

# Université d'Ottawa - University of Ottawa

Faculté de génie École d'ingénierie et de technologie de l'information Faculty of Engineering School of Information Technology and Engineering

#### ELG 3120

## Signal and System Analysis

Final Exam – Fall 2004

Tuesday 21 December 2004 9:30 - 12:30

#### ART 026 (ELG3120A), ART 257 (ELG3120B)

Prof. Jianping Yao

	Q1	
Time allowed: 3 Hours	Q2	
No calculators are permitted Close-book exam	Q3	
	Q4	
Family Name:	Q5	
Given name:	Q6	
Student number:	Total	

### **Question 1 Continuous Fourier Transform**

(A) (5 points) Consider that signal  $x_0(t) = \begin{cases} e^{-t}, & 0 \le t \le 1\\ 0, & elsewhere \end{cases}$ 

- (a) determine its Fourier transform.
- (b) using Fourier Transform properties, find the Fourier transform of the function  $x_1(t)$  shown in Figure 1.

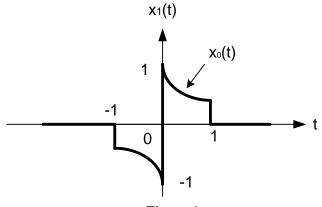


Figure 1

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(B) (5 points) A causal and stable LTI system S has the frequency response

$$H(j\omega) = \frac{j\omega + 2}{(j\omega)^2 + 4j\omega + 3}$$

- (a) Determine the impulse response h(t) of the system.
- (b) If an input signal  $x(t) = te^{-2t}u(t)$  is applied to the input of the system, find the output signal y(t).

### **Question 2: Discrete-time Fourier Transform**

Consider a discrete-time system with unit impulse response  $h[n] = \left(\frac{1}{2}\right)^n u[n] + \frac{1}{2}\left(\frac{1}{4}\right)^n u[n]$ 

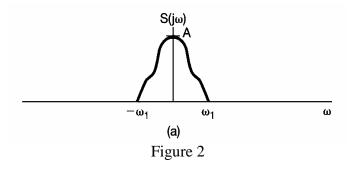
- (a) Find its Fourier transform
- (b) Determine a linear constant-coefficient difference equation relating the input and output of the system.

#### **Question 3: Modulation and demodulation**

Let s(t) be a signal whose spectrum  $S(j\omega)$  is depicted in the Figure 2 below. Also consider the signal  $p(t) = \cos \omega_0 t$ ,

(a) Find and plot the spectrum of r(t) = s(t)p(t) (that is,  $R(j\omega)$ ).

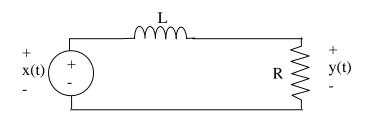
(b) The signal r(t) = s(t)p(t) is a modulated signal generated at a transmitter. To recover the original signal s(t) at a receiver, a demodulation operation is required. Part of the demodulation operation is to do the multiplication of the two signals of r(t) and p(t) where  $p(t) = \cos \omega_0 t$  is generated by a local oscillator. Find and plot the spectrum of g(t) = p(t)r(t).



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## Question 4 First- and second-order systems

A) (6 points) The following circuit with L = 1 mH et R = 1 k $\Omega$ 



Find:

- A.1) The Frequency response  $H(j\omega)$  and the time constant  $\tau$
- A.2) The impulse response h(t)
- A.3) The unit-step response s(t)
- A.4) The Bode plot (amplitude et phase)

B) (3 points) A system is characterized by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 3.5 \frac{dy(t)}{dt} + 1.5 y(t) = 10x(t)$$

Determine if the system is over-damped or under-damped? (note:  $\sqrt{2} \approx 1.4$ ,  $\sqrt{3} \approx 1.7$ )

C) (5 points) A first-order discrete-time system:

$$y[n] - ay[n-1] = x[n]$$

To be a stable system, it is required that |a| < 1.

C.1) Determine for which value of *a*, the system is a low-pass filter and for which value of *a* the system is a high-pass filter? To verify, evaluate the gain  $|H(e^{j\omega})|$  of the filter at  $\omega = 0$  and at  $\omega = \pi$  for a = 0.9 and a = -0.9.

C.2) For a = 0.9 and for a = -0.9, find the impulse response h[n]. For which values of a, the impulse response has an alternation versus n? For which values of a, the impulse response does not have an alternation versus n?

Initials \_\_\_\_\_

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### **Question 5 Sampling**

A) (5 points) A signal x(t) is multiplied by a impulse train p(t) of period T:

$$x_p(t) = x(t) \cdot p(t)$$
$$p(t) = \sum_{n = -\infty}^{\infty} \delta(t - nT)$$

A.1) Prove that the Fourier transform of p(t) is  $P(j\omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\omega - k\omega_s) \ (\omega_s = \frac{2\pi}{T})$ 

A.2) With 
$$P(j\omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\omega - k\omega_s)$$
, prove that  $X_p(j\omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X(j(\omega - k\omega_s))$ 

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Initials _____
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B) (2 points) A complex signal x(t) with a Fourier transform of  $X(j\omega)$  is zero everywhere except for the interval  $-5 < \omega < 2$ . Using  $X_p(j\omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X(j(\omega - k\omega_s))$ , determine the minimum sampling frequency  $\omega_s$  to ensure a reconstruction of the original signal x(t) without losing information.

#### **Question 6 Laplace Transform**

The Laplace transform of an LTI system is shown below

$$H(s) = \frac{1}{(s+3)(s+1)(s-2)}$$

a) Find the 4 possible ROCs (regions of convergence) of the system.

b) Find the ROC that corresponds to a causal system.

c) For the ROC of b) (causal system), find the impulse response h(t) of the system and prove that the system is causal.

d) Find the ROC that corresponds to stable system.

e) For the ROC de d) (stable system), Find the impulse response h(t) of the system.

f) Determine if H(s) can have a system that is both causal and stable? Explain why if your answer is yes, give the corresponding ROC.

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