

**Université d'Ottawa  
Faculté de Génie,  
École d'Ingénierie et des  
Technologies de l'Information**



**University of Ottawa  
Faculty of Engineering,  
School of Information  
Technology and Engineering**

**ELG 3120**

**Signal and System Analysis**

**Midterm**

**Saturday, 22 October 2005**

**13:00 - 14:30**

**Professor: Jianping Yao**

- **No calculators**
- **No textbook and notes (close-book exam)**
- **Initial on the top of each page.**

**Last name:** \_\_\_\_\_

**First name:** \_\_\_\_\_

**Student number:** \_\_\_\_\_

Summations :

$$\sum_{k=0}^{\infty} a^k = \frac{1}{1-a} \quad |a| < 1$$

$$\sum_{k=n_1}^{\infty} a^k = \frac{a^{n_1}}{1-a} \quad |a| < 1$$

$$\sum_{k=0}^{n_1} a^k = \frac{1-a^{n_1+1}}{1-a} \quad a \neq 1$$

$$\sum_{k=n_1}^{n_2} a^k = \frac{a^{n_1} - a^{n_2+1}}{1-a} \quad a \neq 1$$

Other:

$$\int x e^{ax} dx = \frac{e^{ax}}{a^2} (ax - 1)$$

Convolutions :

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau$$

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n - k]$$

Continuous-time Fourier Series:

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$$

$$a_k = \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt$$

$$a_0 = \frac{1}{T} \int_T x(t) dt \quad \omega_0 = \frac{2\pi}{T}$$

$$x(t) = a_0 + 2 \sum_{k=1}^{\infty} A_k \cos(k\omega_0 t + \theta_k),$$

$$a_k = A_k e^{j\theta_k} \quad k \geq 1$$

Discrete-time Fourier Series:

$$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk\left(\frac{2\pi}{N}\right)n}$$

$$a_k = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk\left(\frac{2\pi}{N}\right)n}$$

**TABLE 3.1** PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES

Property	Section	Periodic Signal	Fourier Series Coefficients
		$\left. \begin{array}{l} x(t) \\ y(t) \end{array} \right\} \begin{array}{l} \text{Periodic with period } T \text{ and} \\ \text{fundamental frequency } \omega_0 = 2\pi/T \end{array}$	$\begin{array}{l} a_k \\ b_k \end{array}$
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Linearity	3.5.1	$Ax(t) + By(t)$	$Aa_k + Bb_k$
Time Shifting	3.5.2	$x(t - t_0)$	$a_k e^{-jk\omega_0 t_0} = a_k e^{-jk(2\pi/T)t_0}$
Frequency Shifting		$e^{jM\omega_0 t} = e^{jM(2\pi/T)t} x(t)$	$a_{k-M}$
Conjugation	3.5.6	$x^*(t)$	$a_{-k}^*$
Time Reversal	3.5.3	$x(-t)$	$a_{-k}$
Time Scaling	3.5.4	$x(\alpha t), \alpha > 0$ (periodic with period $T/\alpha$ )	$a_k$
Periodic Convolution		$\int_T x(\tau)y(t - \tau)d\tau$	$Ta_k b_k$
Multiplication	3.5.5	$x(t)y(t)$	$\sum_{l=-\infty}^{+\infty} a_l b_{k-l}$
Differentiation		$\frac{dx(t)}{dt}$	$jk\omega_0 a_k = jk \frac{2\pi}{T} a_k$
Integration		$\int_{-\infty}^t x(\tau) d\tau$ (finite valued and periodic only if $a_0 = 0$ )	$\left(\frac{1}{jk\omega_0}\right)a_k = \left(\frac{1}{jk(2\pi/T)}\right)a_k$
Conjugate Symmetry for Real Signals	3.5.6	$x(t)$ real	$\begin{cases} a_k = a_{-k}^* \\ \Re\{a_k\} = \Re\{a_{-k}\} \\ \Im\{a_k\} = -\Im\{a_{-k}\} \\  a_k  =  a_{-k}  \\ \angle a_k = -\angle a_{-k} \end{cases}$
Real and Even Signals	3.5.6	$x(t)$ real and even	$a_k$ real and even
Real and Odd Signals	3.5.6	$x(t)$ real and odd	$a_k$ purely imaginary and odd
Even-Odd Decomposition of Real Signals		$\begin{cases} x_e(t) = \mathcal{E}\{x(t)\} & [x(t) \text{ real}] \\ x_o(t) = \mathcal{O}\{x(t)\} & [x(t) \text{ real}] \end{cases}$	$\begin{array}{l} \Re\{a_k\} \\ j\Im\{a_k\} \end{array}$
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Parseval's Relation for Periodic Signals			
$\frac{1}{T} \int_T  x(t) ^2 dt = \sum_{k=-\infty}^{+\infty}  a_k ^2$			

**Question 1:****/20**

(a) A continuous-time system is defined by the input-output relationship

$$y(t) = \cos(\omega t)x(t)$$

State and justify whether the system is (i) linear or non-linear; (ii) time-invariant or time-variant; (iii) memoryless or with memory; (iv) causal or non-causal; (v) stable or unstable; (vi) invertible or non-invertible.

(b) A discrete-time system is defined by the input-output relationship

$$y[n] = u(x[n]) - u(x[n] - 1)$$

Where  $u(\cdot)$  is the unit-step function. State and justify whether the system is (i) linear or non-linear; (ii) time-invariant or time-variant; (iii) memoryless or with memory; (iv) causal or non-causal; (v) stable or unstable; (vi) invertible or non-invertible.

**Question 2:****/20**

Let  $x[n] = \sin\left(\frac{2\pi n}{4}\right)u[n]$ .

(a) Carefully sketch the following signals for  $-10 \leq n \leq 10$ :

(i)  $x[n]$

(ii)  $x[-n + 3]$

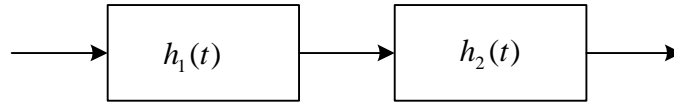
(iii)  $\text{Ev}\{x[n]\}$

(iv)  $\text{Od}\{x[n]\}$

(b) For each of the signals in (i)-(iv), state if it is periodic or non-periodic. If it is periodic, give the fundamental period.

**Question 3:****/20**

Find the overall impulse response of two LTI systems connected in cascade. The impulse responses of the two subsystems are  $h_1(t) = e^{-3t}u(t) + \delta(t-2)$  and  $h_2(t) = u(t-3) - u(t-5)$ .

**Solution:**

$$h(t) = h_1(t) * h_2(t)$$

**Question 4:****/20**

Consider a causal LTI system whose input  $x[n]$  and output  $y[n]$  are related by the difference equation  $y[n] - \frac{1}{3}y[n-1] = x[n]$

- (1) Find the impulse response of the system.
- (2) Determine  $y[n]$  using convolution if  $x[n] = u[n] - u[n-8]$ .

**Question 5:****/20**

(1) Calculate the Fourier series coefficients of the following continuous-time signal:

$$x(t) = \begin{cases} 1 & 0 \leq t \leq 1 \\ -1 & 1 \leq t \leq 2 \end{cases} \text{ with a fundamental period of 2.}$$



(2) A discrete-time periodic signal  $x[n]$  is real valued and has a fundamental period  $N = 5$ . The nonzero Fourier series coefficients for  $x[n]$  are

$a_0 = 2$ ,  $a_2 = a_{-2}^* = 2e^{j\pi/6}$ ,  $a_4 = a_{-4}^* = e^{j\frac{\pi}{3}}$ , express  $x[n]$  in the form of

$$x[n] = A_0 + \sum_{k=1}^{\infty} A_k \sin(\omega_k n + \phi_k)$$