2.19. (a) Consider the difference equation relating y[n] and w[n] for S_2 :

$$y[n] = \alpha y[n-1] + \beta w[n]$$

From this we may write

$$w[n] = \frac{1}{\beta}y[n] - \frac{\alpha}{\beta}y[n-1]$$

 and

$$w[n-1] = \frac{1}{\beta}y[n-1] - \frac{\alpha}{\beta}y[n-2]$$

Weighting the previous equation by 1/2 and subtracting from the one before, we obtain

$$w[n] - \frac{1}{2}w[n-1] = \frac{1}{\beta}y[n] - \frac{\alpha}{\beta}y[n-1] - \frac{1}{2\beta}y[n-1] + \frac{\alpha}{2\beta}y[n-2]$$

Substituting this in the difference equation relating w[n] and x[n] for S_1 ,

$$\frac{1}{\beta}y[n] - \frac{\alpha}{\beta}y[n-1] - \frac{1}{2\beta}y[n-1] + \frac{\alpha}{2\beta}y[n-2] = x[n]$$

That is,

$$y[n] = (\alpha + \frac{1}{2})y[n-1] - \frac{\alpha}{2}y[n-2] + \beta x[n]$$

Comparing with the given equation relating y[n] and x[n], we obtain

$$\alpha = \frac{1}{4}, \qquad \beta = 1$$

(b) The difference equations relating the input and output of the systems S_1 and S_2 are

$$w[n] = \frac{1}{2}w[n-1] + x[n]$$
 and $y[n] = \frac{1}{4}y[n-1] + w[n]$

From these, we can use the method specified in Example 2.15 to show that the impulse responses of S_1 and S_2 are

$$h_1[n] = \left(\frac{1}{2}\right)^n u[n]$$
$$h_2[n] = \left(\frac{1}{4}\right)^n u[n],$$

 and

respectively. The overall impulse response of the system made up of a cascade of
$$S_1$$
 and S_2 will be

$$h[n] = h_1[n] * h_2[n] = \sum_{k=-\infty}^{\infty} h_1[k]h_2[n-k]$$

= $\sum_{k=0}^{\infty} (\frac{1}{2})^k (\frac{1}{4})^{n-k} u[n-k]$
= $\sum_{k=0}^{n} (\frac{1}{2})^k (\frac{1}{4})^{n-k} = \sum_{k=0}^{n} (\frac{1}{2})^{2(n-k)}$
= $[2(\frac{1}{2})^n - (\frac{1}{4})^n]u[n]$

2.28

(b) Noncausal because $h[n] \neq 0$ for n < 0Stable because $\sum_{n=-2}^{\infty} (0.8)^n = \frac{125}{16} < \infty$

(e) Causal because h[n] = 0 for n < 0Unstable because the second term becomes infinite as $n \to \infty$

2.29

(d) Noncausal because $h(t) \neq 0$ for t < 0Stable because $\int_{-\infty}^{\infty} |h(t)| dt = \frac{e^{-2}}{2} < \infty$ (e) Causal because h(t) = 0 for t < 0Stable because $\int_{-\infty}^{\infty} |h(t)| dt = \frac{1}{3} < \infty$

(f) Causal since h(t)=0, for t<0

Stable since

$$\int_{-\infty}^{+\infty} \left| t e^{-t} u(t) \right| dt = \int_{0}^{+\infty} \left| t e^{-t} \right| dt = \left(-t e^{-t} - e^{-t} \right) \right|_{0}^{\infty} = 1 < \infty$$

2.31

Initial rest implies that
$$y[n] = 0$$
 for $n < -2$. Now
 $y[n] = x[n] + 2x[n-2] - 2y[n-1]$
so $y[-2] = 1$
 $y[-1] = 0$
 $y[0] = 5$
 $y[1] = -4$
 $y[2] = 16$
 $y[3] = -27$
 $y[4] = 58$
 $y[5] = -114$
 $y[n] = (-2)^{n-5} y[5] = -114(-2)^{n-5}$

2.32

(a) If
$$y_h[n] = A\left(\frac{1}{2}\right)^n$$
, then we need to verify $A\left(\frac{1}{2}\right)^n - \frac{1}{2}A\left(\frac{1}{2}\right)^{n-1} = 0$
Clearly this is true.

(b) We now require that for
$$n \ge 0$$

$$B\left(\frac{1}{3}\right)^n - \frac{1}{2}B\left(\frac{1}{3}\right)^{n-1} = \left(\frac{1}{3}\right)^n, \text{ so } B = -2$$

(c) From eq. (P2.32-1), we know that $y[0] = x[0] + \frac{1}{2}y[-1] = x[0] = 1$, Now we also have $y[0] = A + B \Rightarrow A = 1 - B = 3$