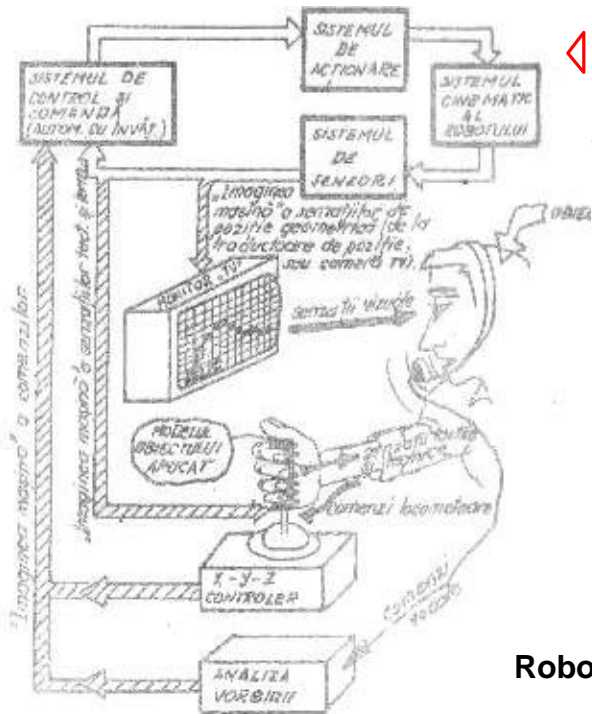


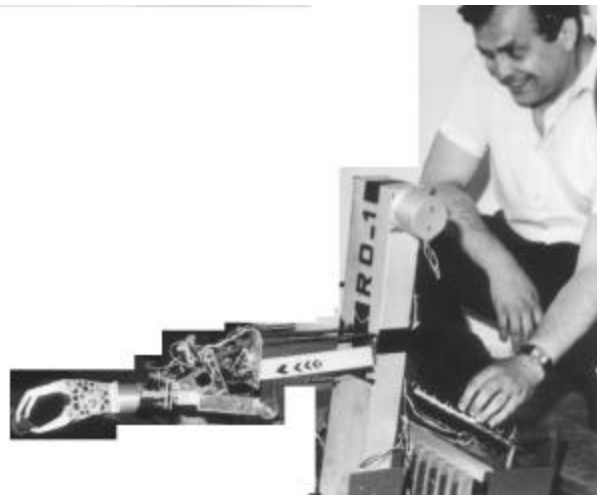
★ Haptic and Video Telerobotic Control

@ the Polytechnic Institute, Timisoara, Romania, early 80s

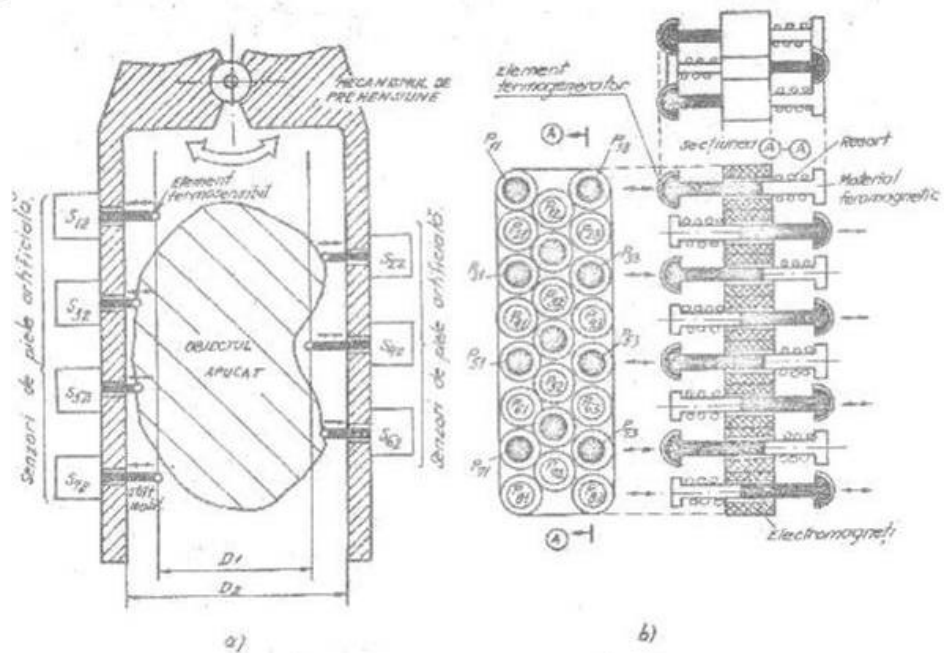
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◀ System architecture



Robot hand and tendon driven compliant wrist



(a) The robotic tactile sensor , and (b) the human tactile feedback