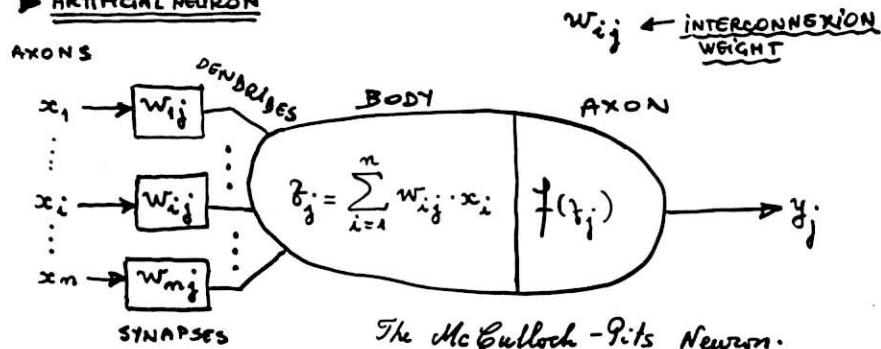


NEURAL NETWORKS PRIMER

► BIOLOGICAL NEURON : BODY, ONE AXON, MULTITUDE OF DENDRITES, MULTITUDE OF SYNAPSES (CONNECTING DENDRITES OF DIFFERENT NEURONS). THE STRENGTH OF A GIVEN SIGNAL IS DETERMINED BY THE EFFICIENCY OF THE SYNAPTIC TRANSMITS. A NEURON SENDS AN IMPULSE DOWN TO ITS AXON IF IT IS RECEIVING ENOUGH SIGNALS FROM OTHER NEURONS IN A WINDOW TIME INTERVAL CALLED THE PERIOD OF LATENT SUMMATION. THE INCOMING SIGNAL TO A DENDRITE MAY BE EITHER INHIBITORY OR EXCITATORY. A NEURON WILL FIRE AN IMPULSE DOWN ITS AXON, IF EXCITATION EXCEEDS ITS INHIBITION BY A CRITICAL AMOUNT CALLED THE THRESHOLD OF THE NEURON.

► ARTIFICIAL NEURON



DIFFERENT N.N. USE DIFFERENT $f(z_j)$ FUNCTIONS

PERCEPTRON = A MCC-P NEURON WITH A BINARY THRESHOLD:



- N.N. {
- WITH FIXED WEIGHTS : THE TASK TO BE ACCOMPLISHED MUST BE WELL DEFINED "A PRIORI". W_{ij} WILL BE EXPLICITLY DETERMINED FROM THE DESCRIPTION OF THE PROBLEM.
 - WITH ADAPTIVE WEIGHTS : LEARNING LAWS ARE USED TO ADJUST W_{ij}
 - SUPERVISED LEARNING N.N IS SUPPLIED WITH BOTH THE INPUT AND THE CORRECT OUTPUT VALUES
 - UNSUPERVISED LEARNING ONLY THE INPUT VALUES ARE PROVIDED.

■ NEURONAL DYNAMICAL SYSTEMS

NEURONAL ACTIVATIONS CHANGE WITH TIME. (DIFFERENTIAL EQUATIONS)
 $\dot{x}_i = g_i(x, y, \dots)$ { HOW THE ACTIVATION (MEMBRANE POTENTIALS) OF THE i TH NEURON IN FIELD F_i CHANGE AS A FUNCTION OF NETWORK PARAMETERS.

■ ADDITIVE NEURONAL DYNAMICS

? WHAT AFFECTS A NEURON {

- EXTERNAL INPUTS;
- OTHER NEURONS;
- NOTHING → ACTIVATION DECAY TO ITS RESTING VALUE:

$$\dot{x}_i = -x_i \Leftrightarrow x_i(t) = x_i(0) \cdot e^{-t}$$

► PASSIVE MEMBRANE DECAY :

PASSIVE DECAY RATE: $A_i > 0$

↳ IT VARIES INVERSELY WITH THE RESISTANCE R_i OF THE CELL MEMBRANE:

$$A_i = \frac{1}{R_i}$$

$$\dot{x}_i = -A_i \cdot x_i$$

$$x_i(t) = x_i(0) \cdot e^{-A_i t}$$

↳ INTERPRETING x_i AS A VOLTAGE →

A_i IS THE CONDUCTANCE OF THE CELL MEMBRANE MEASURING THE PERMEABILITY OF MEMBRANE, AXONAL, OR SYNAPTIC IONS.

► MEMBRANE TIME CONSTANTS

THE MEMBRANE TIME CONSTANT $C_i > 0$ SCALES THE TIME VARIABLE OF THE ACTIVATION DYNAMICAL SYST.

$$C_i \cdot \dot{x}_i = -A_i \cdot x_i$$

ACT AS THE MEMBRANE CAPACITANCE

$C_i \cdot \dot{x}_i = I_i$ THE MEMBRANE CURRENT

MEMBRANE RESTING POTENTIAL P_i ($>, =, < : 0$)

IS THE ACTIVATION VALUE TO WHICH THE MEMBRANE POTENTIAL EQUILIBRATES IN THE ABSENCE OF EXTERNAL OR NEURONAL INPUTS.

$$C_i \dot{x}_i = -A_i x_i + P_i \quad \left\{ P_i \text{ --- MEMBRANE RESTING CURRENT?} \right.$$

$$\underline{x_i(t) = x_i(0) e^{-(A_i/C_i)t} + \frac{P_i}{A_i} (1 - e^{-(A_i/C_i)t})}$$

P_i/A_i = STEADY STATE SOLUTION.

if $A_i = 1, P_i = \text{LARGE ENOUGH}$ ("SUPRATHRESHOLD") THE NEURON WILL SPONTANEOUSLY GENERATE SIGNALS OR PULSE TRAINS IN THE ABSENCE OF EXTERNAL OR NEURONAL STIMULI (AN OBSERVED BIOLOGICAL EFFECT)

if $A_i = 1, P_i = 0$, AND THE LOGISTIC SIGNAL FUNCTION $S_i(x_i) = (1 + e^{-kx})^{-1}$ THEN AT STEADY STATE $S_i = 1/2 \Rightarrow$ MAY CORRESPOND TO A MODERATELY BROAD PULSE TRAIN.

IN GENERAL A_i, C_i , AND P_i VARY SLOWLY WITH TIME, BUT SLOWLY ENOUGH TO BE CONSIDERED CONSTANT DURING A NEURONAL EPOCH OF EQUILIBRATION.

ADDITIVE EXTERNAL INPUT

$$\dot{x}_i = -x_i + \underline{I_i}$$

THIS DENOTES AN INPUT NOT A CURRENT

$$A_i = 1, C_i = 1, P_i = 0$$

$$x_i(t) = x_i(0) \cdot e^{-t} + I_i (1 - e^{-t}) \xrightarrow{t \rightarrow \infty} I_i$$

i.e.: THE MEMBRANE POTENTIAL ADAPTS ITS BEHAVIOR TO THE APPLIED EXTERNAL STIMULUS.

I_i CAN REPRESENT THE MAGNITUDE OF DIRECTLY EXPERIENCED SENSORY INFORMATION OR DIRECTLY APPLIED CONTROL INFORMATION

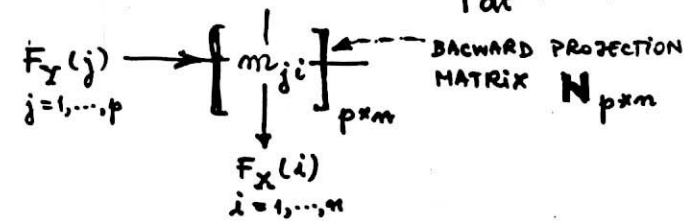
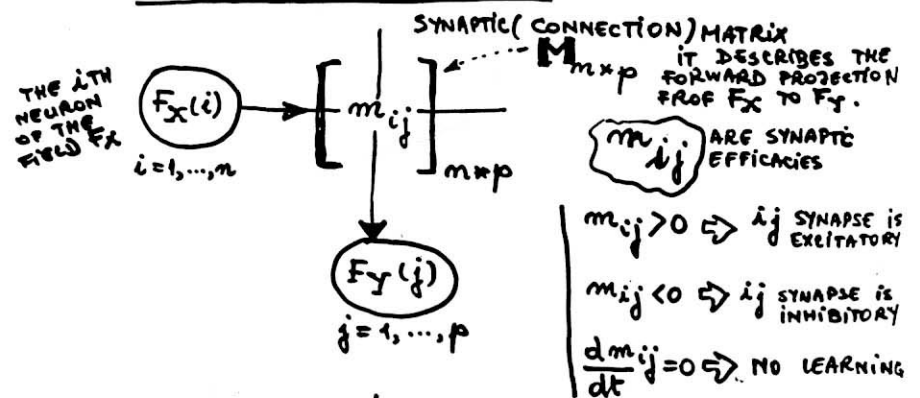
MATHEMATICALLY IS REQUIRED THAT I_i CHANGE SLOWLY ALLOWING TO BE ASSUMED CONSTANT.

NNP-03

ADDITIVE NEURONAL FEEDBACK

N.N. "COMPUTATION": ASYNCHRONOUS, NONLINEAR, MASSIVELY FEED BACK, FAST, AND CEASELESS.

SYNAPTIC CONNECTION MATRICES



N.N. SPECIFIED BY THE 4-TUPLE (F_x, F_y, M, N) .

[KOHONEN]: ONE-LAYER N.N. \rightarrow AUTOASSOCIATIVE;
TWO-LAYER N.N. \rightarrow HETEROASSOCIATIVE;

M AND N MATRICES DIFFER IN STRUCTURE (IN GENERAL)

\downarrow
FIXED POINT EQUILIBRIUM BEHAVIOR TENDS NOT TO OCCUR. THE EQUILIBRIUM BEHAVIOR IS OSCILLATORY OR APERIODIC.

NNP-04

▶ BIDIRECTIONAL AND UNIDIRECTIONAL CONNECTION TOPOLOGIES

- BIDIRECTIONAL NETWORKS = THE FORWARD AND BACKWARD SYNAPTIC PROJECTIONS, M AND N , HAVE THE SAME STRUCTURE; $M = N^T$, $N = M^T$.
- BIDIRECTIONAL ASSOCIATE MEMORY (BAM) = BIDIRECTIONAL NETWORK WITH AN OVERALL STABLE BEHAVIOR (DUE TO THE ACTIVATION DYNAMICS OF F_x AND F_y AND F_y)
- UNIDIRECTIONAL NETWORK = A NEURON FIELD SYNAPTICALLY INTRACONNECTS TO ITSELF, IT IS A BIDIRECTIONAL NETWORK WITH $F_x \equiv F_y$.

• IN "non-BAM" INTERPRETATION $m_{ij} = m_{ji}$ ON THE SAME AXON-SYNAPTIC FIBER
 IN "BAM" INTERPRETATION $m_{ij} = m_{ji}$ BUT M AND N REPRESENT DIFFERENT SYNAPTIC WEBS. (TWO-FIELD NETWORK)

• CONCATENATION OF F_x AND F_y , $F_z = [F_x | F_y]$.
 F_z INTERCONNECTS TO ITSELF BY THE MATRIX $B = \begin{pmatrix} 0 & M \\ N & 0 \end{pmatrix}$
 (I.E. HETEROASSOCIATION IS EXTENDED TO AUTOASSOCIATION.)
 IN THE "BAM" CASE: $B = B^T \Rightarrow$ "BAM" SYMMETRIZES AN ARBITRARY RECTANGULAR MATRIX M .

• M AND N INTERCONNECT F_x AND F_y } $C = \begin{pmatrix} P & M \\ N & Q \end{pmatrix}$ INTRA CONNECTS F_z .

IF P (OR Q) IS SYMMETRIC THEN THERE'S A LATERAL INHIBITION OR COMPETITIVE CONNECTION TOPOLOGY.
 THE STRENGTH OF THE INHIBITORY CONNECTIONS IS OFTEN DISTANCE DEPENDENT, TYPICALLY DECREASING WITH PHYSICAL DISTANCE.

■ ADDITIVE ACTIVATION MODELS

THE ADDITIVE ACTIVATION MODEL OF THE N.N. (F_x, F_y, M, N)

$$\begin{cases} \dot{x}_i = -A_i \cdot x_i + \sum_{j=1}^p S_j(y_j) \cdot m_{ji} + \dot{I}_i & | i=1, 2, \dots, n \\ \dot{y}_j = -A_j \cdot y_j + \sum_{i=1}^n S_i(x_i) \cdot m_{ij} + \dot{J}_j & | j=1, 2, \dots, p \end{cases}$$

THE ADDITIVE AUTOASSOCIATIVE ($F_x = F_y$) MODEL

$$\dot{x}_i = -A_i \cdot x_i + \sum_{j=1}^n S_j(x_j) \cdot m_{ji} + \dot{I}_i \quad | i=1, \dots, n$$

HOPFIELD CIRCUIT: ADDITIVE AUTOASSOCIATIVE MODEL, EACH NEURON HAVING A STRICTLY INCREASING BOUNDED SIGNAL FUNCTION ($S' > 0$), AND SYMMETRIC SYNAPTIC CONNECTION MATRIX ($M = M^T$).

↓
 GLOBALLY STABLE FEEDBACK N.N. (CONVERGE EXPONENTIALLY QUICKLY TO FIXED POINTS FOR ALL INPUTS.)

$$C_i \cdot \dot{x}_i = -\frac{x_i}{R_i} + \sum_{j=1}^n S_j(x_j) \cdot m_{ji} + \dot{I}_i \quad | i=1, \dots, n$$

■ ADDITIVE BIVALENT (BINARY) MODELS

NEURONS WITH THRESHOLD SIGNAL FUNCTIONS ("ON" - "OFF").

▶ BIVALENT ADDITIVE BAM

DISCRETE ADDITIVE "BAM" WITH THRESHOLD SIGNAL FUNCTIONS:

$$\begin{cases} x_i^{k+1} = \sum_{j=1}^p S_j(y_j^k) \cdot m_{ji} + \dot{I}_i & | i=1, \dots, n \\ y_j^{k+1} = \sum_{i=1}^n S_i(x_i^k) \cdot m_{ij} + \dot{J}_j & | j=1, \dots, p \end{cases}$$

("k" ARE DISCRETE TIME STEPS)

WITH THRESHOLD (BINARY) SIGNAL FUNCTIONS, $S_j(y_j^k)$ AND $S_i(x_i^k)$.

$$S_j(y_j^k) = \begin{cases} 1 & \text{if } y_j^k > V_j \\ S_j(y_j^{k-1}) & \text{if } y_j^k = V_j \\ 0 & \text{if } y_j^k < V_j \end{cases}$$

EXAMPLE

ANY REAL-VALUED MATRIX CAN BE USED TO ILLUSTRATE THE "BAM".

$$(y_1, y_2, y_3) = S(x_1, x_2, x_3, x_4) \cdot \begin{pmatrix} -3 & 0 & 2 \\ 1 & -2 & 0 \\ 0 & 3 & 2 \\ -2 & 1 & -1 \end{pmatrix}$$

$U_i = V_j = 0 \iff$ THE THRESHOLD VALUES FOR THE BINARY SIGNAL FUNCTION

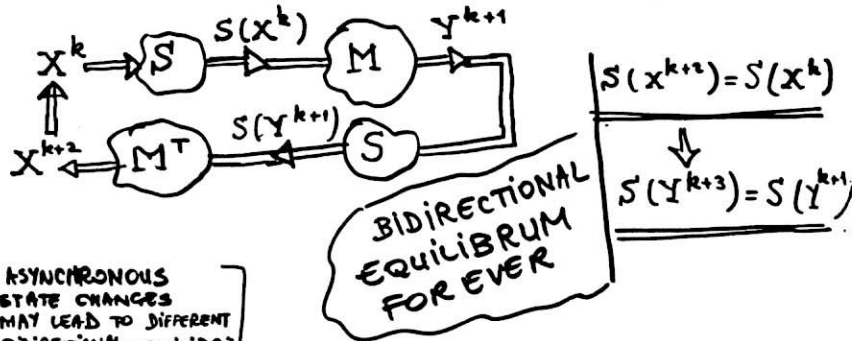
$$X^k = (x_1^k, x_2^k, x_3^k, x_4^k) = (5, -2, 3, 1) \Rightarrow S(X^k) = (1011)$$

$$Y^{k+1} = S(X^k) \cdot M = (1011) \cdot \begin{pmatrix} -3 & 0 & 2 \\ 1 & -2 & 0 \\ 0 & 3 & 2 \\ -2 & 1 & -1 \end{pmatrix} = (-5 \ 4 \ 3) \downarrow$$

$$S(Y^{k+1}) = (011)$$

$$X^{k+2} = S(Y^{k+1}) \cdot M^T = (011) \cdot \begin{pmatrix} -3 & 1 & 0 & -2 \\ 0 & -2 & 3 & 1 \\ 2 & 0 & 2 & -1 \end{pmatrix} = (2 \ -2 \ 5 \ 0) \downarrow$$

$$S(X^{k+2}) = (1011)$$



ASYNCHRONOUS STATE CHANGES MAY LEAD TO DIFFERENT BIDIRECTIONAL EQUILIBRIA

"NEARBY" INITIAL CONDITIONS TEND TO CONVERGE TOWARD THE SAME FIXED-POINT EQUILIBRIUM, THOUGH THE TENDENCY FALLS OFF WITH THE DISTANCE

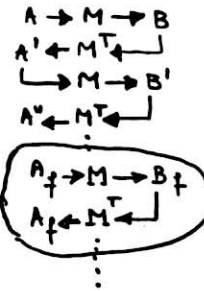
"CONTENT-ADDRESSABLE MEMORY" PROPERTY CHARACTERISTIC OF N.N.

ANN-07

BIDIRECTIONAL STABILITY

A "BAM" N.N. (F_X, F_Y, M) IS BIDIRECTIONALLY STABLE IF ALL INPUTS CONVERGE TO FIXED-POINT EQUILIBRIA

BIDIRECTIONAL STABILITY IS A DYNAMIC EQUILIBRIUM: I.E. THE SAME SIGNAL INFORMATION FLOWS BACK AND FORTH IN A BIDIRECTIONAL FIXED POINT.



THE BIDIRECTIONAL EQUILIBRIUM CAN BE VIEWED AS A RESONANT STATE.

WHEN BOTH THE CHANGING NEURONS (STM) AND THE CHANGING SYNAPSES (LTM) EQUILIBRATE, AN ADAPTIVE "BAM" FIXE POINT OCCUR. [GROSSBERG]: ADAPTIVE RESONANCE (JOINT EQUILIBRATION OF NEURONS AND SYNAPSES).

LYAPUNOV FUNCTIONS

ALLOW TO PROVE THE GLOBAL STABILITY OF A DYNAMICAL SYSTEM WITHOUT SOLVING THE DIFFERENTIAL EQ. OF THAT SYST.

A DYNAMICAL SYSTEM IS STABLE IF SOME LYAPUNOV FUNCTION "L" DECREASES ALONG TRAJECTORIES: $\dot{L} \leq 0$. A DYNAMICAL SYSTEM IS ASYMPTOTICALLY STABLE IF $\dot{L} < 0$. IN A STABLE EQUILIBRIUM THE TRAJECTORY MAY NEVER ARBITRARILY CLOSE TO THE EQUILIBRIUM POINT WITHOUT REACHING IT. IN AN ASYMPTOTICALLY STABLE SYST. THE STATE TRAJECTORY REACHES (IN GENERAL EXPONENTIALLY FAST) THE EQUILIBRIUM.

THE MONOTONICITY OF L PROVIDES A SUFFICIENT (NOT NECESSARY) CONDT. FOR STABILITY. \Rightarrow INABILITY TO PRODUCE L PROVES NOTHING.

FOR A SYMMETRIC MATRIX "A" AND A SQUARE MATRIX "B", THE QUADRATIC FORM OF LYAPUNOV FUNCTION: $L = XAX^T$ IS STRICTLY DECREASING FOR ANY LINEAR DYNAMICAL SYSTEM $\dot{X} = XB$ IF AND ONLY IF THE MATRIX $AB^T + BA$ IS NEGATIVE DEFINITE

INDEED
$$\dot{L} = \dot{X}AX^T + XA\dot{X}^T = XBAX^T + XAB^TX^T = X[BA + AB^T]X^T$$

ANN-08

EXAMPLE

A DYNAMICAL (PASSIVE DECAY) SYSTEM:

$$\dot{x}_i = -x_i$$

(HAVING THE SOLUTION $x_i(k) = x_i(0) \cdot e^{-k}$ WHICH $\rightarrow 0$)

$$L = \frac{1}{2} X I X^T = \frac{1}{2} \sum_{i=1}^m x_i^2$$

$X = (x_1, \dots, x_i, \dots, x_m)$
 $I = m\text{-BY-}m$ IDENTITY MATRIX

$$\dot{L} = \sum_{i=1}^m \frac{\partial L}{\partial x_i} \dot{x}_i = - \sum_{i=1}^m x_i^2 < 0$$

ALONG THE SYSTEM TRAJECTORIES
 I.E. THE SYSTEM IS ASYMPTOTICALLY
 STABLE AS LONG AS AT LEAST ONE
 STATE VARIABLE CHANGES ($\dot{x}_i \neq 0$)
 OR DIFFERS FROM ZERO ($x_i \neq 0$)

OR

$$\dot{L} = - \sum_{i=1}^m x_i^2$$

A DYNAMICAL SYSTEM IS ASYMPTOTICALLY STABLE IF AND ONLY IF
 ITS JACOBIAN MATRIX HAS EIGENVALUES WITH NEGATIVE REAL PARTS.

A LYAPUNOV FUNCTION OFTEN MEASURES THE ENERGY OF A NEURAL SYSTEM
 FOR N.N. PURPOSES A LYAPUNOV FUNCTION NEED ONLY DECREASE
 AND BE BOUNDED.

A BOUNDED DECREASING "L" MUST COME TO A STOP. THE
 STOPPING POINT CORRESPONDS TO AN EQUILIBRIUM POINT (POINT
 OF PROGRAMMABILITY).

"L" APPROACH REVEALS ONLY THE EXISTENCE OF STABLE POINTS,
 NOT THEIR NUMBER OR NATURE.

"BAM" CONNECTION MATRICES

BIPOLAR HEBBIAN (OUTER-PRODUCT) LEARNING - THE MOST POPULAR METHOD
 FOR CONSTRUCTING THE MATRIX "M" (SCULPTING THE SYSTEM ENERGY SURFACE)
 IN THE "BAM" (BIDIRECTIONAL ASSOCIATIVE MEMORIES).

(A_i, B_i) ^{1/0} ASSOCIATION OF BINARY VECTORS A_i (OF LENGTH m) AND
 B_i (OF LENGTH p).

(X_i, Y_i) ASSOCIATION OF BIPOLAR VECTORS X_i (OF LENGTH m) AND
 Y_i (OF LENGTH p).

$A_i = (X_i + 1)/2$; $X_i = 2 \cdot A_i - 1$; $[1 = (1, 1, \dots, 1)]$ m -BIT VECTOR

m - ASSOCIATIONS

THE BIPOLAR OUTER-PRODUCT: $M = \sum_{k=1}^m X_k^T Y_k$;
 m -BY- p CORRELATION MATRIX

THE BINARY OUTER-PRODUCT: $M = \sum_{k=1}^m A_k^T B_k$;
 m -BY- p CORRELATION MATRIX

THE BOOLEAN OUTER-PRODUCT: $M = \bigoplus_{k=1}^m A_k^T B_k$;

THE WEIGHTED OUTER-PRODUCT: $M = \sum_{k=1}^m w_k X_k^T Y_k$;
SCALED m -BY- p BIPOLAR CORRELATION MATRIX

w_k COEFFICIENTS CAN BE SELECTED TO PRODUCE
 A FADING-MEMORY EFFECT: E.G. TIME-ORDERING
 THE WEIGHTS: $w_1 < w_2 < \dots < w_m$ WHICH GIVES MORE
 WEIGHT TO MORE RECENT ASSOCIATIONS (WITH LARGER k);
 ANOTHER EXAMPLE IS EXPONENTIAL FADING $w_k = r^{m-k}$ ($0 < r < 1$)

AN APPROPRIATELY WEIGHTED FADING-MEMORY N.N. YIELDS
 A "MOVING WINDOW" NONLINEAR FILTER FOR AN ARBITRARY
 SEQUENCE OF ASSOCIATION TRAINING SAMPLES.

OPTIMAL LINEAR ASSOCIATIVE MEMORY (OLAM) MATRIX

(→ KOHONEN'S WORKS)

DATA-DEPENDENT
"BAM" CONNECTION MATRIX:

$$\hat{M} = X^* Y$$

X^* = PSEUDO-INVERSE OF X ;
- FOR A SCALAR x , $x^* = 1/x$
OR $x^* = 0$ IF $x = 0$;
- FOR A VECTOR x , $x^* = \frac{x^T}{x x^T}$
OR $x^* = 0$ IF $x = \underline{0}$;
- FOR A RECTANGULAR MATRIX X , $X^* = X^T (X X^T)^{-1}$
IF $(X X^T)^{-1}$ EXISTS

1) THE "OLAM" MATRIX \hat{M} MINIMIZES THE MEAN-SQUARE ERROR OF FORWARD RECALL IN ONE-SHOT, SYNCHRONOUS LINEAR NETWORK.

** IF THE SET OF VECTORS $\{X_1, \dots, X_m\}$ IS ORTHONORMAL ($X_i X_j^T = 1$ IF $i=j$; $= 0$ IF $i \neq j$) THEN THE "OLAM" MATRIX REDUCES TO THE LINEAR ASSOCIATIVE MEMORY (LAM):

$$M = X^T Y$$

THIS ASSUMPTION (OF LINEAR INDEPENDENCE) IS CRITICAL FOR THE "LAM" RECALL ACCURACY

AUTOASSOCIATIVE "OLAM" FILTERING

AUTOASSOCIATIVE "OLAM" ASSOCIATES m KNOWN SIGNAL VECTORS X_1, \dots, X_m TO THEMSELVES.

$$M = X^* X$$

M LINEARLY FILTERS INPUT MEASUREMENT x VECTOR TO THE OUTPUT VECTOR x' BY MATRIX MULTIPLICATION $x' M = x$

KOHONEN CALLS $i - X^* X$ THE NOVELTY DETECTOR ON R^n . IT WAS APPLIED TO IMAGE-SUBTRACTION PROBLEMS.

$X X^*$ AND $i - X^* X$ UNIQUELY DECOMPOSE EVERY R^n

VECTOR x INTO A SIGNAL VECTOR \hat{x} AND AN ORTHOGONAL NOVELTY VECTOR \tilde{x} .

$$x = x X X^* + x (i - X^* X) = \hat{x} + \tilde{x}$$

"BAM" CORRELATION ENCODING EXAMPLE

UNWEIGHTED ($w_1 = w_2 = 1$) BINARY ASSOCIATIONS:

$$A_1 = (101010), \quad B_1 = (1100)$$

$$A_2 = (111000), \quad B_2 = (1010)$$

CORRESPONDENT
BIPOLAR ASSOCIATIONS

$$X_1 = (1-1-1-1-1), \quad Y_1 = (1-1-1-1)$$

$$X_2 = (111-1-1-1), \quad Y_2 = (1-1-1-1)$$

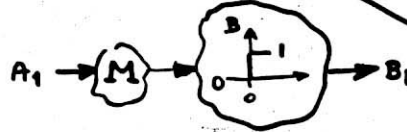
A_i AND X_i ARE CONSIDERED (FOR CONVENIENCE) ^{TO BE} SIGNAL FUNCTIONS.

THE "BAM" MEMORY MATRIX M IS CONSTRUCTED BY ADDING POINTWISE THE BIPOLAR CORRELATION MATRICES: $X_1^T Y_1$ AND $X_2^T Y_2$.

$$X_1^T Y_1 = (1-1-1-1-1)^T (1-1-1-1) = \begin{bmatrix} 1 & 1 & -1 & -1 \\ -1 & -1 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ -1 & -1 & 1 & 1 \\ 1 & 1 & -1 & -1 \end{bmatrix};$$

$$X_2^T Y_2 = (111-1-1-1)^T (1-1-1-1) = \begin{bmatrix} 1 & -1 & 1 & -1 \\ 1 & -1 & 1 & -1 \\ -1 & 1 & -1 & 1 \\ -1 & 1 & -1 & 1 \\ 1 & -1 & 1 & -1 \end{bmatrix}$$

$$M = X_1^T Y_1 + X_2^T Y_2 = \begin{bmatrix} 2 & 0 & 0 & -2 \\ 0 & -2 & 2 & 0 \\ 2 & 0 & 0 & -2 \\ -2 & 0 & 0 & 2 \\ 0 & 2 & -2 & 0 \\ -2 & 0 & 0 & 2 \end{bmatrix}$$



$$A_1 M = (101010) \cdot M = (4 \ 2 \ -2 \ -4) \xrightarrow{\text{THRESH}} B_1 = (1100);$$

$$B_1 M^T = (1100) \cdot M^T = (2 \ -2 \ 2 \ -2) \rightarrow A_1 = (101010)$$

THE LYAPUNOV "ENERGY" $L(A_1, B_1) = -A_1 M B_1^T = -(4 \ 2 \ -2 \ -4) (1100)^T = (-B_1 M^T A_1^T) = -6$, THE BACKWARD "L" ENERGY $= -6$

(A_1, B_1) IS A FIXED POINT OF THE "BAM" DYNAMICAL SYSTEM

SIMILARLY (A_2, B_2) IS A FIXED "BAM" POINT WITH

A "L" ENERGY OF -6 ; "BAM" HAS TWO FIXED EQUALLY DEEP ATTRACTORS.

FOR PATTERN RECOGNITION THE "WIDTH" OF AN ATTRACTOR BASIN IS MORE RELEVANT THAN ITS "DEPTH".

THE HAMMING DISTANCE OF TWO VECTORS $H(A_i, A_j)$ COUNTS THE SLOTS IN WHICH THE TWO BINARY VECTORS DIFFER.

a) $A = (011000) \rightarrow H(A, A_2) = 1, H(A, A_1) = 3;$
 $AM = (011000)M = (2-2 2-2) \rightarrow S(AM) = (1010) = B_2$
 THE "L" ENERGY: $-AMB_2^T = -4$ {i.e. THE "BAM" SYSTEM RECALLS THE RESONANT PAIR (A_2, B_2) .

b) $A = (000110) \rightarrow H(A, A_1) = 3, H(A, A_2) = 5;$
 $AM = (000110)M = (-2 2-2 0) \rightarrow S(AM) = (0101) = B_2^C$
 $H(A, A_2^C) = 1, H(A, A_1^C) = 3$
 $A_2^C M = (000111)M = (-4 2-2 4) \rightarrow S(A_2^C M) = (0101) = B_2^C$
 THE COMPLEMENT BIT VECTOR OF B_2 .

A IS "ROLLING" INTO THE UNINTENDED FIXED POINT SPURIOUS ATTRACTOR (A_2^C, B_2^C) WITH THE "L" ENERGY $-A_2^C M (B_2^C)^T = -6$

a) $X = (-111-1-1-1) \rightarrow H(X, X_1) = 3, H(X, X_2) = 1;$

$X M = (4-4 4-4) \xrightarrow{S(\dots)} (1-1-1-1) = Y_2;$
 i.e. THE 1-BIT NOISY INPUT $X = (-111-1-1-1)$ EVOKES THE FIXED POINT (X_2, Y_2) WITH "L" ENERGY $-X M Y_2^T = -(4-4 4-4) \cdot (1-1-1-1)^T = -16.$

b*) $X = (-1-1-1 11-1) \rightarrow$ CLOSEST TO X_2^C AS $H(X, X_2^C) = 1$ EVOKES THE SPURIOUS (COMPLEMENT) ATTRACTOR (X_2^C, Y_2^C) WITH INITIAL "L" ENERGY $-X M Y_2^C T = -16$ DECREASING AT THE NEXT ITERATION TO $-X_2^C M Y_2^C T = -24$

$X M = (-4 4 4 4) \xrightarrow{S(\dots)} (-11-11) = Y_2^C;$
 $Y_2^C M^T = (-4-4-4 4 4 4) \xrightarrow{S(\dots)} X_2^C;$

► MEMORY CAPACITY: DIMENSIONALITY LIMITS CAPACITY

e.g. AS MORE BINARY CORRELATION MATRICES $A_k^T B_k$ ARE BOOLEAN ADDED, THE RESULTING MATRIX ELEMENTS ARE MORE FREQUENTLY $m_{ij} = 1$ ($M = \sum_{k=1}^m A_k^T B_k$) \Rightarrow AFTER A POINT, ADDITIONAL ASSOCIATIONS (A_k, B_k) DO NOT SIGNIFICANTLY CHANGE THE CONNECTION MATRIX.

THE N.N. TENDS TO EXCEED THE MEMORY CAPACITY AS THE NUMBER m OF PATTERNS APPROACHES $\min(m, p)$ FOR "OLAM" (Optimal Linear Associat. Memory)

DIMENSIONALITY/CAPACITY ALWAYS HOLD BUT IN DIFFERENT WAYS

SUPERVISED N.N., ESPECIALLY FEEDFORWARD MULTILAYER NETWORKS TRAINED WITH AN ESTIMATED-GRADIENT-DESCENT ALGORITHM, CAN USUALLY ACCURATELY STORE MORE PATTERNS m THAN THE NUMBER n OF NETWORK NEURONS. THE PRICE IS ↑ THE NUMBER OF TRAINING ITERATIONS

CAPACITY IMPROVES WITH N.N. SIZE. NETWORK TEND TO LEARN MORE PATTERNS AS THE # OF NEURONS (i.e. SYNAPSES) ↑.

GROSSBERG'S SPARSE CODING THEOREM: FOR DETERMINISTIC ENCODING, PATTERN DIMENSIONALITY MUST EXCEED PATTERN NUMBER TO PREVENT LEARNING SOME PATTERNS AT THE EXPENSE OF FORGETTING OTHERS.

ON AVERAGE BIPOLAR $\{(-1, 1)$ INSTEAD OF $(0, 1)\}$ SIGNAL STATE VECTORS $S(\dots)$ PRODUCE MORE ACCURATE

RECALL THAN BINARY SIGNAL STATE VECTORS.

$X_1 M = (1-11-1-1-1) \cdot M = (8 4-4-8) \xrightarrow{S(\dots)} (11-1-1) = Y_1$
 $X_2 M = (111-1-1-1) \cdot M = (8-4 4-8) \xrightarrow{S(\dots)} (1-1 1-1) = Y_2$
 $Y_1 M = (11-1-1) \cdot M^T = (4-4 4-4 4-4) \xrightarrow{S(\dots)} (1-11-1-1) = X_1$
 $Y_2 M = (1-1 1-1) \cdot M^T = (4 4 4-4-4-4) \xrightarrow{S(\dots)} (111-1-1-1) = X_2$

$L(X_1, Y_1) = -X_1 M Y_1^T = -(8 4-4-8)(11-1-1)^T = -24$
 $\{ = -Y_1 M^T X_1^T = \dots$

(X_1, Y_1) AND (X_2, Y_2) ARE FIXED POINTS, WITH "L" ENERGY = -24, IN THE BIPOLAR PRODUCT SPACE $\{-1, 1\}^m \times \{-1, 1\}^p$ OF THE "BAM" DYNAMICAL SYSTEM. NNP 13

FOR BOOLEAN ENCODING OF BINARY ASSOCIATIONS WITH A BIVALENT ADDITIVE "BAM" THE MEMORY CAPACITY ↑ GREATLY WITH THE UPPER BOUND $\min(2^m, 2^p)$ (INSTEAD OF $\min(m, p)$) IF THE THRESHOLDS U_i, V_i ARE FORTUNOUSLY SELECTED.