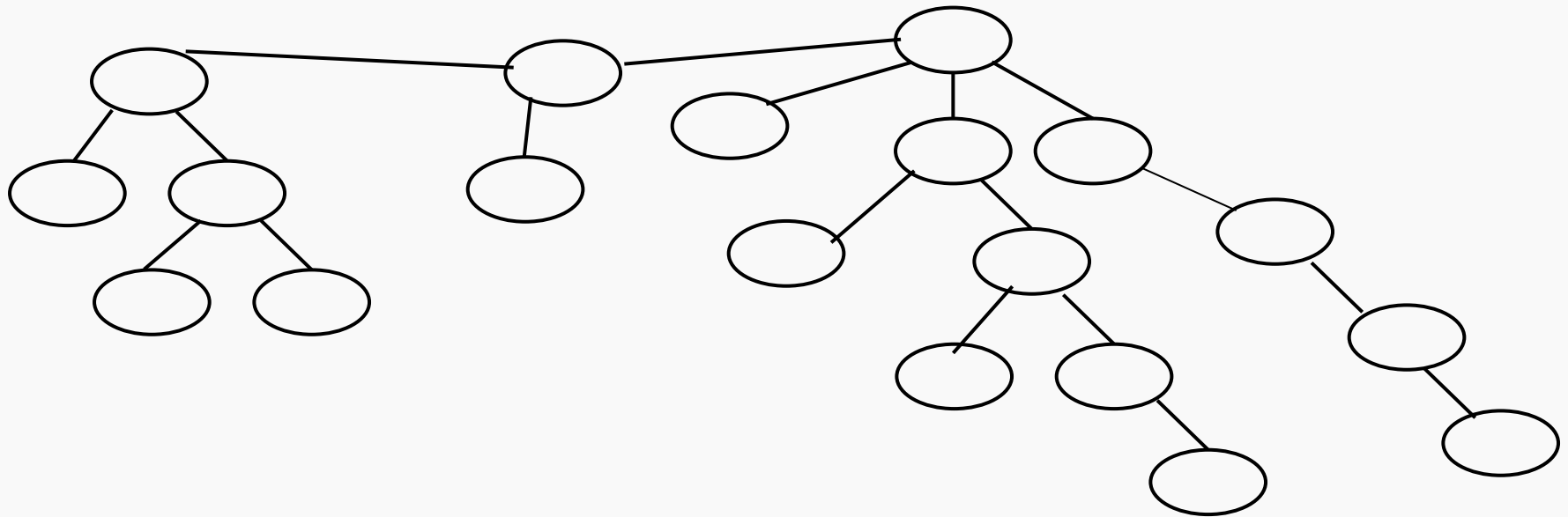
- 1) FIND THE ECCENTRICITY OF THE TWO SATURATED NODES
- 2) PROPAGATE THE NEEDED INFO SO THAT THE OTHER NODES CAN FIND THEIR ECCENTRICITY (IN THE NOTIFICATION PHASE)

Complexity = saturation



# Observations and Examples

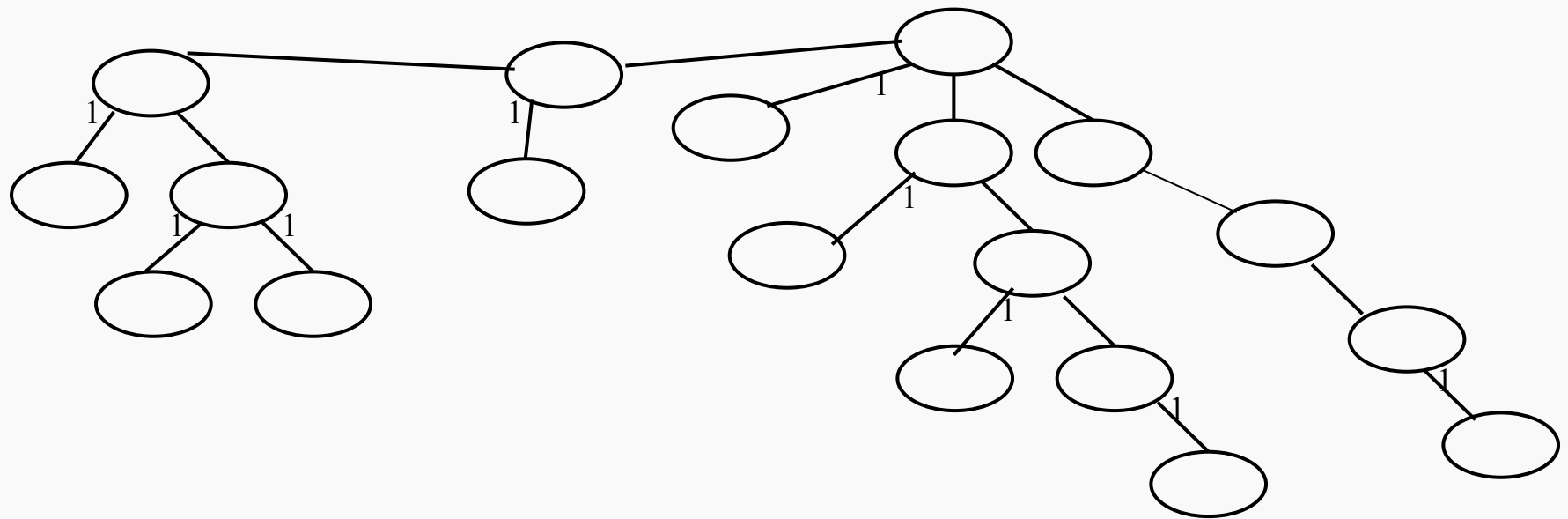
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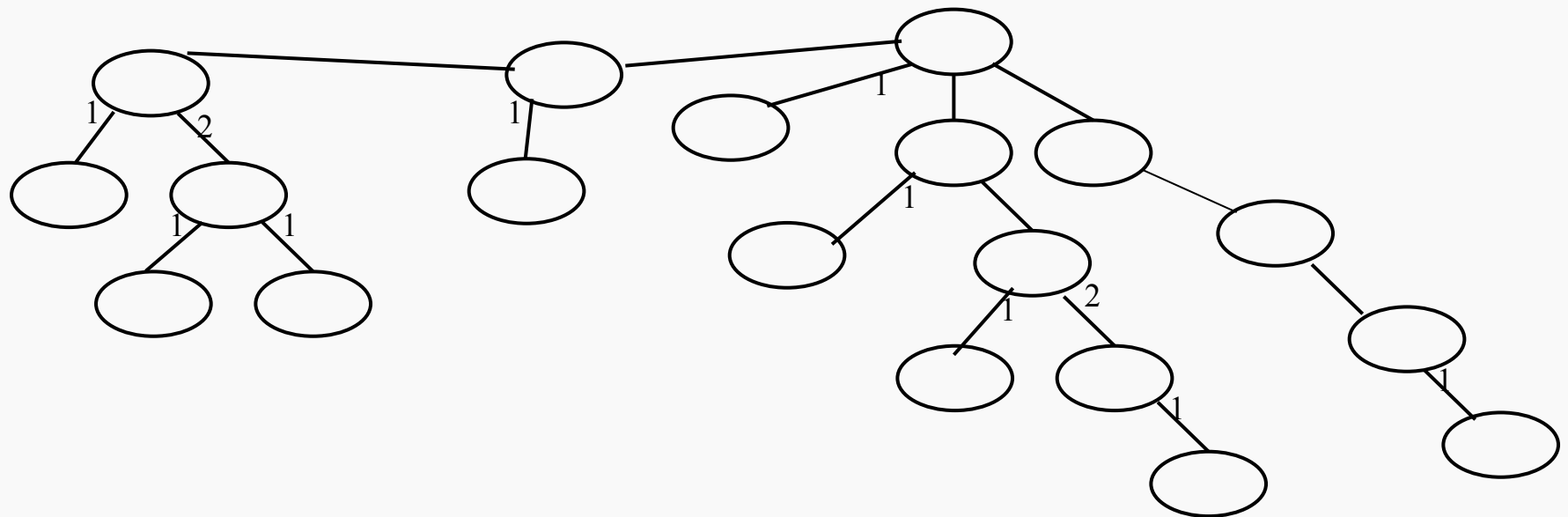
States  $S$  {AVAILABLE, ACTIVE, PROCESSING,  
SATURATED}     $S_{init} = AVAILABLE$

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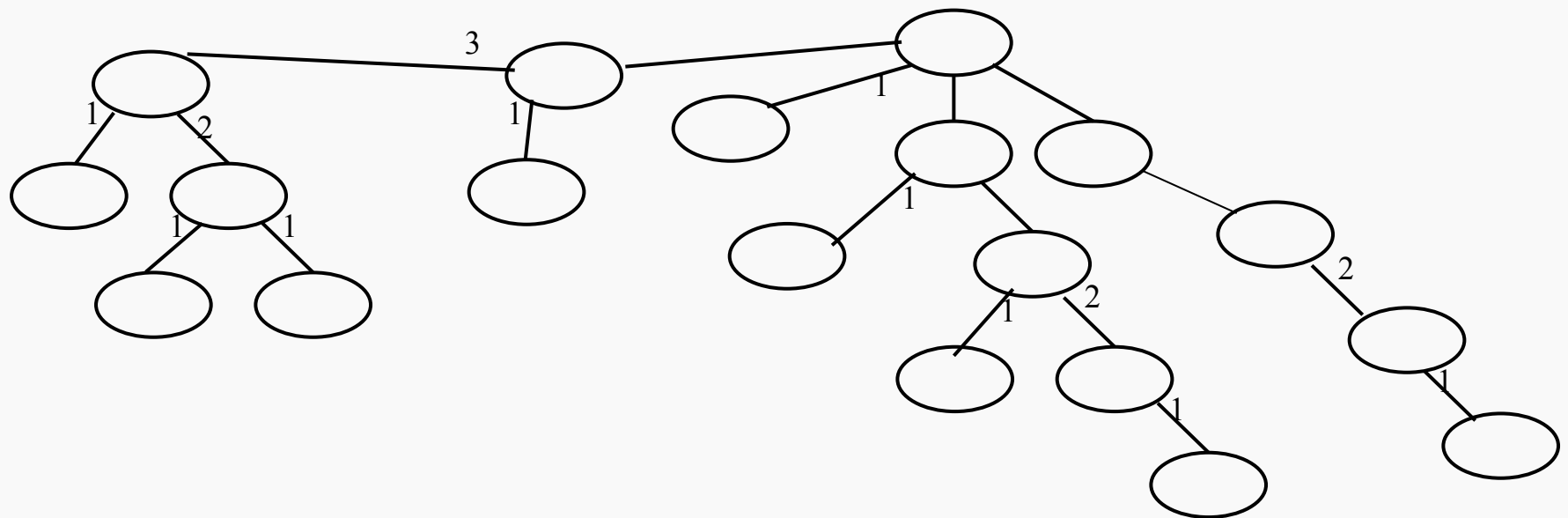
# FIND THE ECCENTRICITY



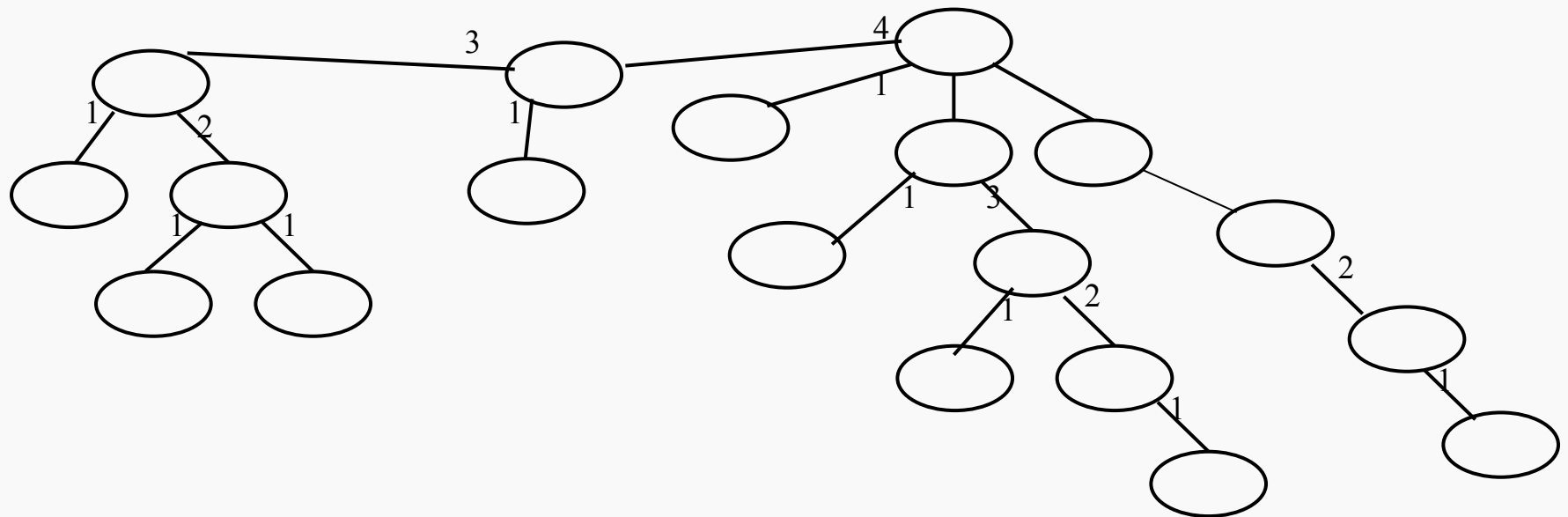
# FIND THE ECCENTRICITY



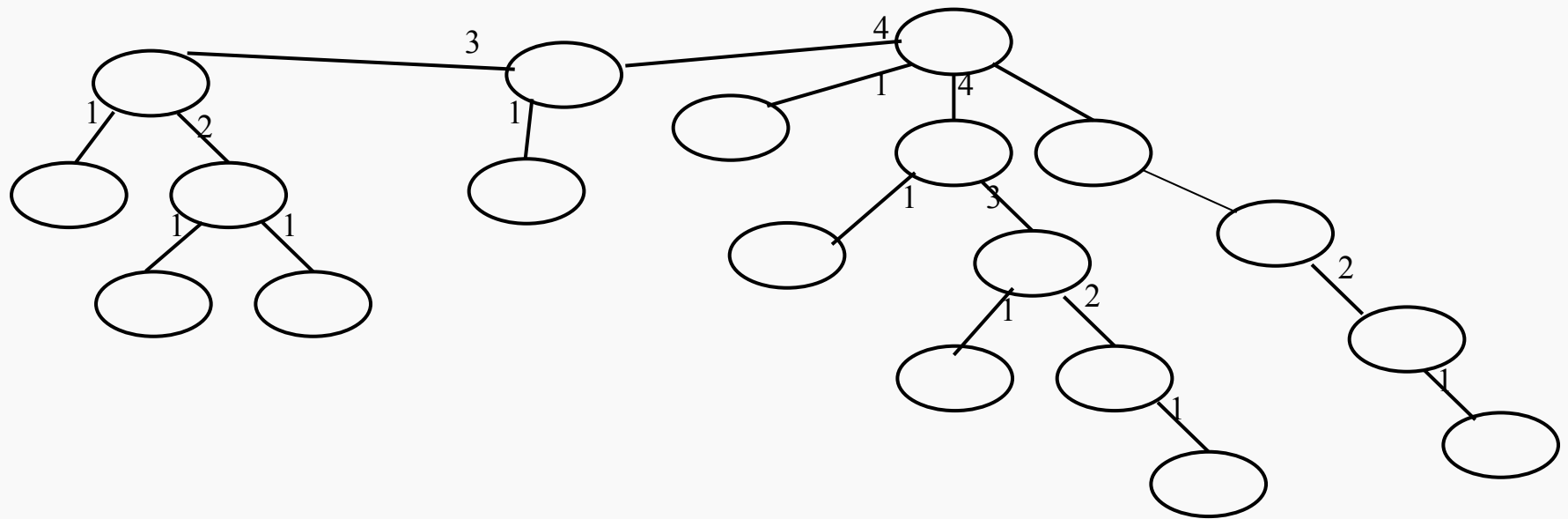
# FIND THE ECCENTRICITY



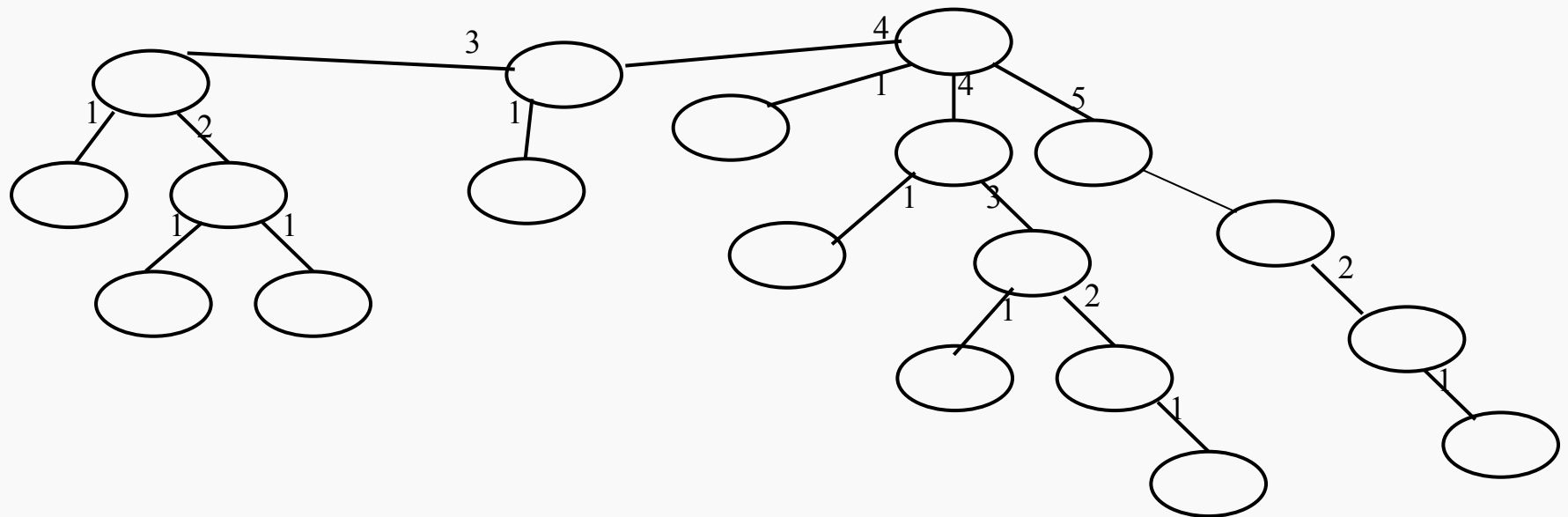
# FIND THE ECCENTRICITY



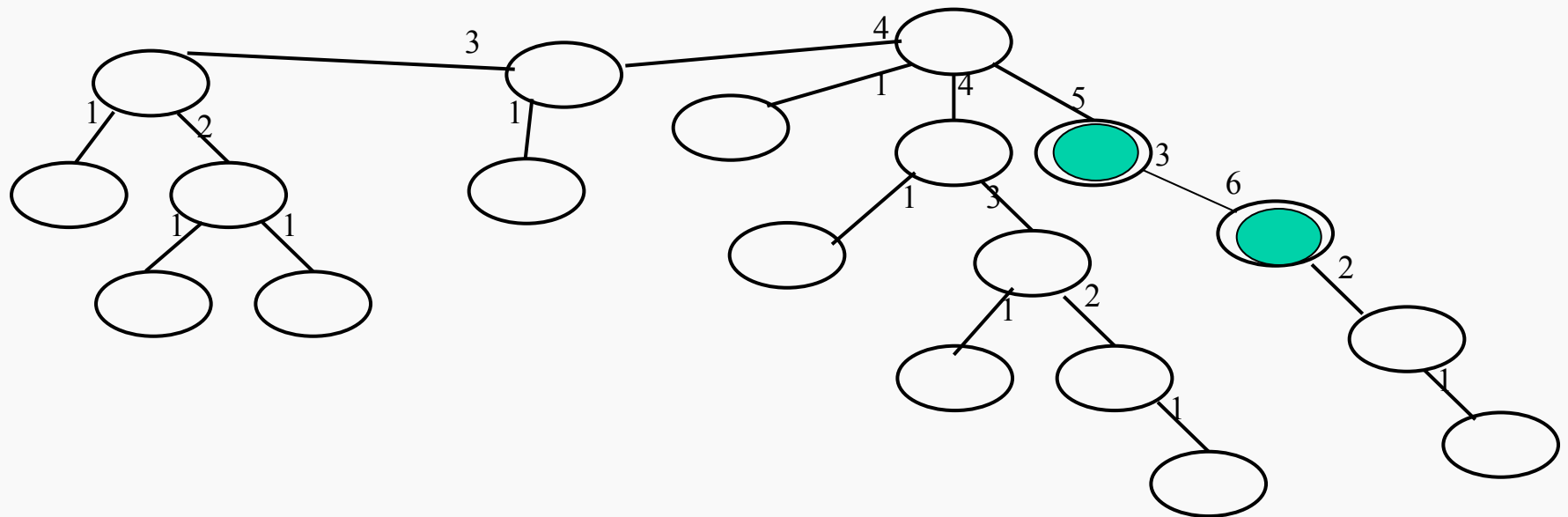
# FIND THE ECCENTRICITY



# FIND THE ECCENTRICITY

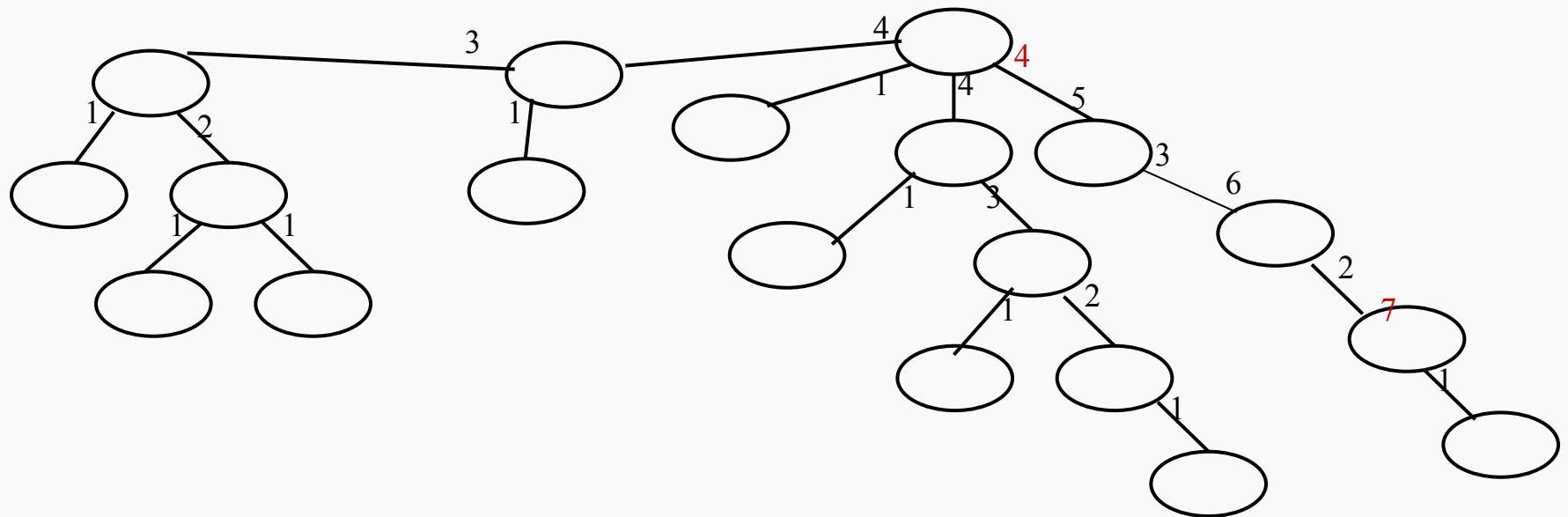


# FIND THE ECCENTRICITY

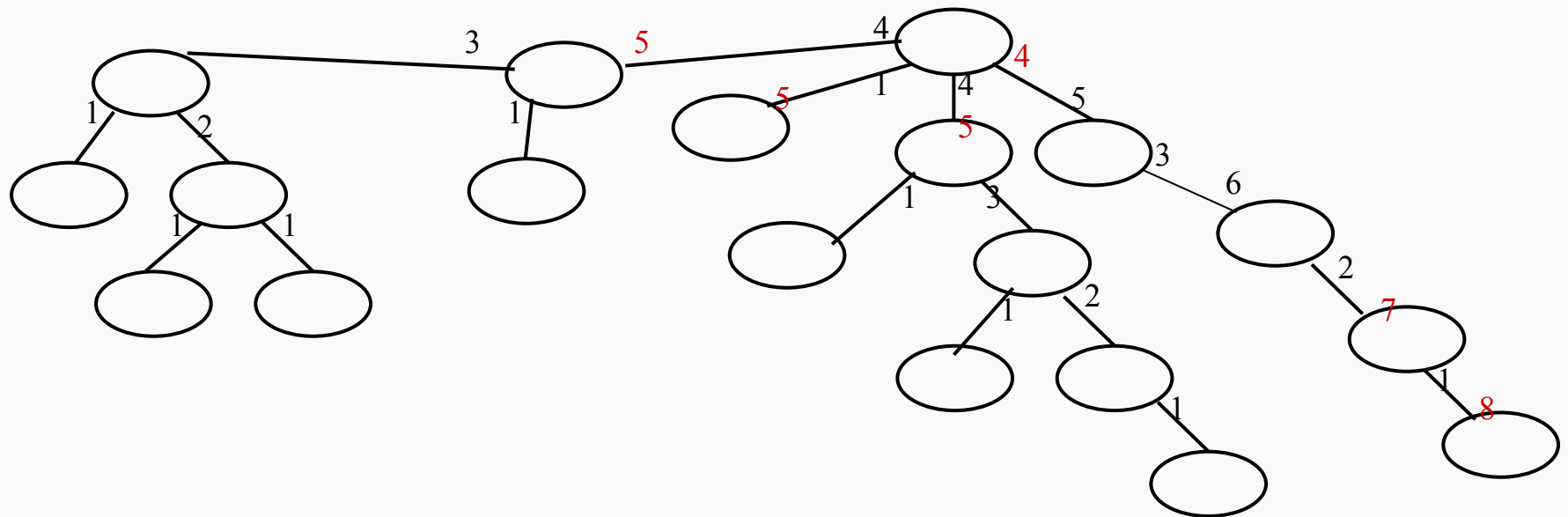




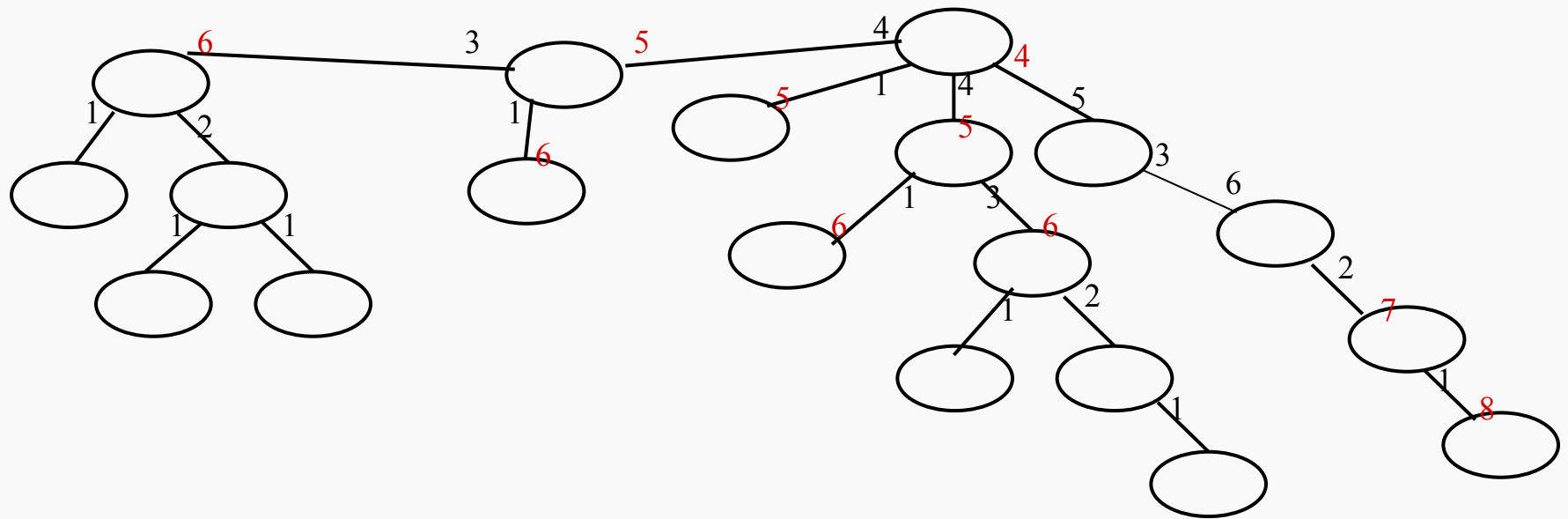
# FIND THE ECCENTRICITY



# FIND THE ECCENTRICITY

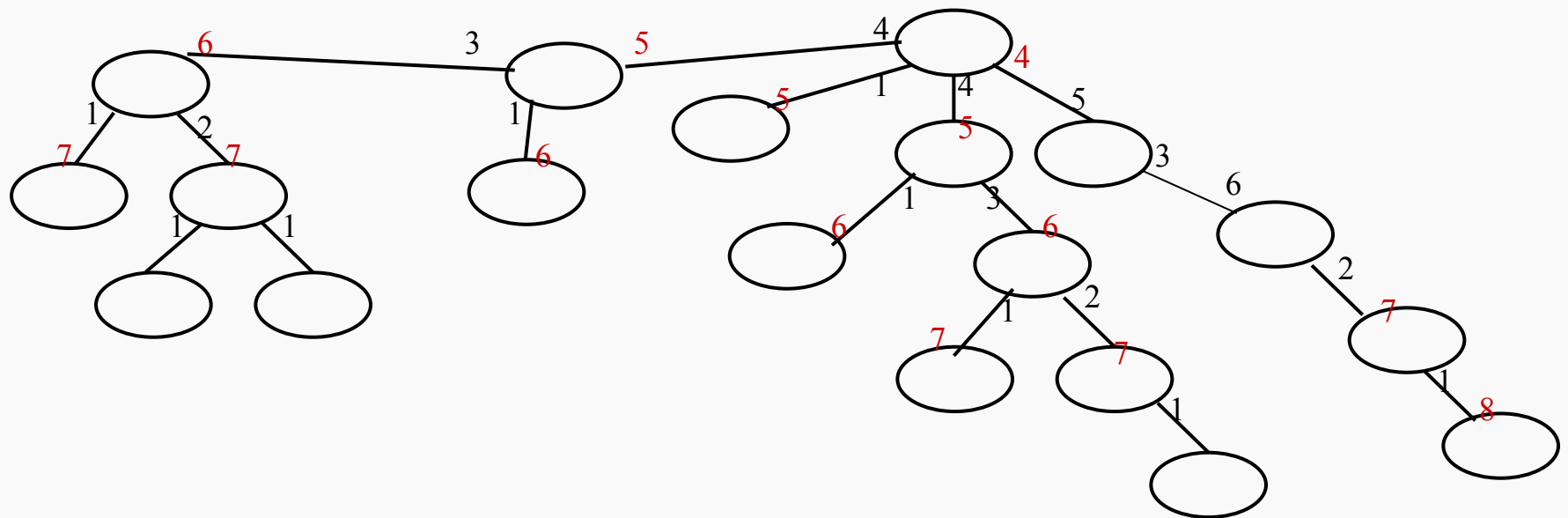


# FIND THE ECCENTRICITY



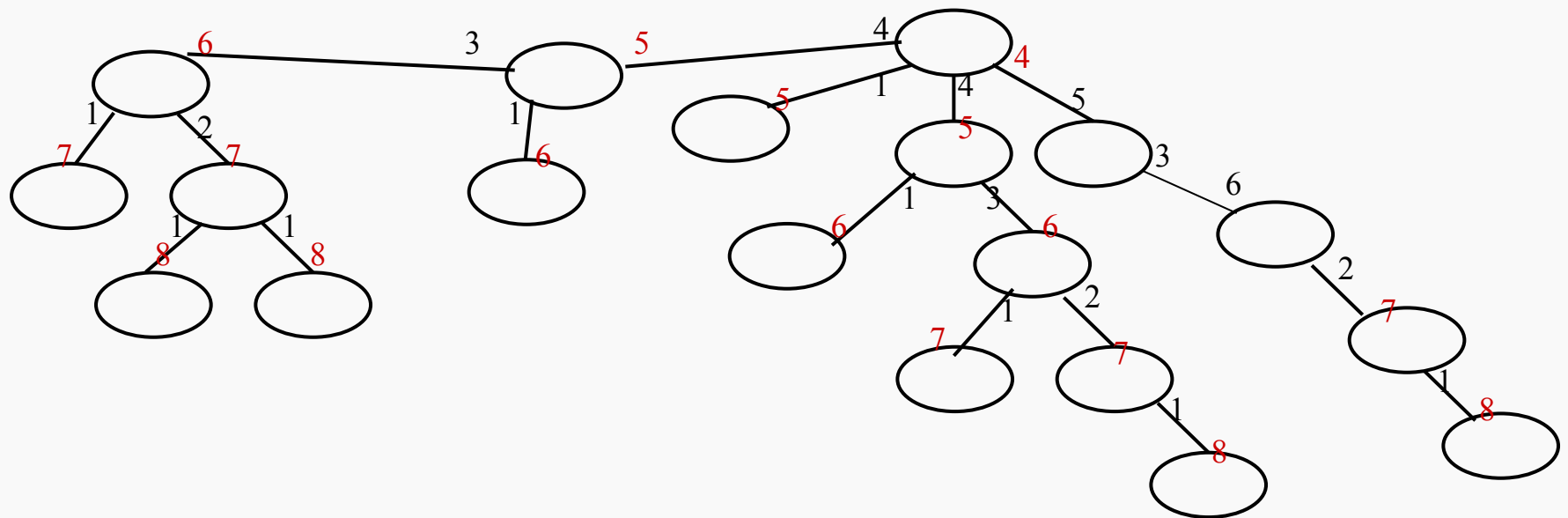
Paola Flocchini

# FIND THE ECCENTRICITY



Paola Flocchini

# FIND THE ECCENTRICITY



## define Distance[ ]

### AVAILABLE

*Spontaneously*

**send**(Activate) **to** N(x);

Distance[x]:= 0;

Neighbours:=N(x)

if |Neighbours|=1 then

    maxdist:= 1+ Max{Distance[\*]}

    M:=("Saturation", maxdist);

    parent  $\leftarrow$  Neighbours;

**send**(M) **to** parent;

**become** PROCESSING;

else **become** ACTIVE;

*Receiving(Activate)*

```
send(Activate)to N(x) – {sender};  
Distance[x]:= 0;  
Neighbours:= N(x);  
if |Neighbours|=1 then  
    maxdist:= 1+ Max{Distance[*]}  
    M:=("Saturation", maxdist);  
    parent  $\leftarrow$  Neighbours;  
    send(M) to parent;  
    become PROCESSING;  
else become ACTIVE;
```

## ACTIVE

*Receiving(M)*

Distance[{sender}] := Received\_distance;

Neighbours := Neighbours - {sender};

if |Neighbours| = 1 then

    maxdist := 1 + Max{Distance[\*]}

    M := ("Saturation", maxdist);

    parent ← Neighbours;

**send(M) to parent;**

**become PROCESSING;**



## PROCESSING

*receiving(M)*

Distance[{ sender}]:= Received\_distance;

$r(x) := \text{Max} \{ \text{Distance}[z] : z \in N(x) \}$

**for all**  $y \in N(x) - \{\text{parent}\}$  **do**

    maxdist:= 1+ Max{Distance[z]:  
   $z \in N(x) - \{y\}$

**send**("Resolution", maxdist) **to** y

endfor

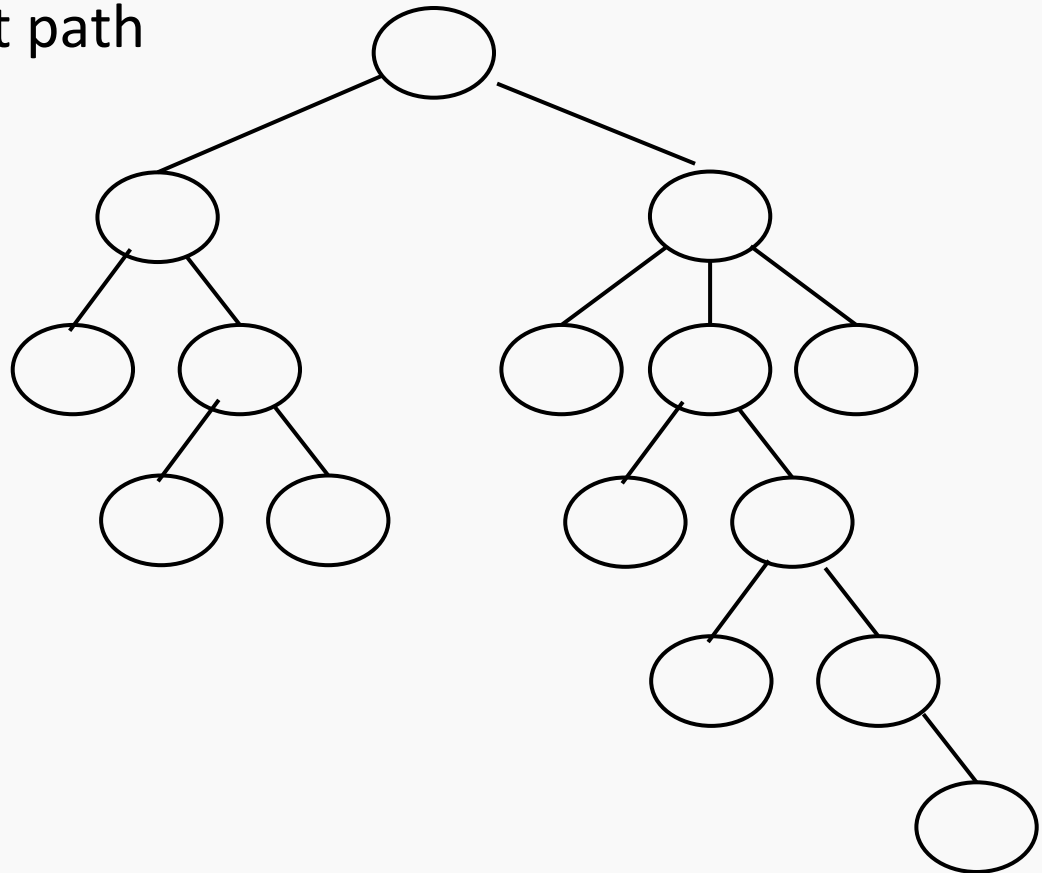
**become** DONE

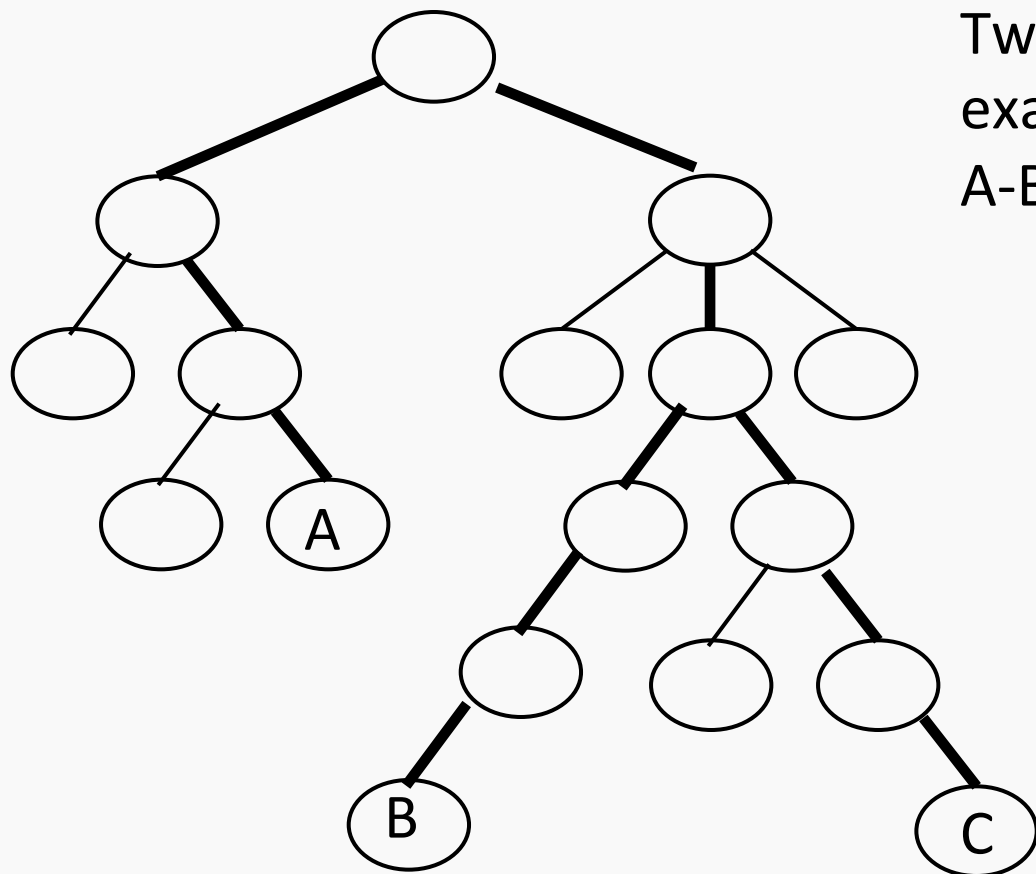
# Center Finding

---

$c$  is the center if  $r(c) \leq r(x)$  for all  $x$  belonging to  $V$ . **Max distance is minimized.**

Diametral path: Longest path

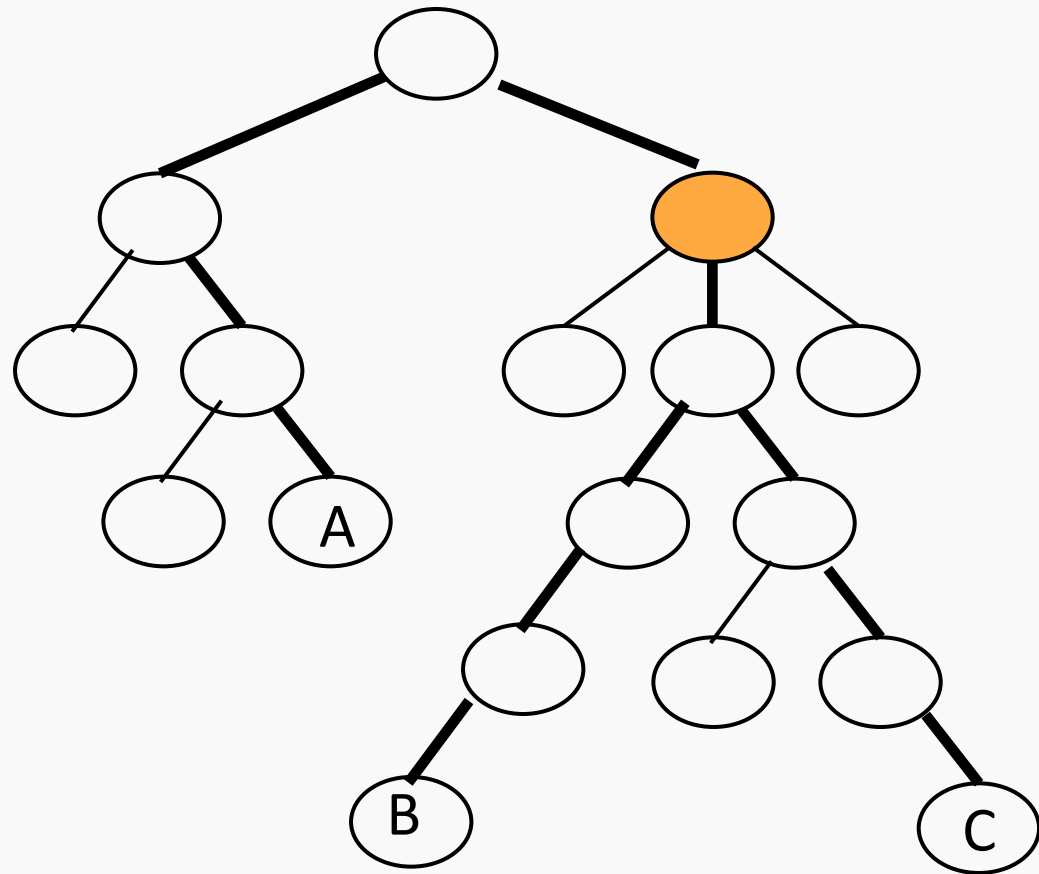




Two diameters in this example:  
A-B, and A-C

---

The center is the node with smallest eccentricity



One Idea:

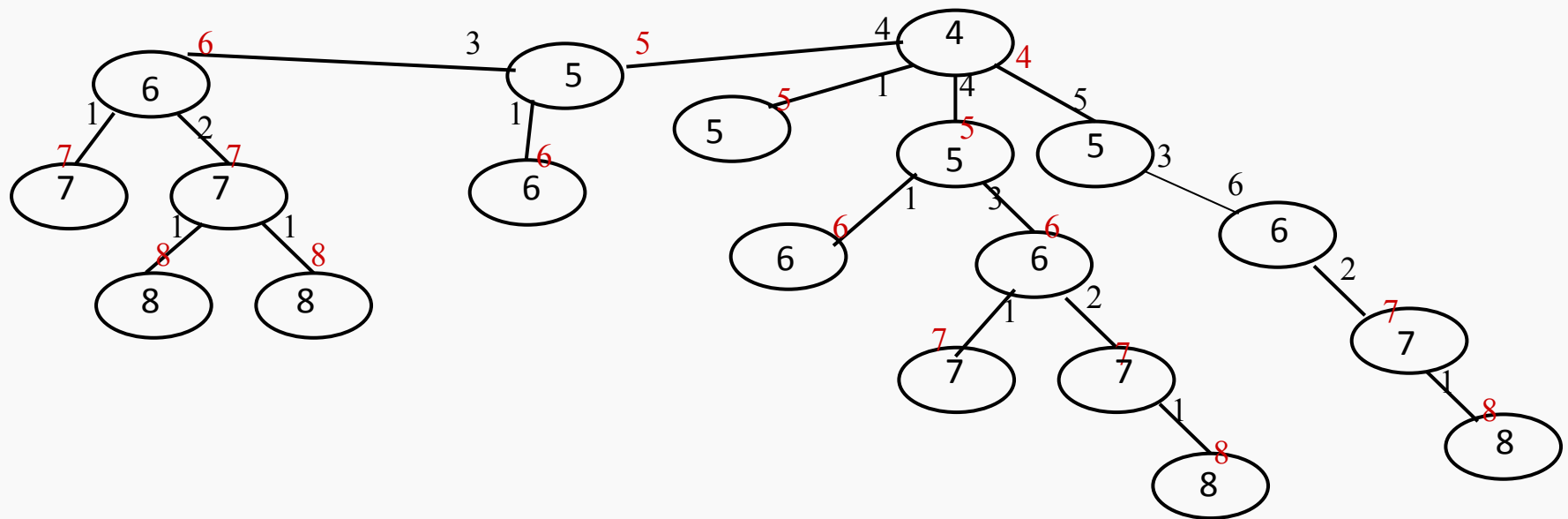
- 1) FIND ALL THE ECCENTRICITIES
- 2) FIND THE SMALLEST

$$4n-4$$

$$2n-2$$



$$6n-6$$



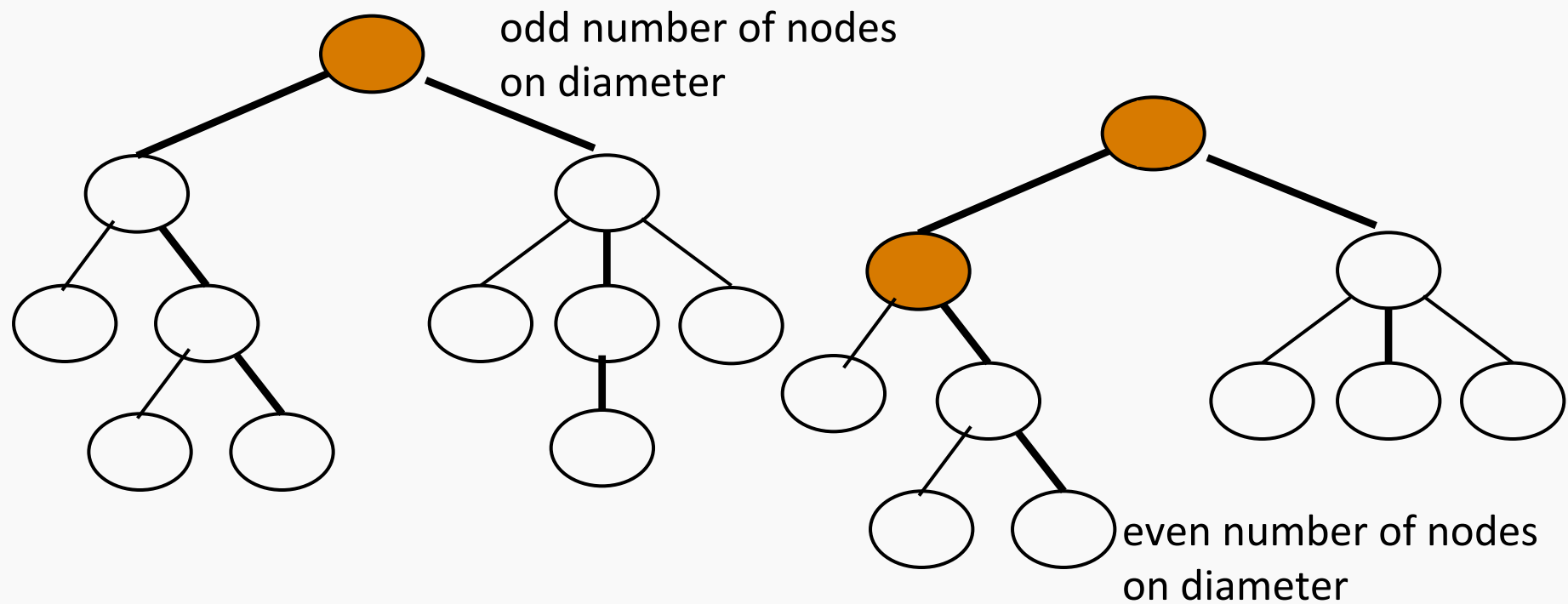
1) FIND ALL THE ECCENTRICITIES  
 2) FIND THE SMALLEST

---

A better strategy can be devised exploiting properties of the center.

---

**Property 1:** In a tree there is a unique center, or there are two centers that are neighbours



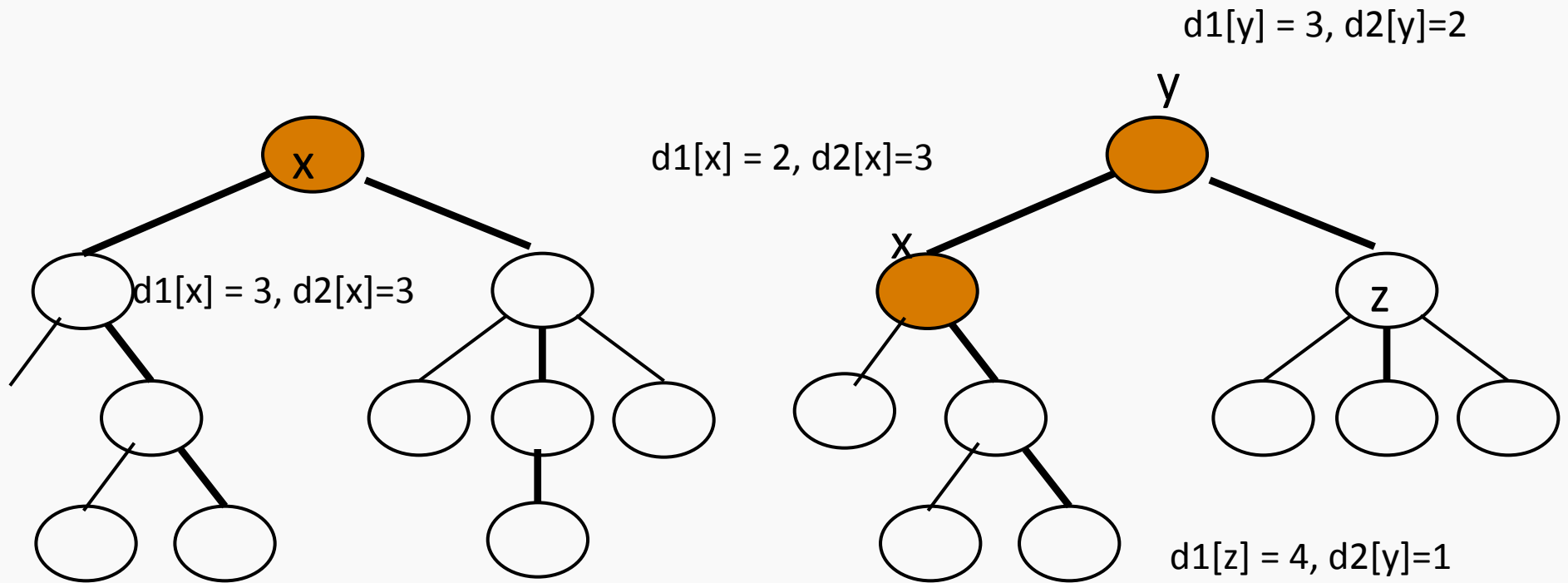
**Proposition 2:** Centers are on diametral paths.

$d1[x] = \text{max dist}$      $d2[x] = \text{second max dist (through different neighbours)}$

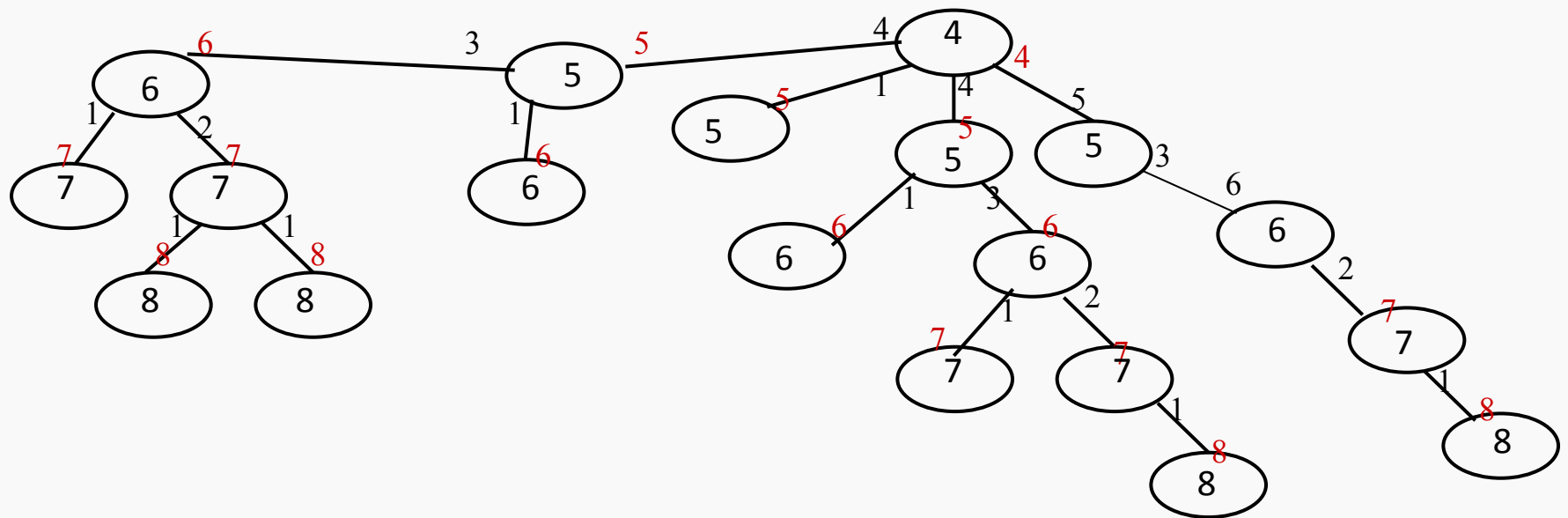
**Property 3:** A node  $x$  is a center iff

$$d1[x] - d2[x] \leq 1$$

(if  $d1[x] = d2[x]$  there is only one center).







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Another Idea:

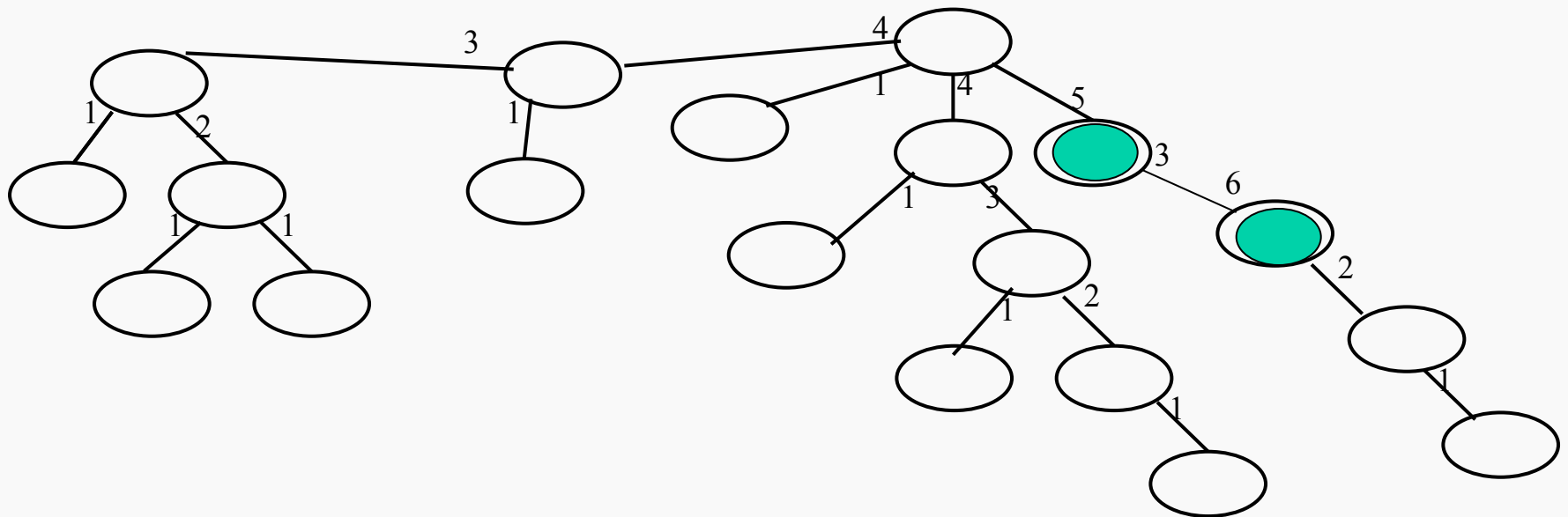
- 1) FIND ALL THE ECCENTRICITIES
- 2) EACH NODE CAN FIND OUT LOCALLY WHETHER IT IS THE CENTER OR NOT

4n-4

Yet another better idea:

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1) FIND THE ECCENTRICITIES OF THE SATURATED NODES



2) LOCALLY CHECK IF I AM THE CENTER

3) IF I AM NOT THE CENTER ...

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Yet another better idea:

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- 1) FIND THE ECCENTRICITIES OF THE SATURATED NODES  $3n-2$
- 2) LOCALLY CHECK IF I AM THE CENTER (CHECKING LARGEST AND SECOND LARGEST)
- 3) IF I AM NOT THE CENTER, PROPAGATE THE DISTANCE INFORMATION ONLY IN THE DIRECTION OF THE CENTER  $\leq n/2$

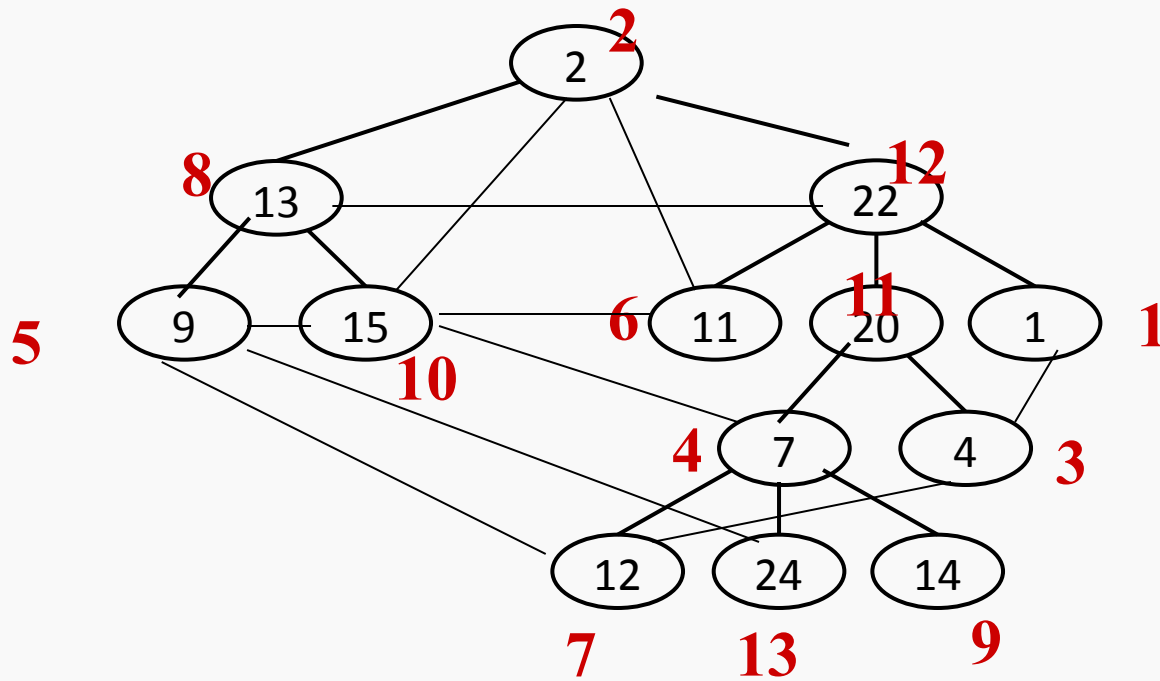
How do I know the direction of the center ?

Examples .....  
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$\leq 3.5 n-2$

# Ranking

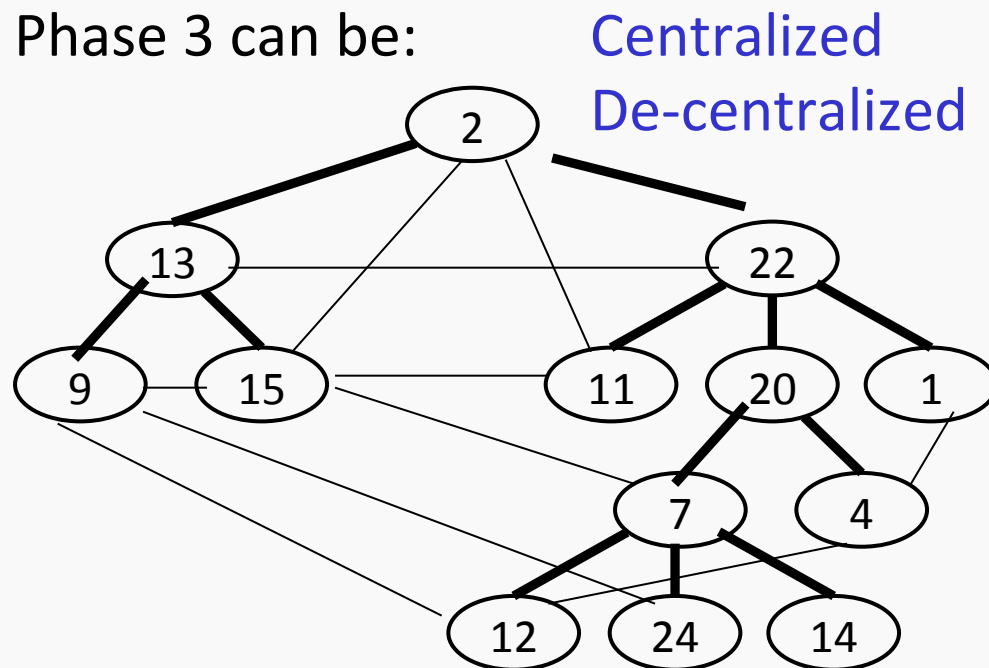
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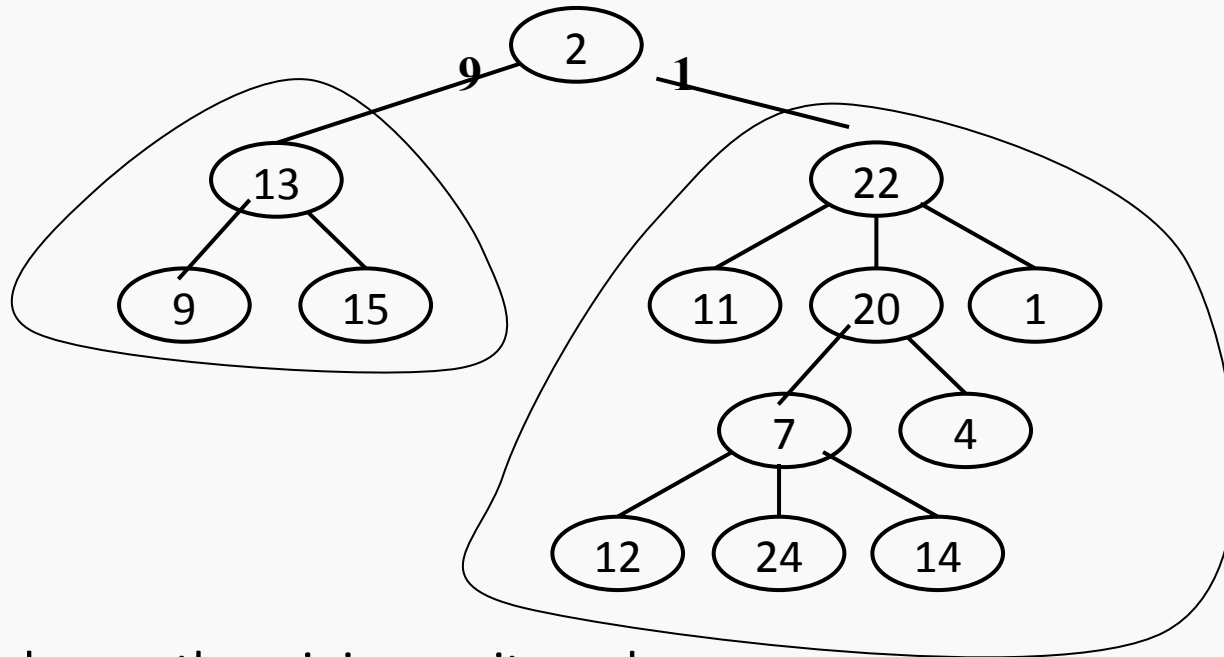
## In an arbitrary network:

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- 1) Find a spanning tree
- 2) Use saturation+ minimum finding to find a starting node
- 3) Do-ranking



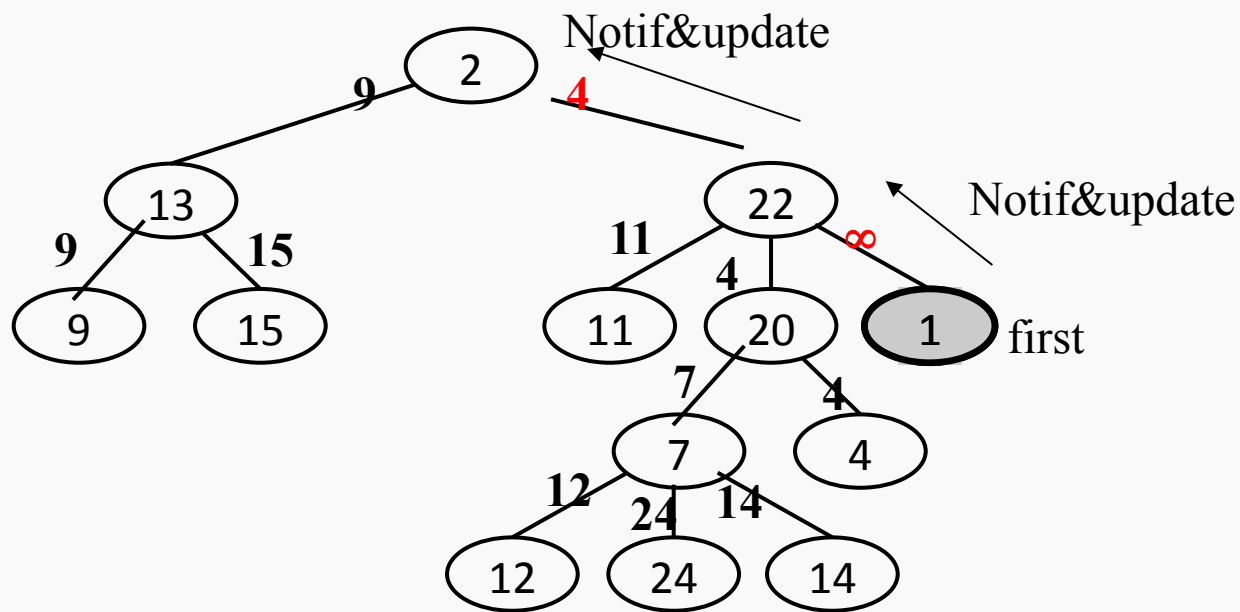
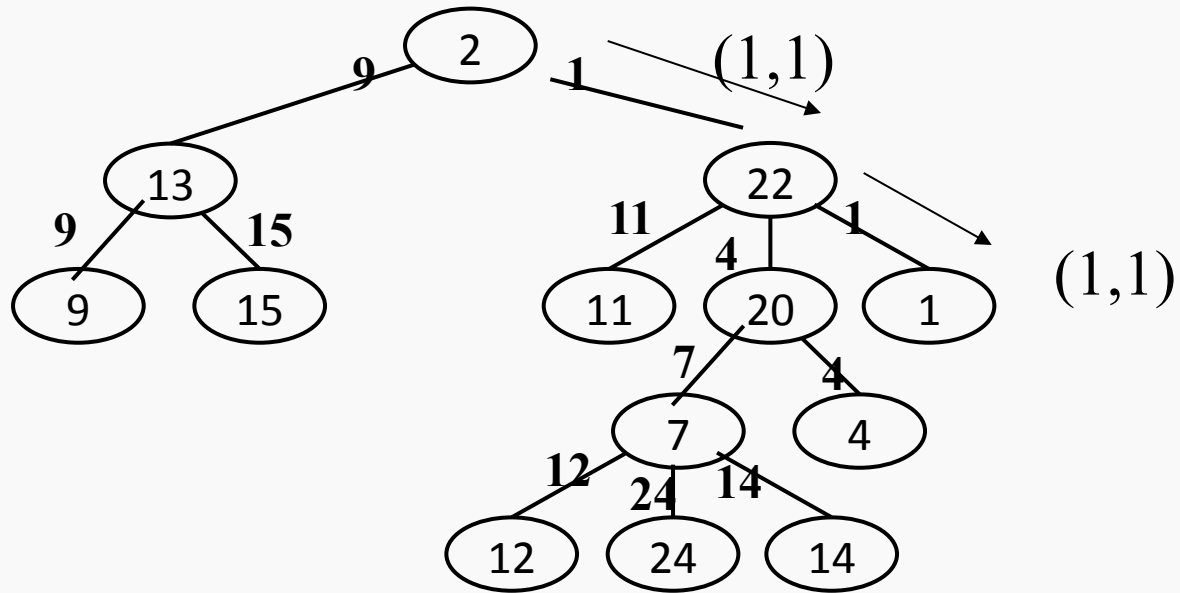
## Centralized Ranking



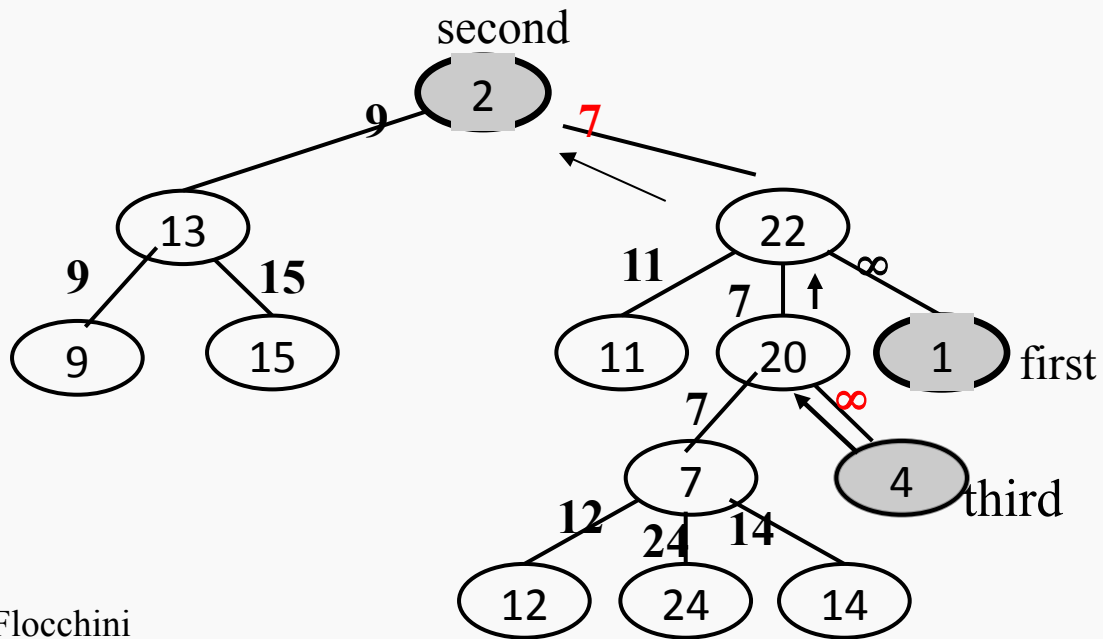
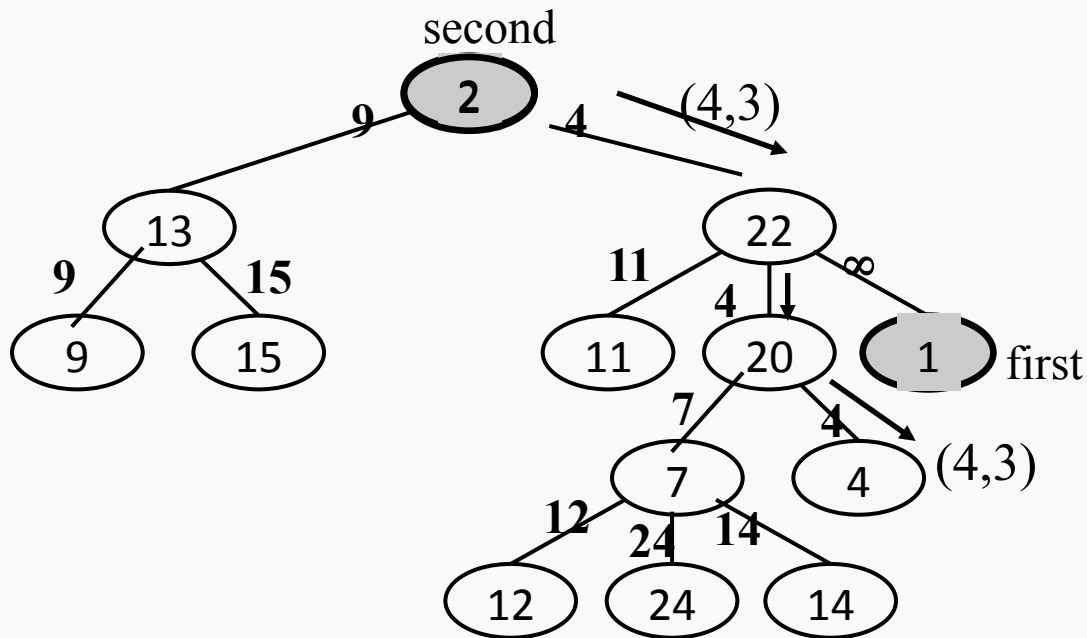
The leader knows the minimum, it sends in that direction a ranking message

Every node knows the minimum in its subtrees, they can then forward the ranking message in the right direction

When the node to be ranked receives the message  
It sends up a notification&update message that will travel up to the leader





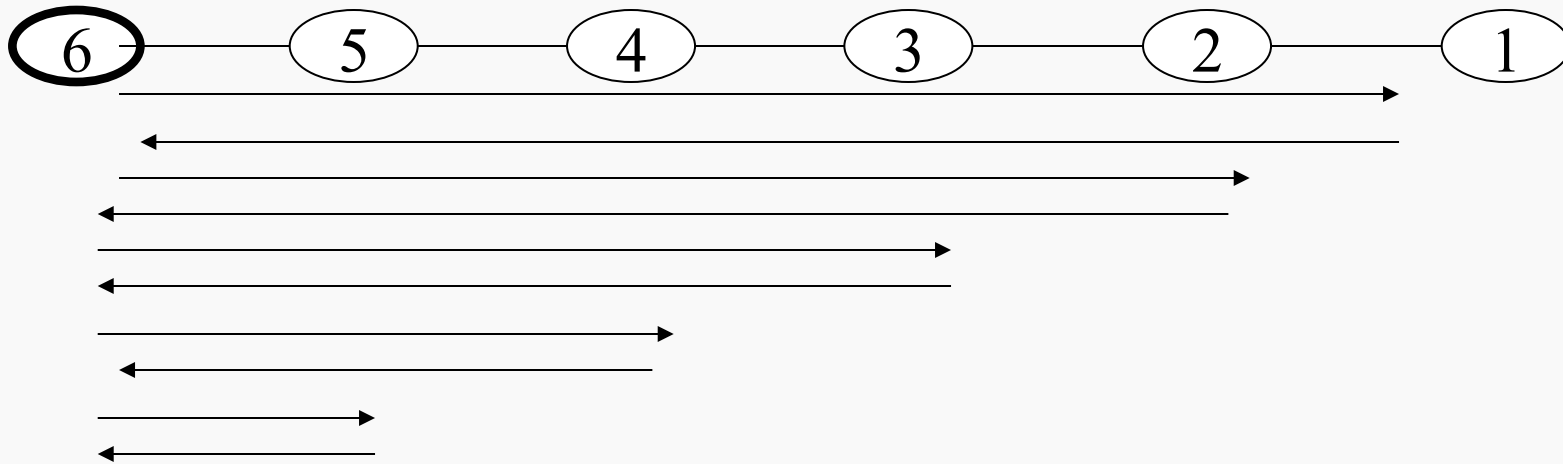


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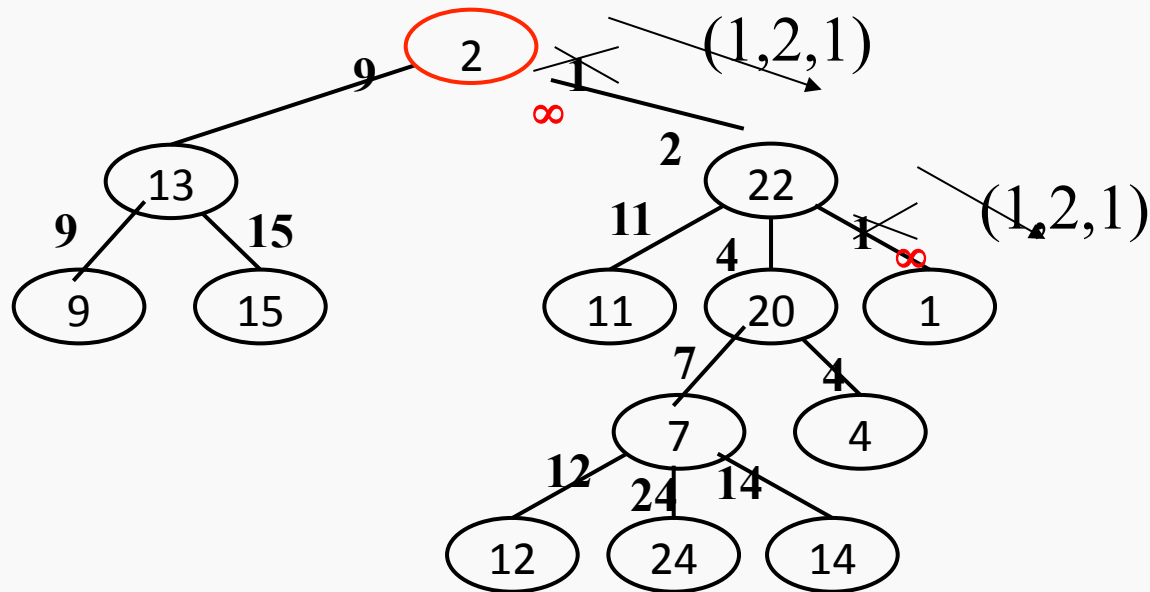
Etc...

## Complexity: worst case

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# Decentralized Ranking



The starter node send a ranking message of the form:  
**(first, second, rank)** in the direction of first.

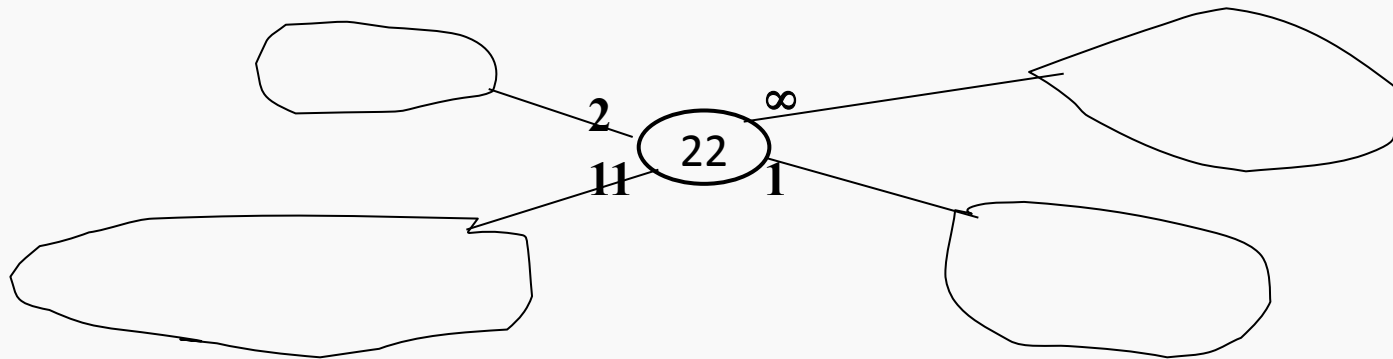
**first:** smallest value

**second:** second smallest known **SO FAR**

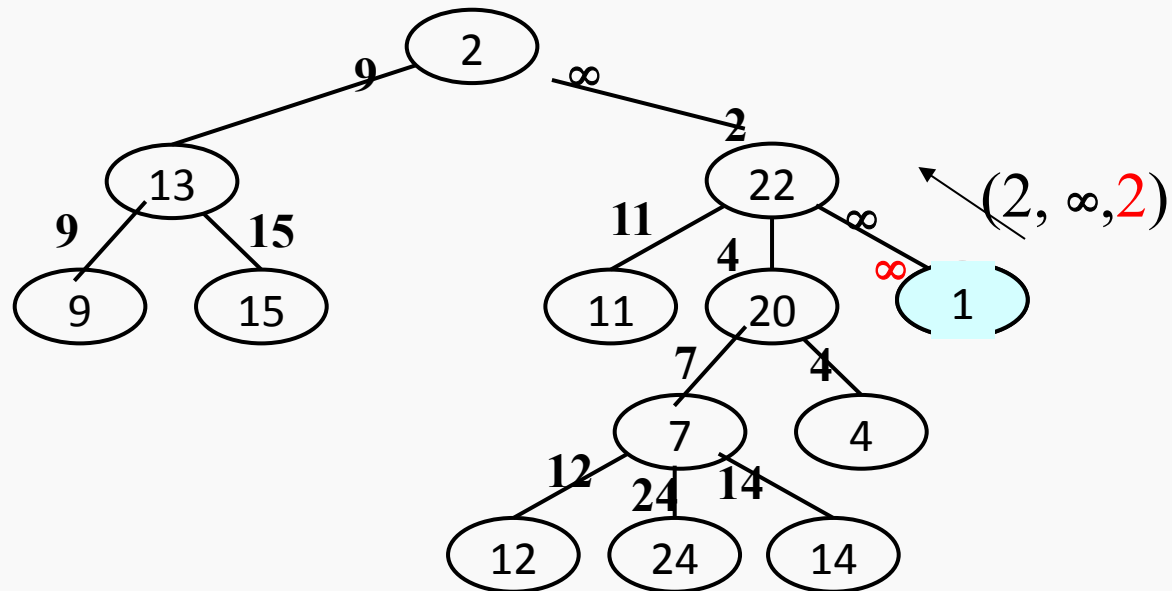
(this is a guess on the value that has to be ranked after first)

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The value on a link indicates the SMALLEST value in the corresponding subtree.



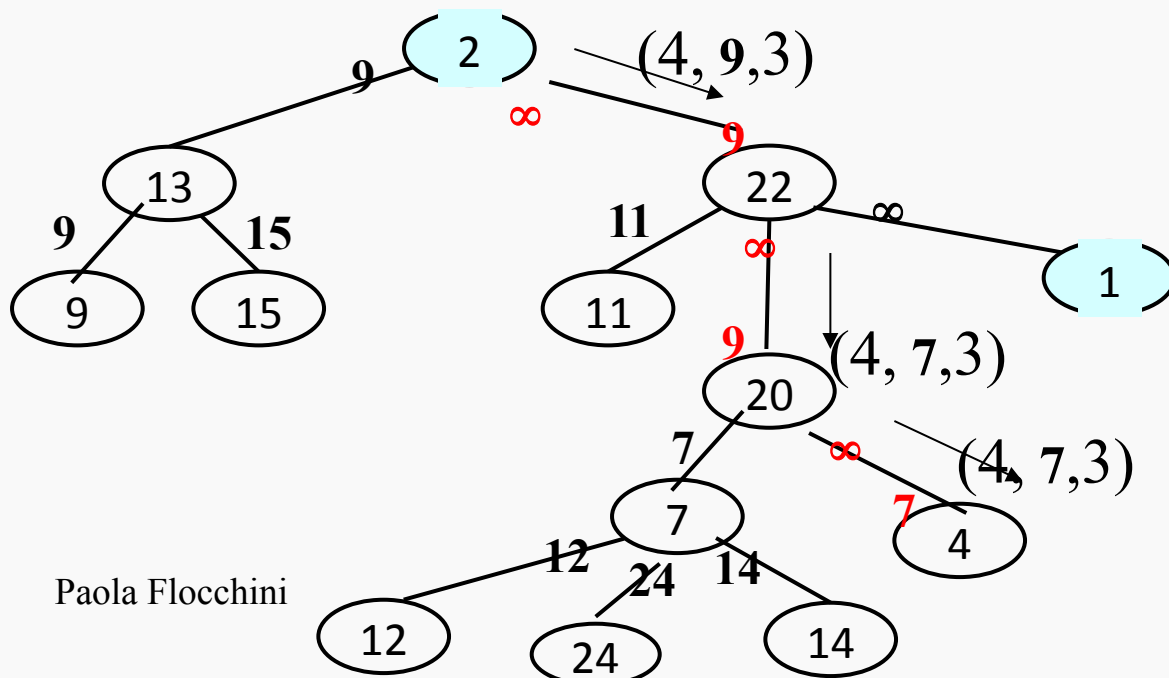
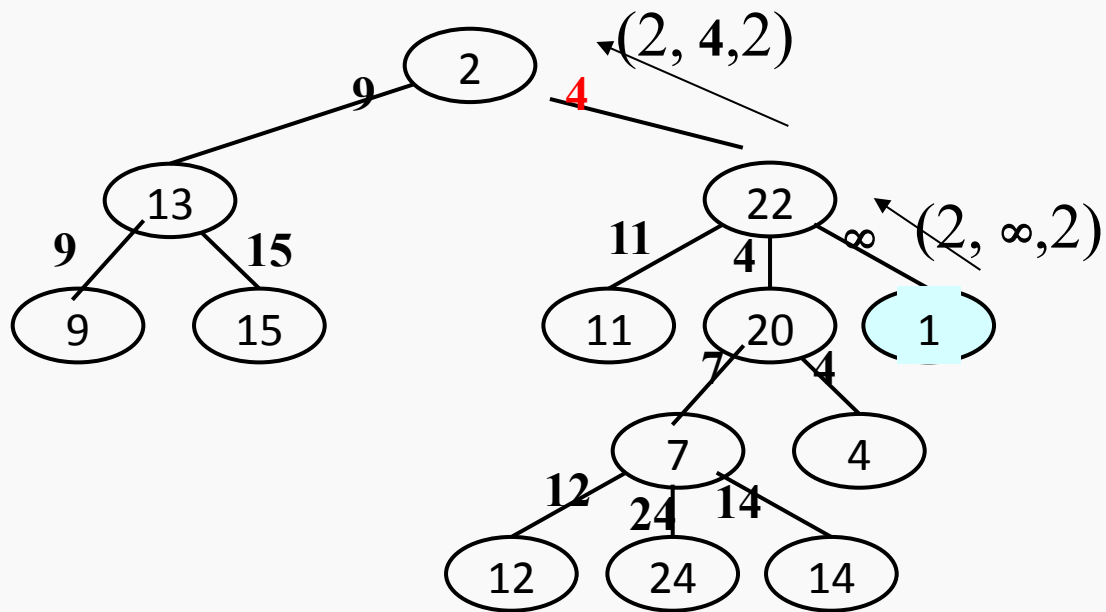
If no value is indicated (or the value is  $\infty$ ) it means that the smallest in the corresponding subtree is unknown (for the moment)



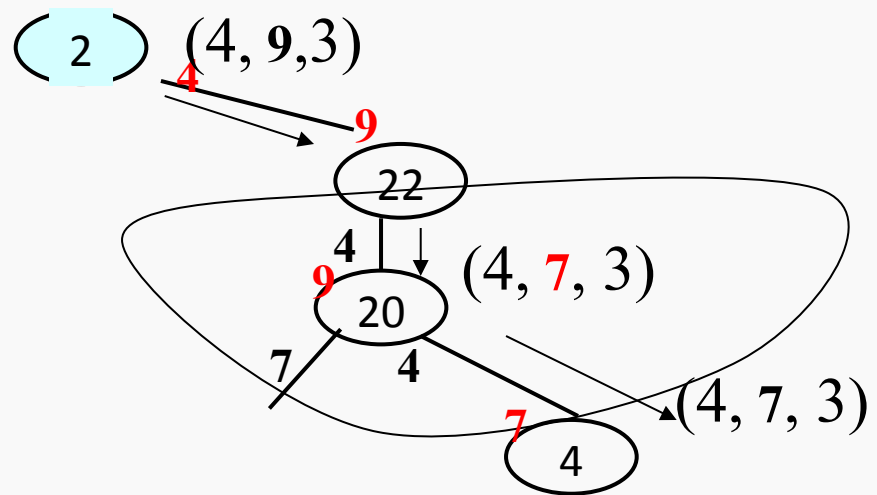
The ranked node attempts to send a ranking message to the next node to be ranked

**Second** might now be unknown, in this case the value  $\infty$  is used

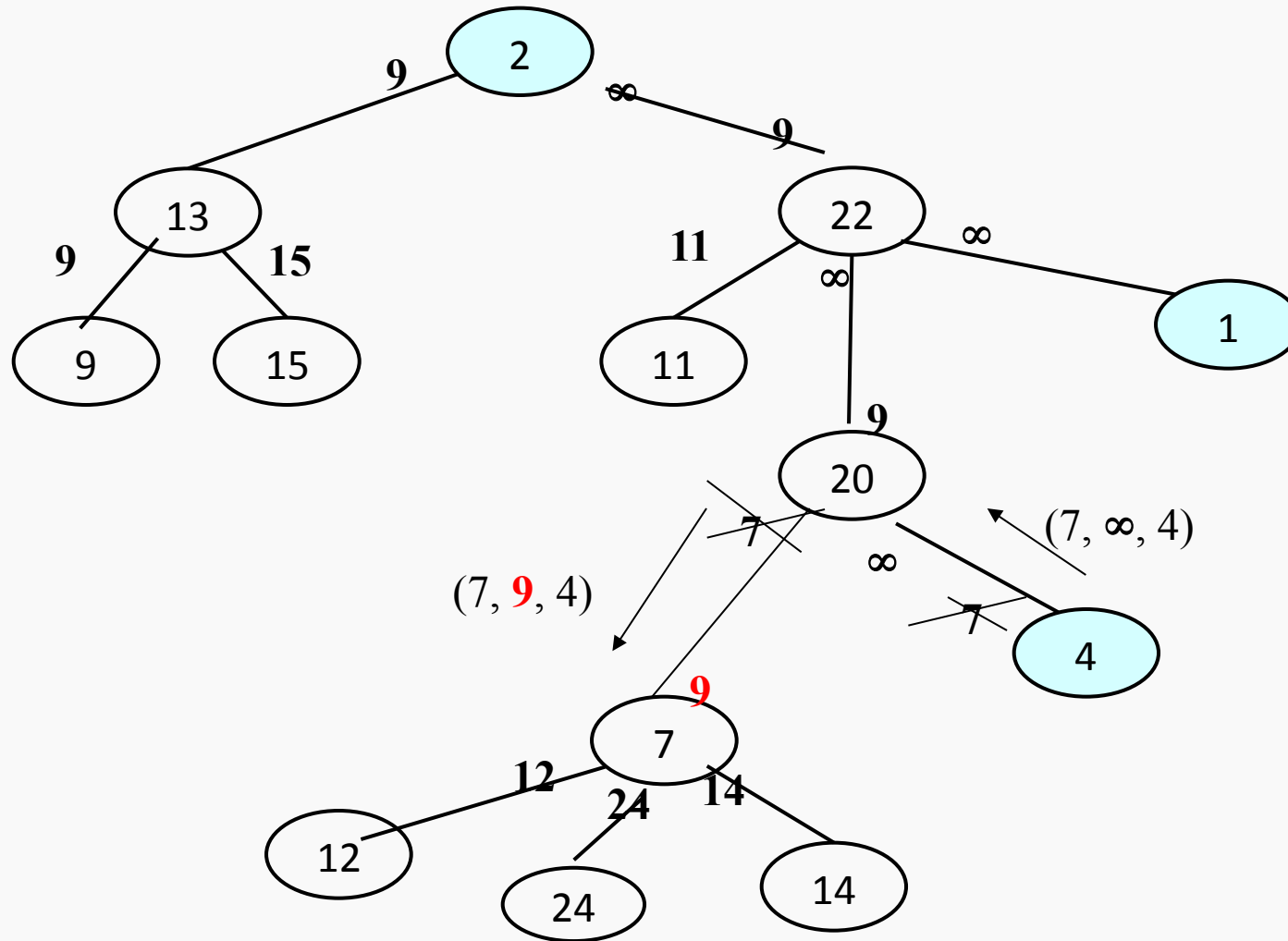
The second variable of the rank message is updated during its travel and the minimum values on the links of the tree are also updated



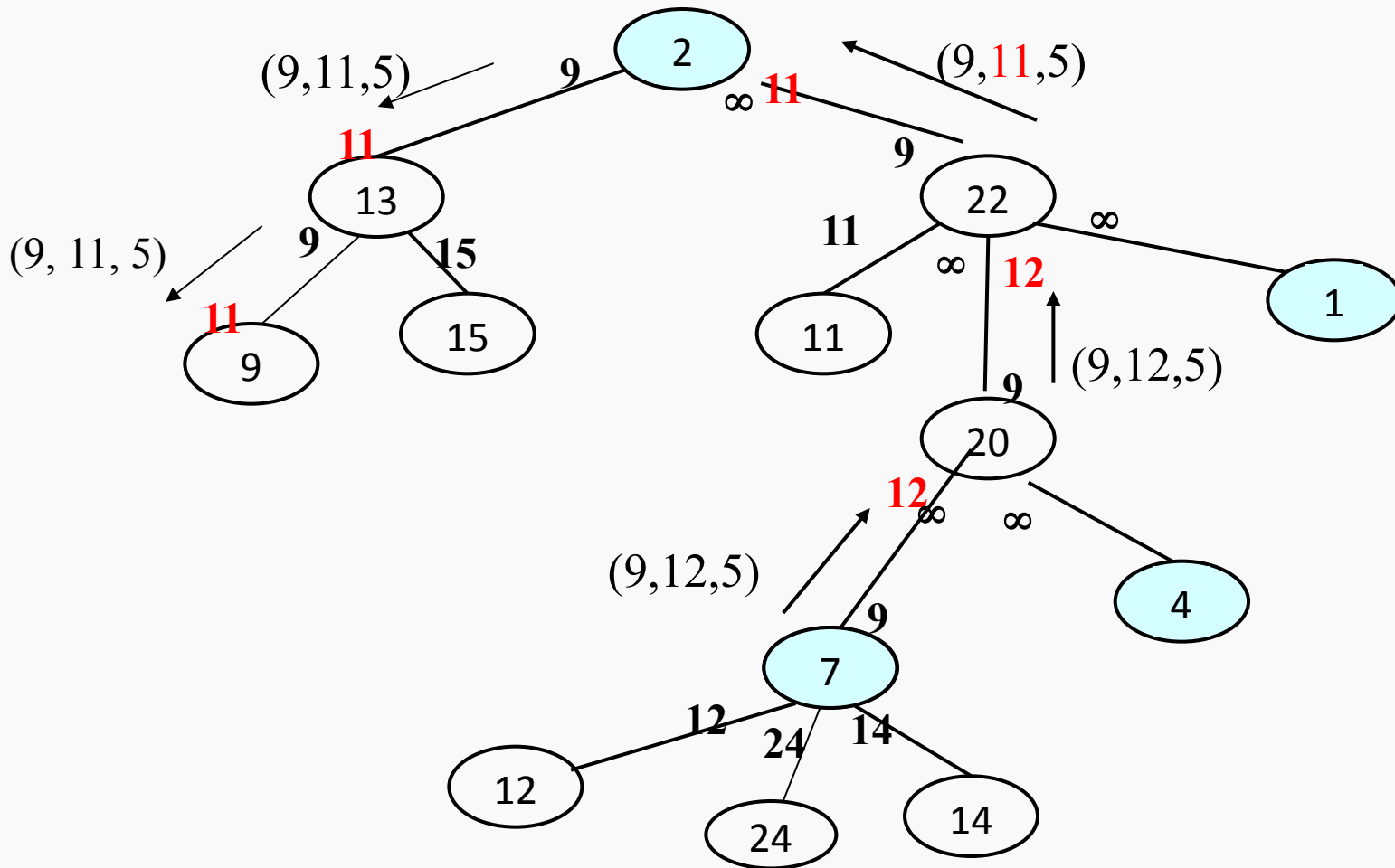
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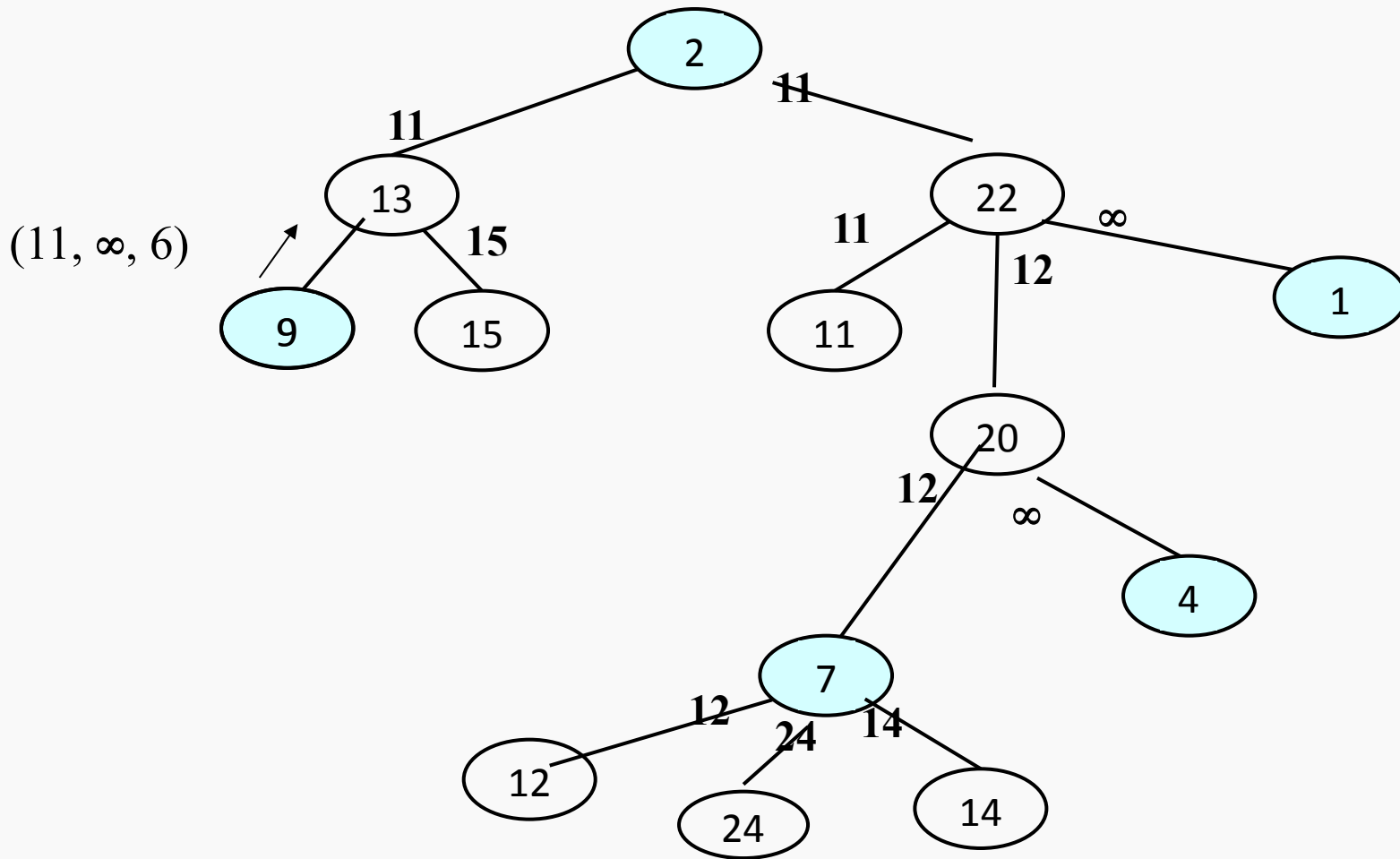


Notice the update









## Complexity: worst case

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