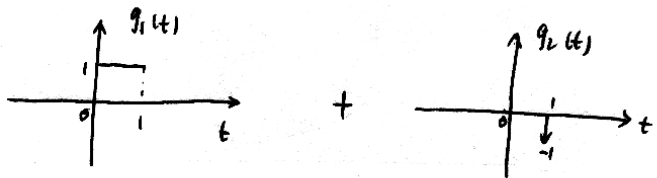


2002 Final

Question 1

$$g(t) = \frac{dx(t)}{dt} \Rightarrow$$



$$g(t) = g_1(t) + g_2(t)$$

$$G_1(j\omega) = \mathcal{F}[g_1(t)] = \frac{2 \sin \omega \cdot \frac{1}{2}}{\omega} e^{-j\omega \frac{1}{2}}$$

$$G_2(j\omega) = \mathcal{F}[g_2(t)] = e^{-j\omega}$$

$$G(j\omega) = G_1(j\omega) + G_2(j\omega) = \frac{2 \sin \omega \cdot \frac{1}{2}}{\omega} e^{-j\omega \frac{1}{2}} - e^{-j\omega}$$

$$X(j\omega) = \frac{G(j\omega)}{j\omega} + \pi G(0) \delta(\omega)$$

$$\text{and } G(0) = 0$$

$$\text{So } X(j\omega) = \frac{\frac{2 \sin \omega \cdot \frac{1}{2}}{\omega} e^{-j\omega \frac{1}{2}} - e^{-j\omega}}{j\omega}$$

$$= \frac{2 e^{-j\frac{\omega}{2}} \sin \frac{\omega}{2}}{j\omega^2} - \frac{e^{-j\omega}}{j\omega}$$

Question 2

(a) the impulse response of the system is

$$H(j\omega) = \frac{2}{(j\omega)^2 + 6j\omega + 8}$$

(b) the input $x(t) = e^{-2t} u(t)$

its Fourier transform is $X(j\omega) = \frac{1}{2+j\omega}$

so the output of this system is

$$Y(j\omega) = H(j\omega) X(j\omega)$$

$$= \frac{2}{(j\omega)^2 + 6j\omega + 8} \cdot \frac{1}{2+j\omega}$$

$$= \frac{2}{(2+j\omega)^2 (4+j\omega)}$$

$$= \frac{A_{11}}{2+j\omega} + \frac{A_{12}}{(2+j\omega)^2} + \frac{A_{13}}{4+j\omega}$$

Based on the techniques of partial-fraction expansion

we obtained $A_{11} = -\frac{1}{2}$, $A_{12} = 1$, $A_{13} = \frac{1}{2}$

$$Y(j\omega) = \frac{-\frac{1}{2}}{2+j\omega} + \frac{1}{(2+j\omega)^2} + \frac{\frac{1}{2}}{4+j\omega}$$

the output of the system can then be found by inverse transform

$$y(t) = \left(-\frac{1}{2} e^{-2t} + t e^{-2t} + \frac{1}{2} e^{-4t} \right) u(t)$$

Question 3

$$X(j\omega) = \frac{1}{1 - \frac{1}{2}e^{-j\omega}}$$

$$Y(j\omega) = \frac{1}{4} \cdot \frac{1}{1 - \frac{1}{2}e^{-j\omega}} + \frac{1}{1 - \frac{1}{4}e^{-j\omega}}$$

$$\begin{aligned} H(j\omega) &= \frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{\frac{1}{4} \cdot \frac{1}{1 - \frac{1}{2}e^{-j\omega}} + \frac{1}{1 - \frac{1}{4}e^{-j\omega}}}{\frac{1}{1 - \frac{1}{2}e^{-j\omega}}} \\ &= \frac{1}{4} + \frac{1 - \frac{1}{2}e^{-j\omega}}{1 - \frac{1}{4}e^{-j\omega}} = \frac{1}{4} + 1 - \frac{\frac{1}{4}e^{-j\omega}}{1 - \frac{1}{4}e^{-j\omega}} \\ &= \frac{5}{4} - \frac{1}{4} \cdot \frac{1}{1 - \frac{1}{4}e^{-j\omega}} \cdot e^{-j\omega} \end{aligned}$$

$$h(n) = \mathcal{F}^{-1}[H(j\omega)] = \frac{5}{4} \delta(n) - \frac{1}{4} \left(\frac{1}{4}\right)^{n-1} u(n-1)$$

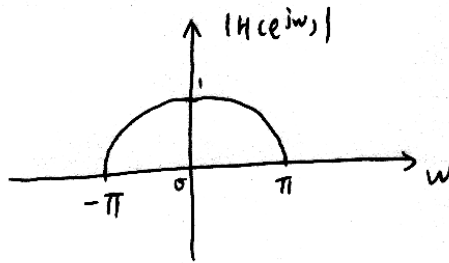
Question 4

(a) $H(e^{j\omega}) = \frac{1}{2} + \frac{1}{2}e^{-j\omega}$

$$h(n) = \frac{1}{2}\delta(n) + \frac{1}{2}\delta(n-1)$$

(b) $|H(e^{j\omega})| = \frac{1}{2} |1 + e^{-j\omega}| = \left|\cos\frac{\omega}{2}\right|$

(c)



(d) low-pass filter

Question 5

(a) the differential expression for this system is

$$RC \frac{dy(t)}{dt} + LC \frac{d^2y(t)}{dt^2} + y(t) = x(t)$$

$$(b) H(j\omega) = \frac{1}{LC(j\omega)^2 + RC(j\omega) + 1}$$

$$(c) L = 10 \times 10^{-3} \text{ H}$$

$$C = 100 \times 10^{-6} \text{ F}$$

$$R = 1 \Omega$$

$$H(j\omega) = \frac{\frac{1}{LC}}{(j\omega)^2 + \frac{R}{L}j\omega + \frac{1}{LC}} = \frac{\frac{1}{LC}}{(j\omega)^2 + 2\frac{1}{\sqrt{LC}} - \frac{\sqrt{LC} \cdot R}{2L}j\omega + \frac{1}{LC}}$$

$$\zeta = \frac{1}{2} \sqrt{\frac{R}{L}} = \frac{1}{2} \sqrt{\frac{100 \times 10^{-6}}{10 \times 10^{-3}}} < 1$$

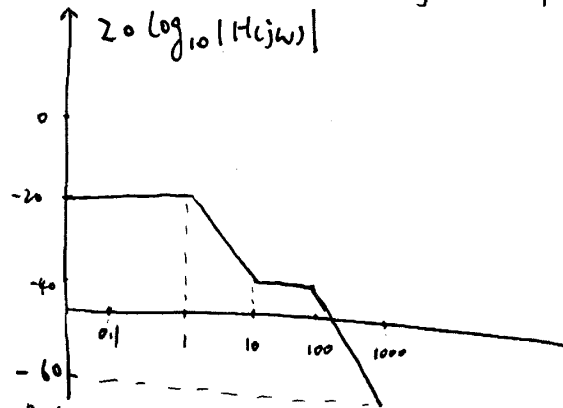
So the system is ~~over~~-damped
under

Question 6

$$H(j\omega) = \frac{10 + j\omega}{(1 + j\omega)(100 + j\omega)}$$

$$= \frac{1}{10} \cdot \frac{1}{1 + j\omega} \cdot \frac{1}{1 + \frac{j\omega}{100}} \cdot (1 + \frac{j\omega}{10})$$

The Bode plot for system magnitude function is below



The Bode plot for system phase function is below

Question 7

(a) $x(t) = 1 + \cos(100\pi t) + \cos(200\pi t)$

$$f_m = 100$$

So Nyquist rate $f_s = 2 f_m = 200$

(b) $y(t) = x^2(t) = (1 + \cos 100\pi t + \cos 200\pi t)^2$

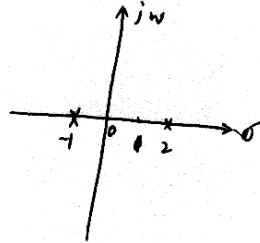
$$f_m = 200$$

So Nyquist rate $f_s = 2 f_m = 400$.

Question 8

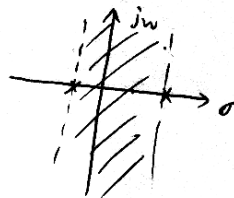
(a) $H(s) = \frac{1}{s^2 - s - 2}$

(b) $H(s) = \frac{1}{(s-2)(s+1)} \Rightarrow$



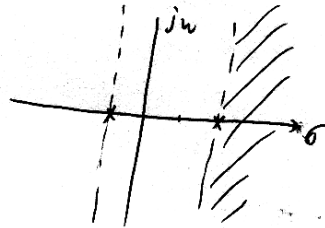
(c) $H(s) = \frac{A}{s-2} + \frac{B}{s+1} = \frac{\frac{1}{3}}{s-2} - \frac{\frac{1}{3}}{s+1}$

(i) The system is stable \rightarrow



$h(t) = -\frac{1}{3}e^{2t}u(-t) - \frac{1}{3}e^{-t}u(t)$

(ii) The system is causal \rightarrow



$h(t) = (\frac{1}{3}e^{2t} - \frac{1}{3}e^{-t})u(t)$

(iii) The system is neither stable nor causal

$h(t) = (-\frac{1}{3}e^{2t} + \frac{1}{3}e^{-t})u(-t)$

