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ELG 5372 Error Control Coding

Lecture 20: Convolutional Codes: Equivalent Codes and Basic Encoders

Université d'Ottawa | University of Ottawa



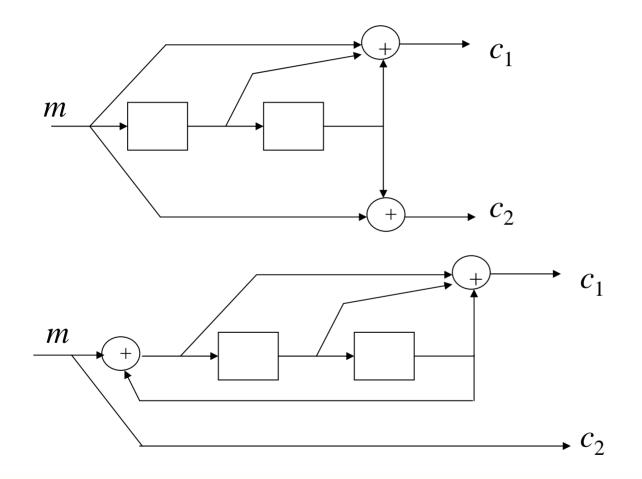
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Equivalent Codes

- Two convolutional codes are said to be equivalent if the set of sequences that they produce are identical.
- Consider the following two encoders:
 - $-G_a(D) = [1+D+D^2, 1+D^2]$
 - $G_b(D) = [1+D+D^2/(1+D^2), 1]$

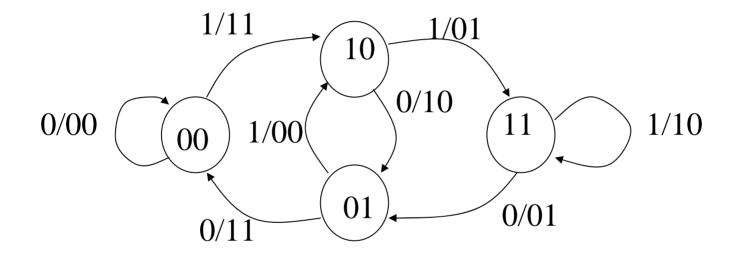


Encoders for $G_a(D)$ and $G_b(D)$



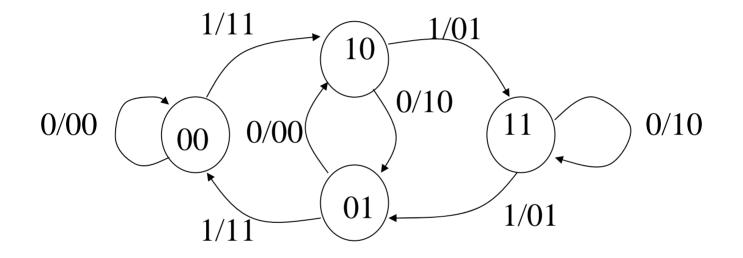


State Diagram for $G_a(D)$





State Diagram for $G_b(D)$





Comparison

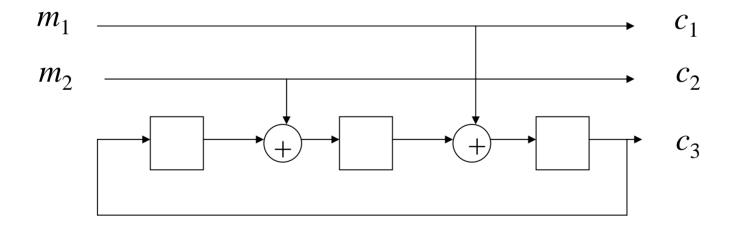
- When comparing the state diagram of $G_a(D)$ to that of $G_b(D)$, we see that some state changes are affected, but the same outputs occur.
- For encoder *a*, if **m**_{*a*} = 1000, output = 11,10, 11, 00
- For encoder *b*, if $\mathbf{m}_b = 1010$, output = 11, 10, 11, 00.
- This is because $G_b(D) = T(D)G_a(D)$, where T(D) is a $k \times k$ invertible matrix.
- Let $\mathbf{c}_a = \mathbf{m}_a G_a(D)$ and $\mathbf{c}_b = \mathbf{m}_b G_b(D) = \mathbf{m}_b T(D) G_a(D) = \mathbf{c}_a$ if $\mathbf{m}_b T(D) = \mathbf{m}_a$. If T(D) is invertible, then for every possible \mathbf{m}_a , there is a distinct \mathbf{m}_b such that $\mathbf{m}_a = \mathbf{m}_b T(D)$.
- In this example, $T(D) = 1/(1+D^2)$



Example 2

Consider the code

$$G_1(D) = \begin{bmatrix} 1 & 0 & D/(1+D^3) \\ 0 & 1 & D^2/(1+D^3) \end{bmatrix}$$

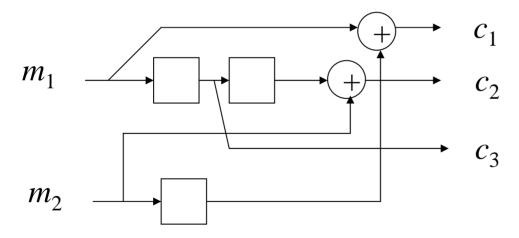




Example 2 cont'd

• Let $G_2(D)$ be given by:

$$G_2(D) = \begin{bmatrix} 1 & D^2 \\ D & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & D/(1+D^3) \\ 0 & 1 & D^2/(1+D^3) \end{bmatrix} = \begin{bmatrix} 1 & D^2 & D \\ D & 1 & 0 \end{bmatrix}$$



Both implementations use 3 storage devices and 2 adders.



Catastrophic Encoders

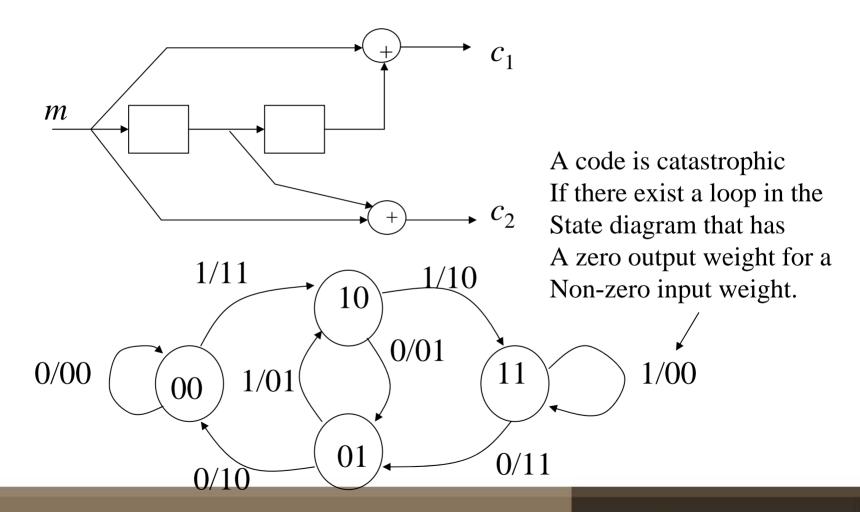
Consider the rate 1/2 encoder

 $G(D) = \begin{bmatrix} 1 + D^2 & 1 + D \end{bmatrix}$

Let m = 1111111..., $\mathbf{m}(D) = 1+D+D^2+D^3+...=1/(1+D)$ Then $\mathbf{c}(D) = [1+D, 1] = 1110000000...$ Suppose the first three bits are received in error $\mathbf{r}(D) = 0000000...$, this will be decoded as m' = 0000.... Therefore a finite number of channel errors cause an infinite number of decoded bit errors. This is called a catastrophic code.



Catastrophic Encoders cont'd

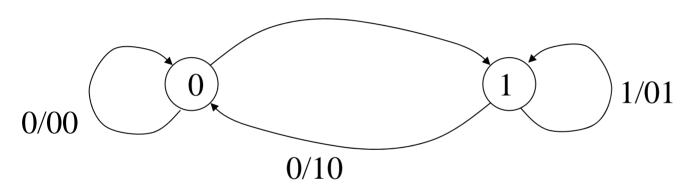




Catastrophic Codes cont'd

The code $G_2(D) = [1+D, 1]$ is equivalent

1/11



This code, which is less complex to implement, is not catastrophic. The output sequence 111000000... is produced by input 10000....



Catastrophic Codes cont'd

• The main conclusion is that catastrophic codes may have equivalent codes that are not catastrophic.



Right Inverse

- Let k<n. A right inverse of a k×n matrix G is a n×k matrix G⁻¹, such that GG⁻¹ = I_k.
- For $\mathbf{G} = [1+D^2, 1+D], \ \mathbf{G}^{-1} = [1/(D+D^2))^T (D+D^2)]^T$.



Polynomial Encoder

- A transfer function matrix with only polynomial entries is said to be a polynomial encoder
 - It uses FIR filters.
- If the transfer function has rational entries, it is a rational encoder
 - It uses IIR Filters.



Catastrophic Codes revisited

- Let G(D) be the transfer function matrix of a convolutional code.
- c(D) = m(D)G(D) and $c(D)G^{-1}(D) = m(D)$.
- If the code is catastrophic, there is a finite length c(D) that is produced by an infinite length m(D). This only occurs is G⁻¹(D) is rational.
- Therefore if **G**⁻¹(*D*) is a polynomial matrix, the code cannot be catastrophic.



Basic Encoders

- A transfer function matrix G(D) is basic if it is polynomial and it has a polynomial right inverse.
- It is shown on page 464 of the text that all rational encoders have a basic equivalent.

