

## ELG3120A Midterm Solutions

## Question 1

$$(a) y(t) = (t+5)\cos\left(\frac{1}{x(t)}\right)$$

1.

Since the output depends on the present value of the input, the system is causal.

2.

$$t \rightarrow \infty$$

$$y(t) = (t+5)\cos\left(\frac{1}{x(t)}\right) \rightarrow \infty$$

Bounded input generate unbounded output, the system is not stable.

3.

The I/O equation of the system

$$y(t) = (t+5)\cos\left(\frac{1}{x(t)}\right) = \mathbf{t}\{x(t)\}$$

The response of this system to  $x(t-t_0)$  is

$$y(t, t_0) = (t+5)\cos\left(\frac{1}{x(t-t_0)}\right) \quad (1)$$

We delay the output by  $t_0$  time, we obtain

$$y(t-t_0) = (t-t_0+5)\cos\left(\frac{1}{x(t-t_0)}\right) \quad (2)$$

Since

$$y(t, t_0) \neq y(t-t_0)$$

The system is time variant.

4.

For two input sequences  $x_1(t)$  and  $x_2(t)$ , the corresponding outputs are

$$y_1(t) = (t+5)\cos\left(\frac{1}{x_1(t)}\right)$$

$$y_2(t) = (t+5)\cos\left(\frac{1}{x_2(t)}\right)$$

A linear combination of the two inputs sequences results in the output

$$y_3(t) = \mathbf{t}[ax_1(t) + bx_2(t)] = (t+5)\cos\left(\frac{1}{ax_1(t)}\right) + (t+5)\cos\left(\frac{1}{bx_2(t)}\right) \quad (3)$$

A linear combination of the output results in the output:

$$ay_1(t) + by_2(t) \neq (t+5)\cos\left(\frac{1}{ax_1(t)}\right) + (t+5)\cos\left(\frac{1}{bx_2(t)}\right) \quad (4)$$

Since the right sides of (3) and (4) are not identical, the system is not linear.

b)  $y[n] = \log(x[2n-4])$

1.

Since the output depends on the future values of the input when  $(n > 4)$ , the system is not causal.

2.

$$\begin{aligned} \text{when } |x[n]| \rightarrow 0 \\ |y[n]| = |\log(x[2n-4])| \rightarrow \infty \end{aligned}$$

Bounded input generates unbounded output, the system is not stable.

3.

$$y[n] = \log(x[2n-4]) = \mathbf{t}\{x[n]\}$$

If the input is delayed by  $n_0$  units in time and applied to the system, the output will be

$$y[n, n_0] = \log(x[2n - n_0 - 4]) \quad (5)$$

We delay  $y[n]$  by  $n_0$  units in time, we obtain

$$y[n - n_0] = \log(x[2(n - n_0) - 4]) \quad (6)$$

Since the right sides of (5) and (6) are identical,

$$y[n, n_0] \neq y[n - n_0]$$

The system is time variant.

4.

For two input sequences  $x_1[n]$  and  $x_2[n]$ , the corresponding outputs are

$$y_1[n] = \log(x_1[2n-4])$$

$$y_2[n] = \log(x_2[2n-4])$$

A linear combination of the two inputs sequences results in the output

$$y_3[n] = \mathbf{t}\{ax_1[n] + bx_2[n]\} = \log(ax_1[2n-4]) + \log(bx_2[2n-4]) \quad (7)$$

A linear combination of the outputs results in the output

$$ay_1[n] + by_2[n] = a\{\log(x_1[2n-4])\} + b\{\log(x_2[2n-4])\} \quad (8)$$

Since the right sides of (7) and (8) are not identical, the system is not linear.

## Question 2

(a) With  $\mathbf{d}(t)$  as input, we can get  $y(t)$  as  $h(t)$ .

$$y(t) = y_h(t) + y_p(t)$$

Because  $x(t) = \mathbf{d}(t)$

$$\Rightarrow y_p(t) = 0$$

$$y_h(t) = Ae^{st}$$

$$4Ase^{st} - 2Ae^{st} = 0$$

$$s = 1/2$$

Then,

$$4 \frac{dh(t)}{dt} - 2h(t) = \mathbf{d}(t)$$

$$4 \int_{0^-}^{0^+} \frac{dh(t)}{dt} dt - \int_{0^-}^{0^+} 2h(t) dt = \int_{0^-}^{0^+} \mathbf{d}(t) dt$$

$$\because \int_{0^-}^{0^+} 2h(t) dt = 0$$

$$\therefore 4[h(t)]_{0^-}^{0^+} = 1$$

$$\therefore 4[h(0^+) - h(0^-)] = 1$$

$$\because h(0^-) = 0$$

$$\therefore 4h(0^+) = 1$$

$$4Ae^{\frac{1}{2} \cdot 0} = 1$$

$$\therefore A = \frac{1}{4}$$

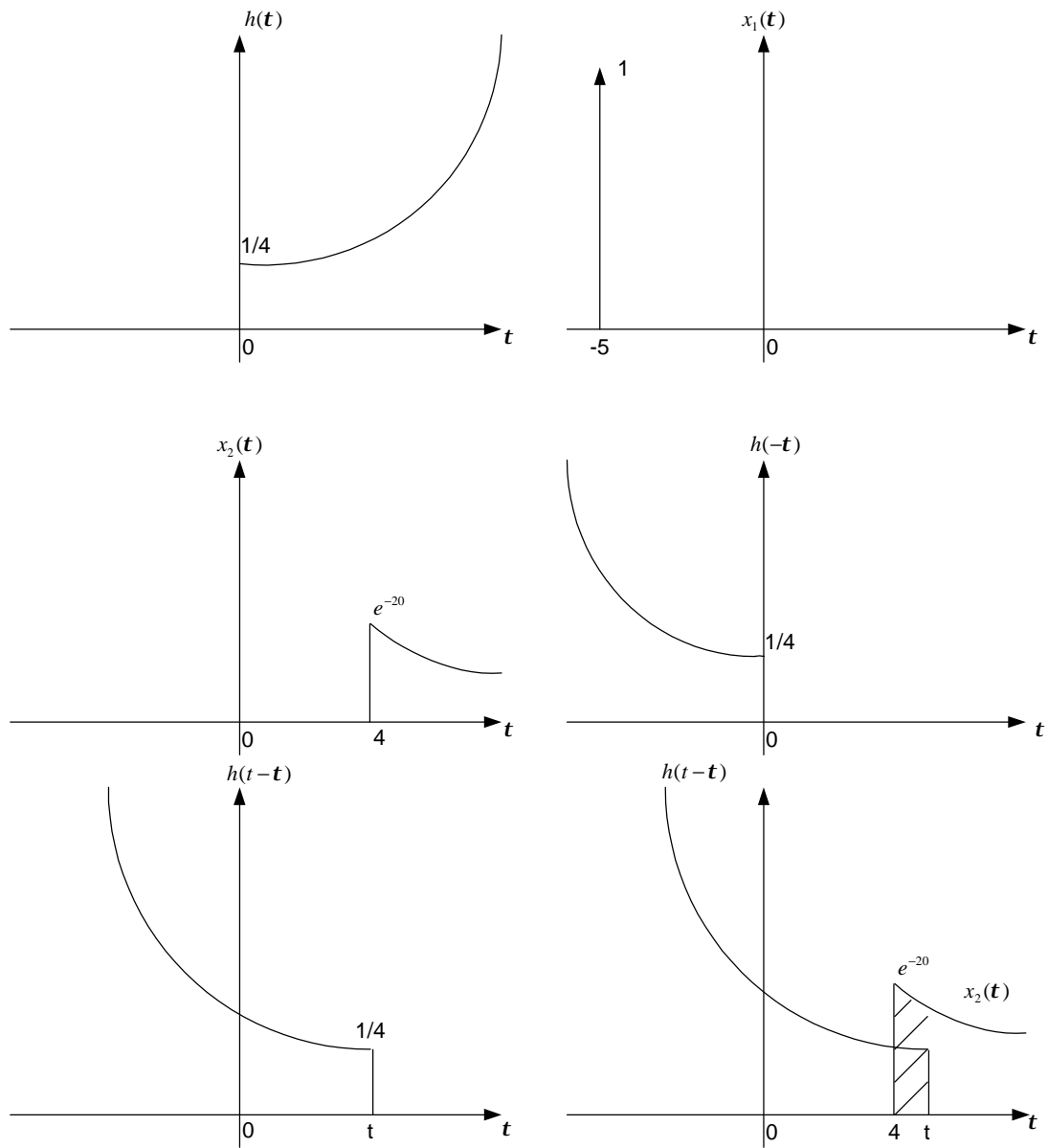
$$\therefore y(t) = h(t) = \frac{1}{4} e^{\frac{1}{2}t} u(t)$$

(b) For  $y(t) = h(t) = \frac{1}{4} e^{\frac{1}{2}t} u(t)$

$$\int_{-\infty}^{\infty} h(t) dt = \int_{-\infty}^{\infty} \frac{1}{4} e^{\frac{1}{2}t} u(t) dt \rightarrow \infty$$

So, the system is not stable.

(c)



Because this is a LTI system, we can have

$$y(t) = x_1(t) * h(t) + x_2(t) * h(t)$$

Where

$$x_1(t) = \mathbf{d}(t+5)$$

$$x_2(t) = e^{-5t}u(t-4)$$

Thus,  $y_1(t) = \mathbf{d}(t+5) * h(t) = \frac{1}{4} e^{\frac{1}{2}(t+5)} u(t+5)$

for..... $t < 4, y_2(t) = 0$

for..... $t \geq 4, y_2(t) = \frac{1}{4} \int_4^t e^{-5t} e^{\frac{1}{2}(t-t)} dt = -\frac{1}{22} (e^{-5} - e^{-22}) u(t-4)$

$y(t) = y_1(t) + y_2(t) = \frac{1}{4} e^{\frac{1}{2}(t+5)} u(t+5) - \frac{1}{22} (e^{-5} - e^{-22}) u(t-4)$

### Question 3

(a)

$$N = 6$$

$$a_k = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk(\frac{2p}{N})n} = \frac{1}{6} \sum_{n=0}^5 x[n] e^{-jk(\frac{2p}{6})n}$$

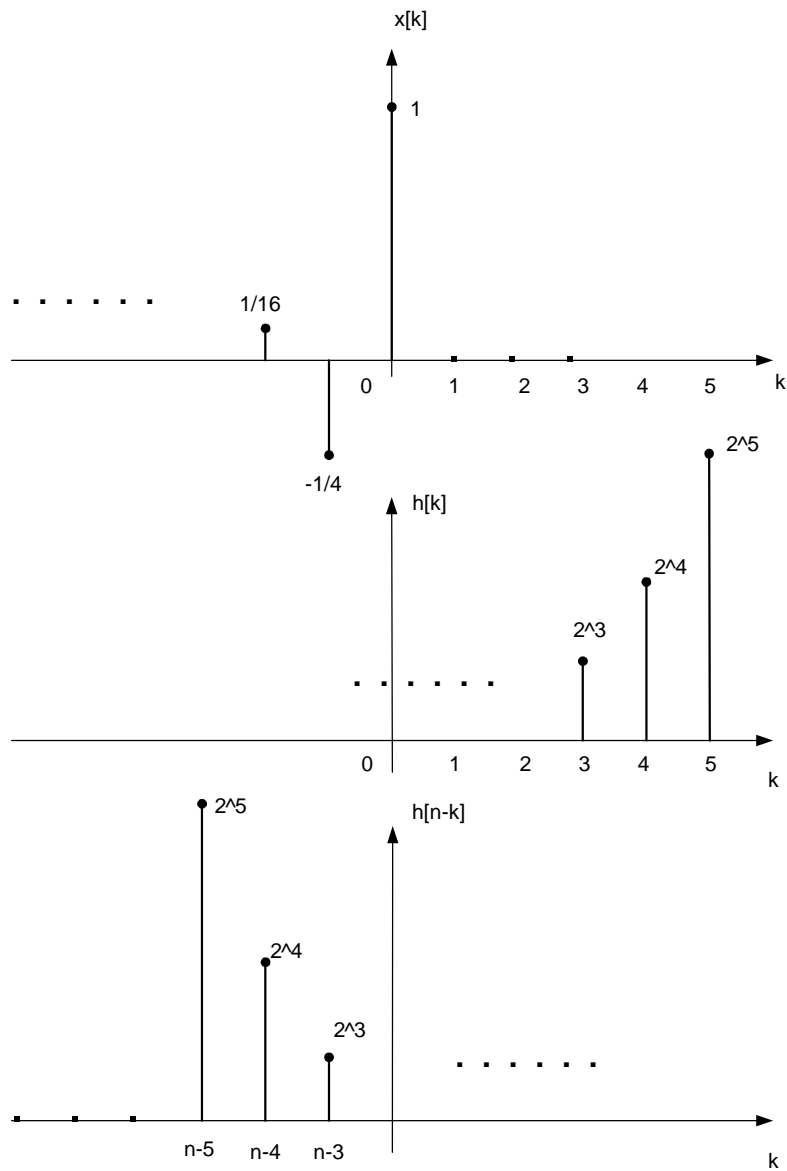
$$a_k = \frac{1}{6} (0 + 3e^{-jk(\frac{2p}{6})1} + 0 + 0 + 1e^{-jk(\frac{2p}{6})4} + 0) = \frac{1}{2} e^{-jk\frac{p}{3}} + \frac{1}{6} e^{-jk\frac{4p}{3}}$$

(b)

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} \text{ where } \dots \omega_0 = \frac{2p}{T} = p$$

$$\text{So } x(t) = 10 + 2je^{j3pt} - 2je^{-j3pt} + 5e^{j5pt} + 5e^{-j5pt} = 10 - 4\sin 3pt + 10\cos 5pt$$

Question 4



for...  $n > 5$

$$y[n] = 0$$

For...  $n \leq 5$

$$y[n] = \sum_{k=n-5}^0 x[k]h[n-k] = \sum_{k=n-5}^0 (-4)^k 2^{n-k} = 2^n \sum_{k=n-5}^0 \left(\frac{-4}{2}\right)^k = 2^n \frac{(-2)^{n-5} - (-2)^{0+1}}{1 - (-2)} = \frac{2^{n+1} - 2(-4)^{n-3}}{3}$$